



## RACE STUDIO CONFIGURATION USER MANUAL



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## Chapter 1 – Race Studio 2 software

**Race Studio 2** is the application properly designed and developed by AIM to configure its loggers and analyze their data using a PC. It is made up of two software: Race studio Configuration and Race Studio Analysis.

**This user manual refers to the Race Studio Configuration (from 2.30.05) only.**

**Race Studio 2** developed following the evolution of AIM loggers and ever improving its potentialities. Thanks to the configuration, the user can better customize its logger to take the most out of it.

With **Race Studio 2** it is possible to integrate in a flexible and dynamic system all the external expansion modules and the innovative devices that AIM Research and Development Dept. creates as well as all the custom sensors that any user can connect to his logger.

Configuring a logger with **Race Studio 2** means adapting it to one's needs, taking the most out of it.

### 1.1 – Compatibility between Race Studio 2 and operative systems

**Race Studio 2** has been developed to guarantee the maximum working reliability and its correct working has been tested with the following operative systems: Microsoft Windows XP Microsoft Windows Vista and Microsoft Widows 7.

All operative systems (Linux, Unix, Macintosh®) not indicated in this tutorial are to be considered not supported by this application.

For any problem it is suggested to check [www.aimshop.com](http://www.aimshop.com) website to verify if any recent news has been issued and, if not, to contact the technical support that can be found in home page at [www.aimshop.com](http://www.aimshop.com).

## Chapter 2 – Installing Race Studio 2 and the USB Driver

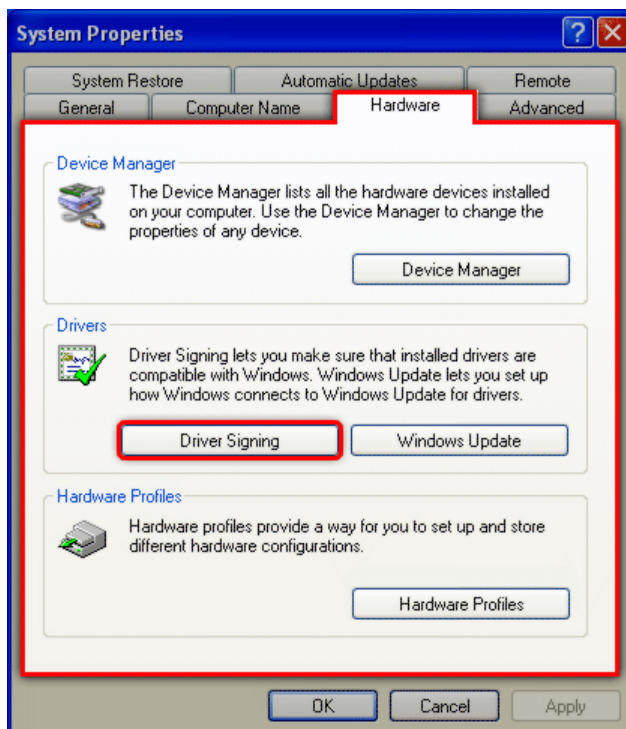
To configure most of AIM loggers it is necessary to install **Race Studio 2** and the AIM USB driver.

### 2.1 – Preliminary operation.

Before starting software installation disconnect any AIM logger from the PC USB port and close all running applications.

A suggested preliminary operation is to check Windows™ “Driver signing” setting.

- Follow this path: Start ➔ setting ➔ Control Panel ➔ System and select “Hardware” layer (figure below on the left).
- Click on “Driver signing” and select “Warn – Prompt me each time to choose an action” (figure below in the right).
- Confirm pressing OK button and close all windows.





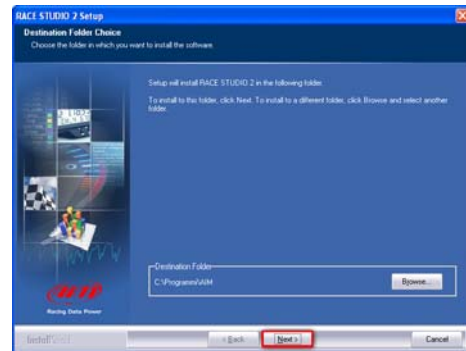
## 2.2 – Installing Race Studio 2 under Microsoft Windows XP

Before installing the software close all applications and insert **Race Studio 2** CD. If “auto play” option is enabled the installation starts automatically, otherwise click twice on “SETUP” icon.

In case of very first Race Studio 2 installation the window on the right appears. It allows to select the window where to install the software.

Press “Browse” button to select Race Studio 2 installation folder.

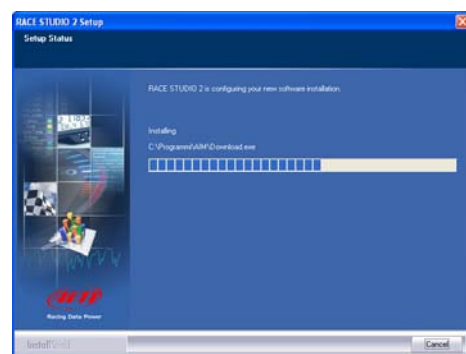
Press “Next” to install the software in the default folder X:/program files/AIM, where “X” is the hard disk where the operative system is installed.



In case of new release of **Race Studio 2** the window on the right appears: enable “New Release of Race Studio 2” checkbox and click on “Next>”



From here onward the installation is the same. The window on the right appears and **Race Studio 2** is installed.

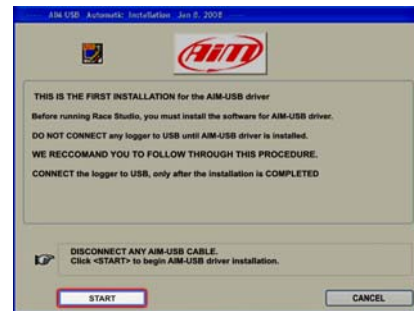


When the installation is over, in case of new release of **Race Studio 2**, the window on the right appears. Click “Finish”. Installation is completed.

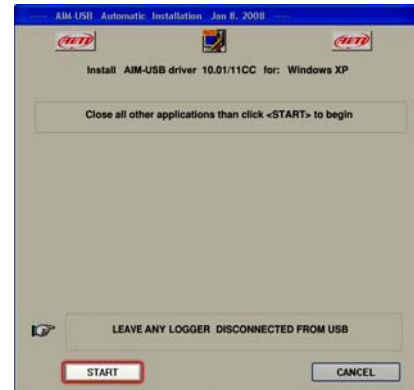


In case of very first installation, on the contrary, the software starts AIM USB driver installation and the window on the right appears.

Disconnect any AIM USB cable from the PC USB port and click on "Start" button.



Close all applications and click "Start".



Click "Continue".



Three panels will assist in the following steps.

Connect the USB cable to the PC USB port and switch the logger on. Wait some seconds and the following panel appears.



This pop up informs the user that the logger is correctly connected to the PC.

**Note:** when the procedure is over, connecting the logger to another PC USB port, the system could ask for USB driver installation on the new port too.



Enable “No, not now” checkbox and click “Next>”.



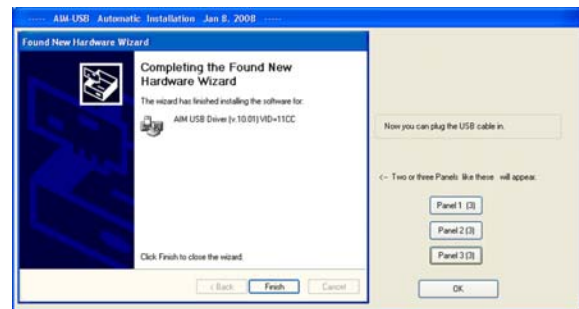
Enable “Install the software automatically” checkbox and click “Next >”.



Click “Finish”.



Click “OK”.



Click “Finish”.



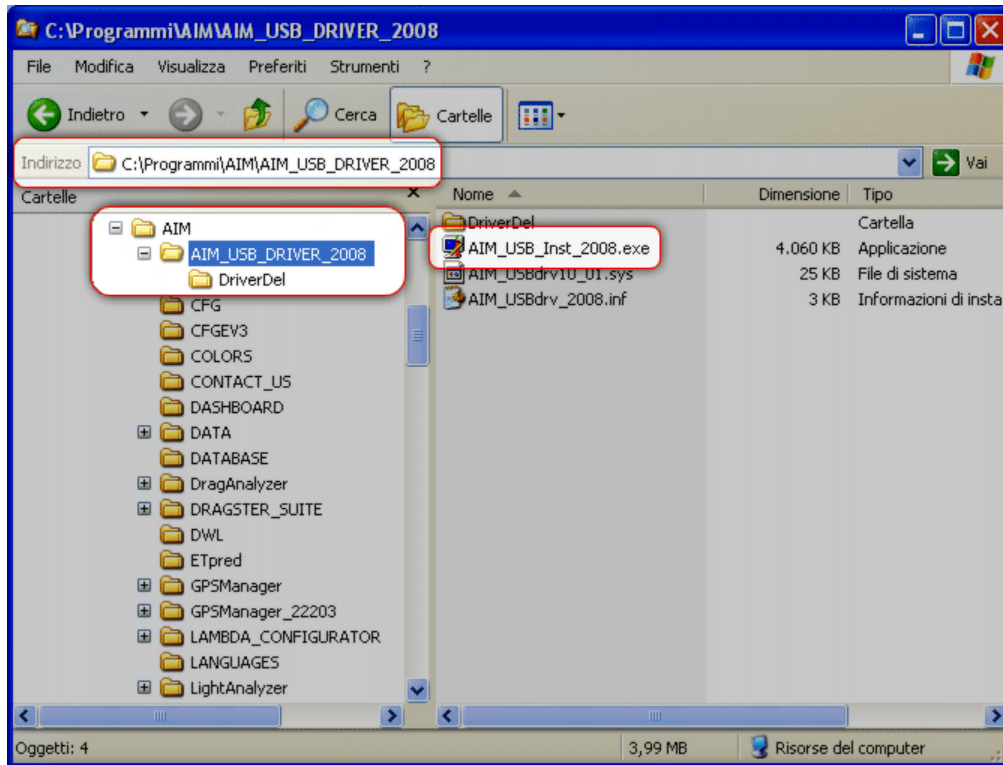
After the first installation two new icons, shown on the right, appear on the PC desktop: Race Studio 2 (Configuration) icon and Race Studio Analysis one. For this last one refer to the proper user manual.



When the first **Race Studio 2** installation is over, all new release installations will jump driver installation (please remember to periodically check download/software area of [www.aimshop.com](http://www.aimshop.com) if new release have been published).

## 2.3 – Troubleshooting

In case driver installation ends incorrectly for any reason, starts maintenance procedure running AIM\_USB\_Inst\_2008.exe. Follow this path: C:\Program files \ AIM \ AIM\_USB\_DRIVER\_2008.



Run AIM\_USB\_Inst\_2008.exe file.



This panel appears. Click "Reinstall driver" and a procedure similar to the first installation starts.

## 2.4 – Installing Race Studio 2 under Microsoft Windows Vista

Microsoft Vista™ operative system introduced more rigid safety procedures.

AIM USB driver is certified by Verisign but “unsigned” by Microsoft. “Unsigned” driver installation needs to run the program “As administrator” that means starting Microsoft Vista™ using an “administrator” account. PC are normally sold with this account.

**Race Studio 2** installation creates a new icon on the PC desktop, that allows the user to start USB driver installation as “Administrator”.



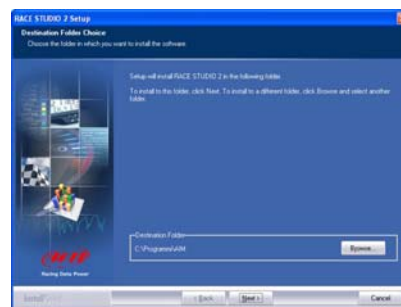
AIM\_USB\_Inst\_2008.exe

Before starting the installation, ensure that the logger is NOT connected to the PC USB port. In case it is, disconnect it.

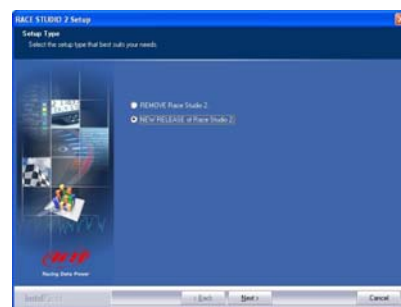
Insert **Race Studio 2** CD in the CD Rom: if “auto play” option is enabled the installation starts automatically, otherwise click twice on “SETUP” icon.

In case of **Race Studio 2** very first installation the window on the right appears. It allows the user to select the software installation folder.

Click on “Browse” to select **Race Studio 2** destination folder or on “Next” to install the software in X:/program files/AIM folder, where “X” is the hard disk where the operative system is installed on.



In case of new release of **Race Studio 2**, the window on the right appears: enable the checkbox “New Release of Race Studio 2” and click “Next>”.



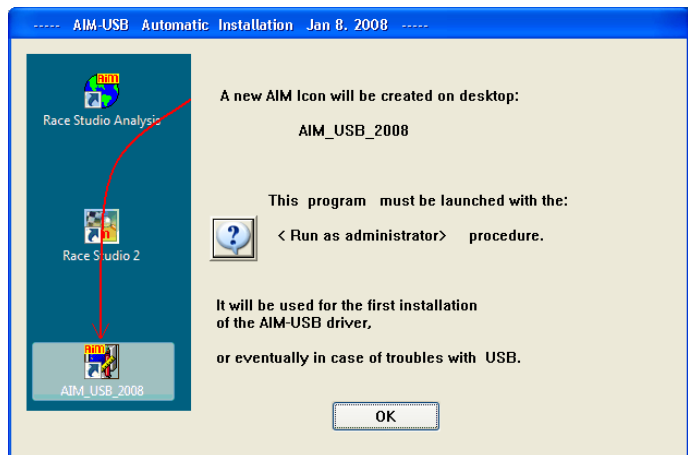
The window on the right appears.



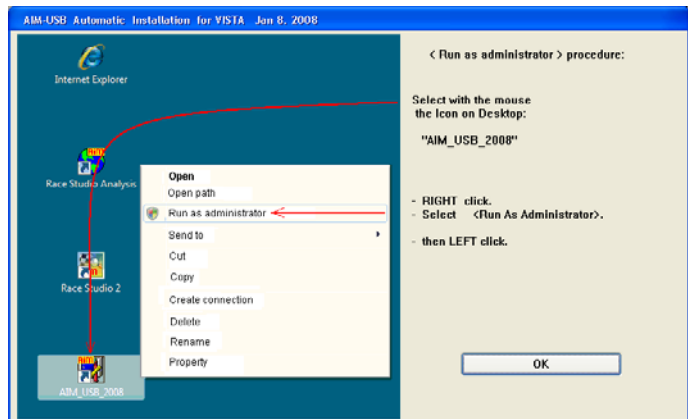
After the installation – in case of new release of **Race Studio 2** – the window on the right appears. Click “Finish”. The installation procedure is complete.



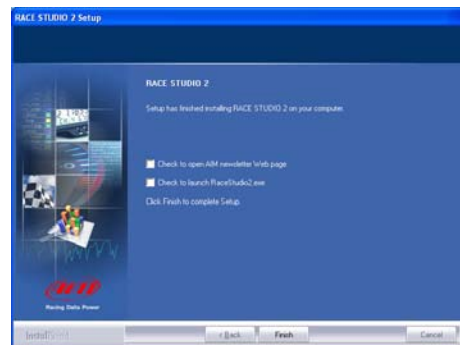
In case of very first installation the window on the right appears. Click on “OK” button, to continue the installation. Click on the question mark to know the <Run as Administrator> procedure. The following window appears.



It shows how to execute <Run as Administrator> procedure; click on “OK” to continue.

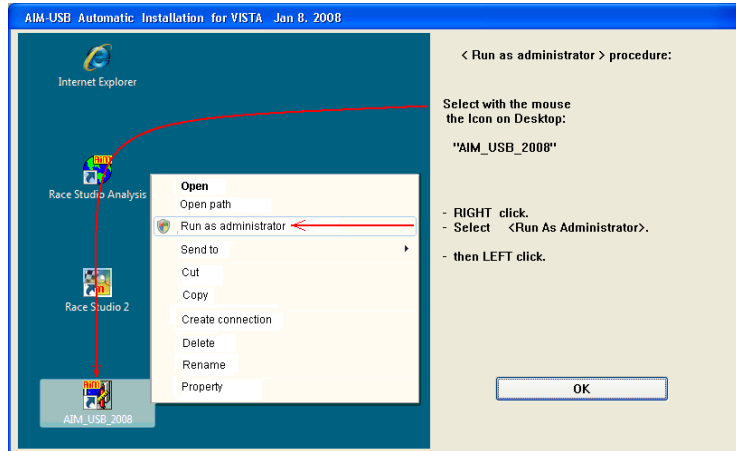


Click on “Finish”.

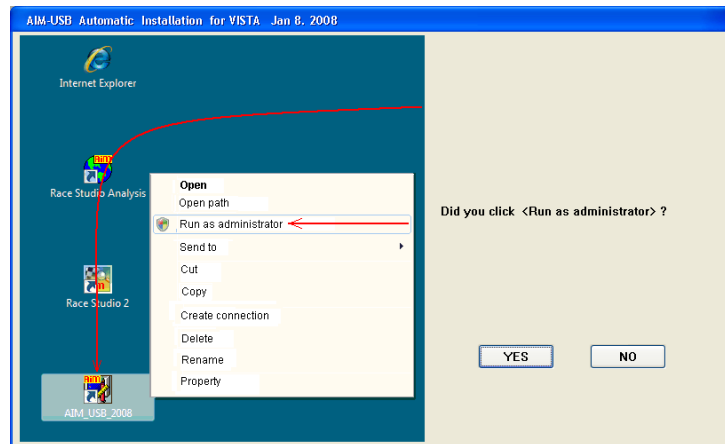


## 2.5 – Installing the USB driver: “Run as Administrator” procedure

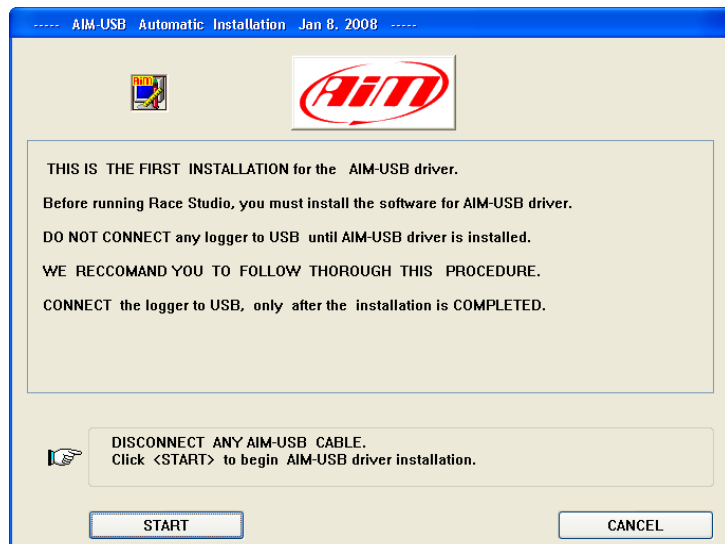
As explained in the image on the right, right click AIM\_USB\_2008 icon on the PC desktop and select “Run as Administrator” option.



Click “YES” to continue.

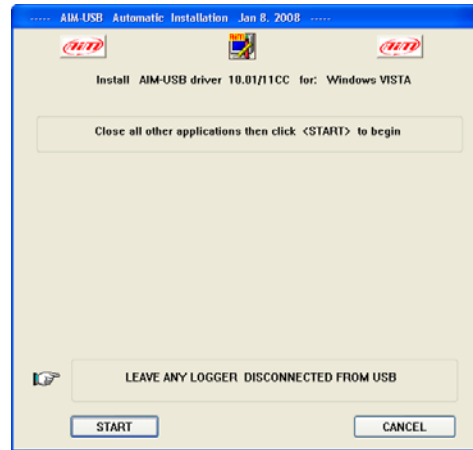


Disconnect any USB cable and click on “START”.

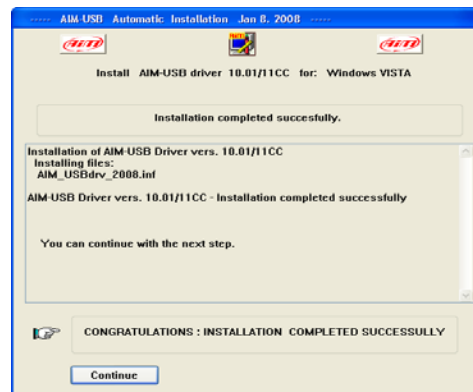




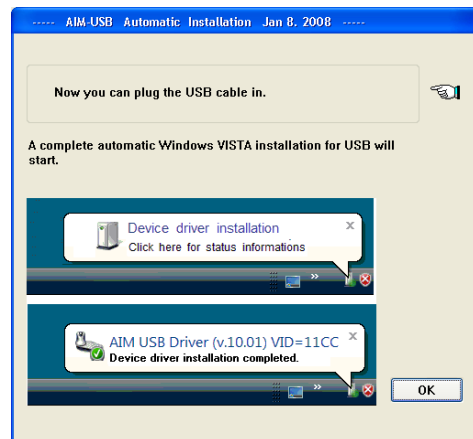
Click "START". AIM USB driver installation starts.



Click "Continue".



Connect the USB cable to the PC USB port.



During **Race Studio 2** and AIM USB driver installation, three new icons appear on the PC desktop:



AIM USB Driver icon



Race Studio 2 (Configuration) icon



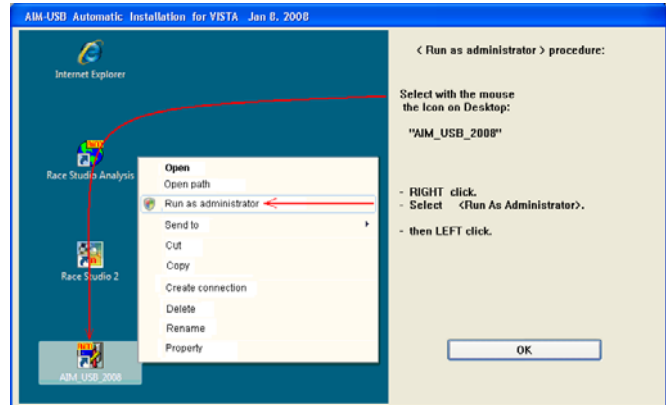
Race Studio Analysis icon

As far as Race Studio Analysis icon is concerned, refer to the proper user manual.

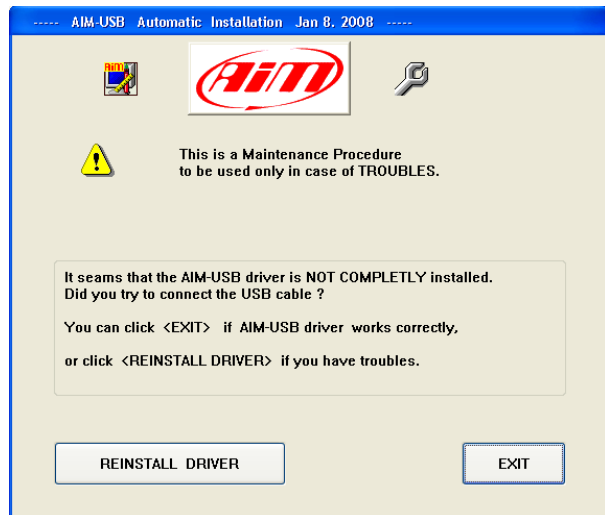
## 2.6 – Troubleshooting

In case USB driver installation ended incorrectly for any reason it is possible to start the maintenance procedure repeating the “Run as Administrator” procedure.

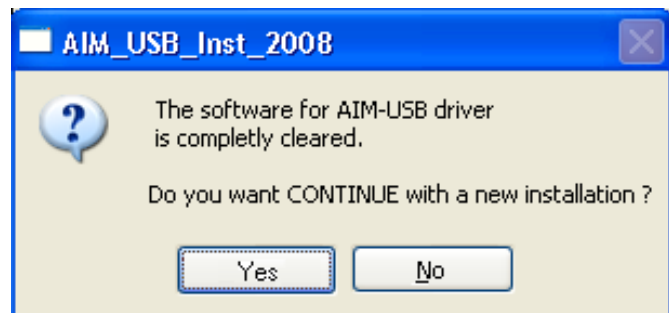
As shown in the figure on the right, right click on “AIM\_USB\_2008” icon on the PC desktop and select “Run as administrator” option.



The panel on the right appears: click “Reinstall driver”.  
 The first step completely erases the first installation.

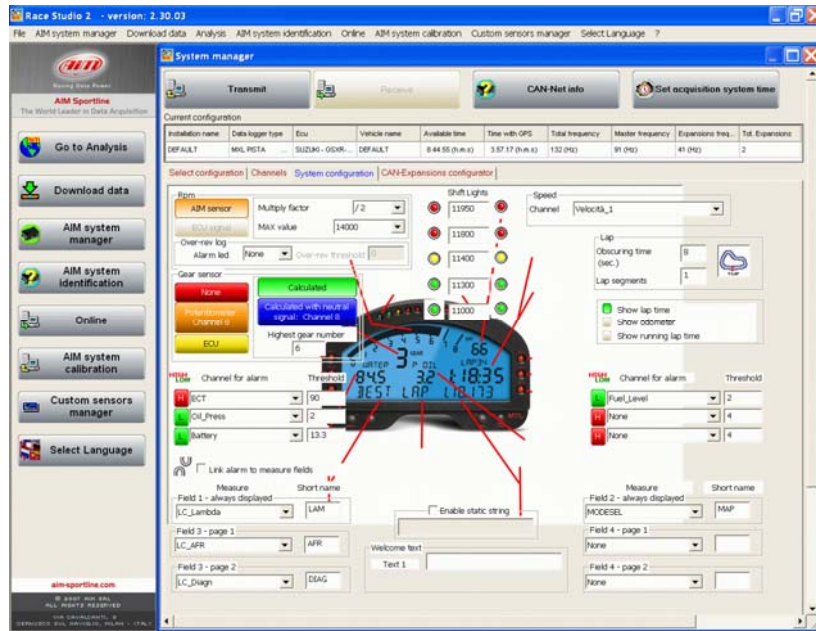


The system asks for confirmation.  
 Click “Yes” to complete the new installation.  
 Click “No” to quit and restart installation procedure later.



## 2.7 – Race Studio 2 visualization problems

Running **Race Studio 2** the display may show a misrepresented image like the one here below.



In this case it is necessary to change monitor settings.

**Warning:** close all running applications, Race Studio 2 included. This operation requires PC rebooting.

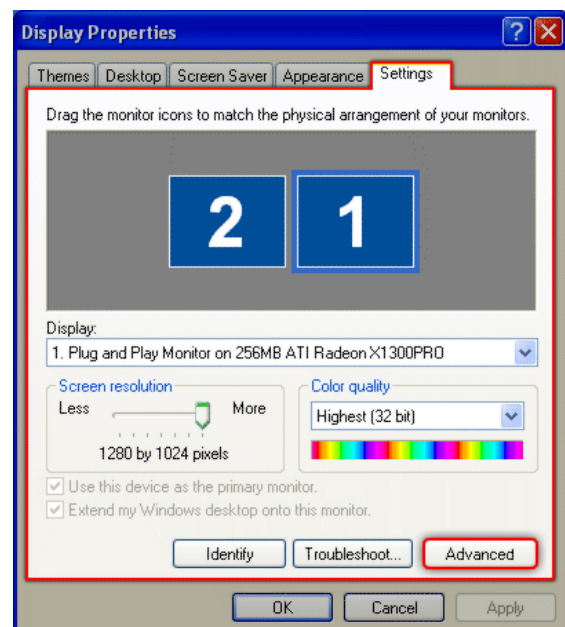
Here below the explanation of the procedure to modify monitor settings:

Follow this path:  
“Start/Setting/ Control Panel /Display”.

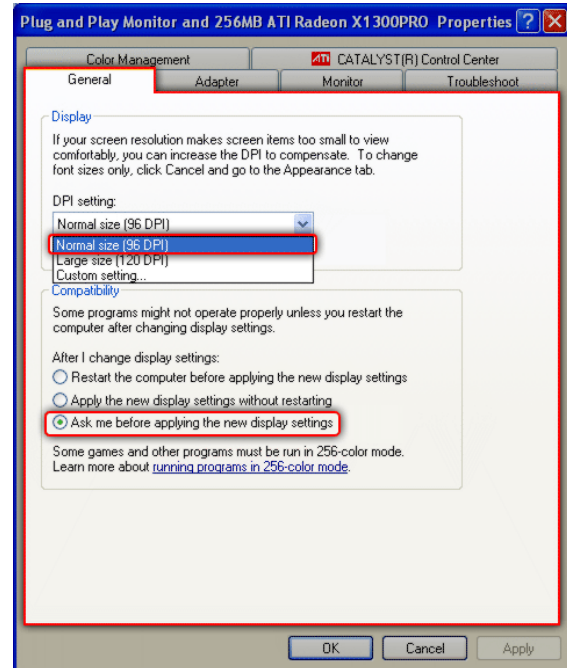
The window “Display Properties”, shown here on the right, appears.

Select “Settings” layer.

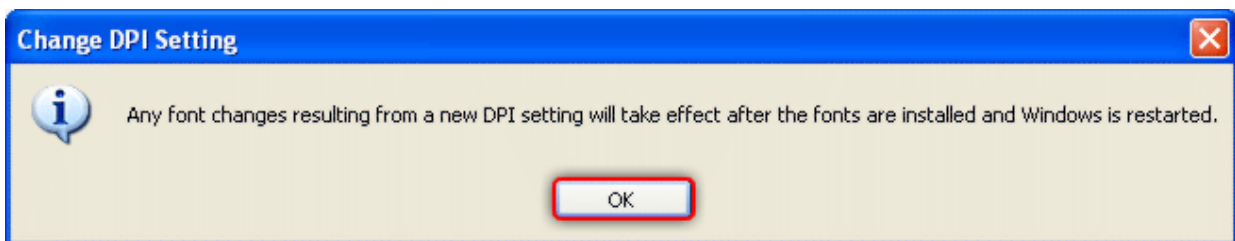
Press “Advanced”.



Enable “Ask me before applying the new display settings” option.  
Set DPI setting on “Normal (96 DPI)”

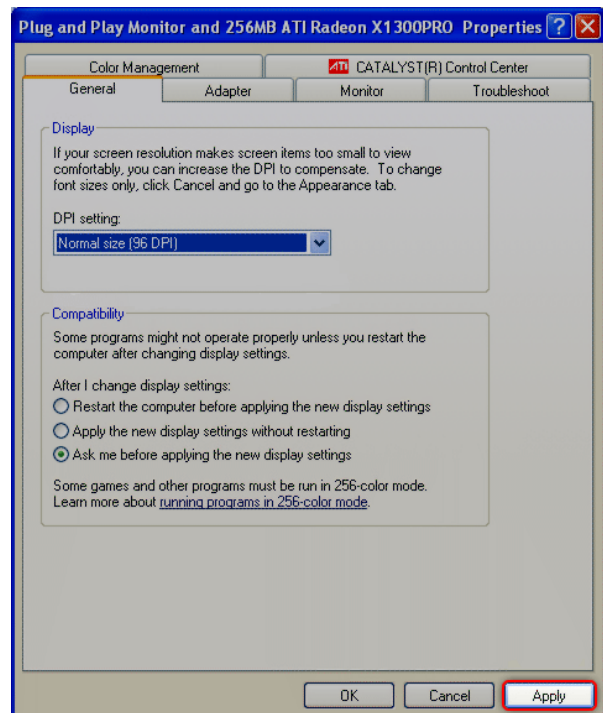


The window here below appears.

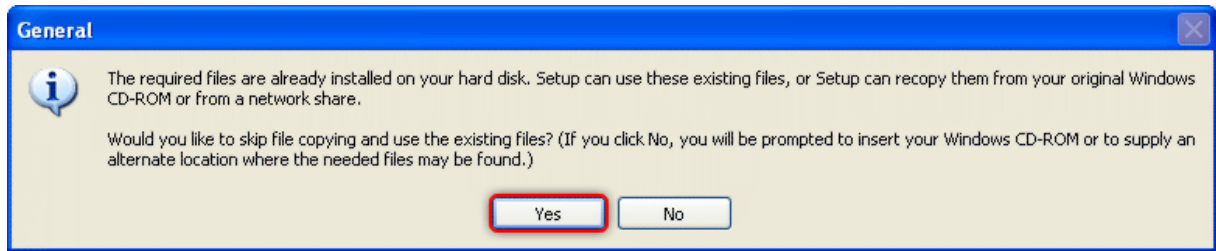


Press “OK”.

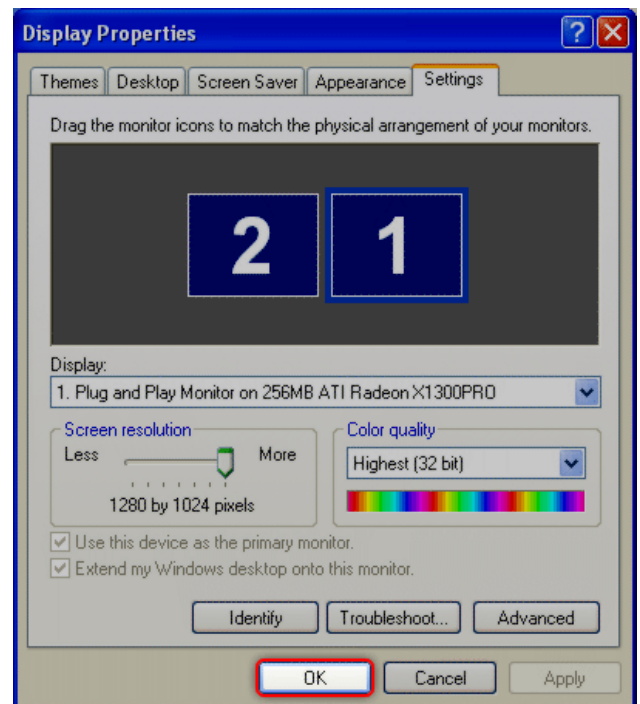
Press “Apply”.



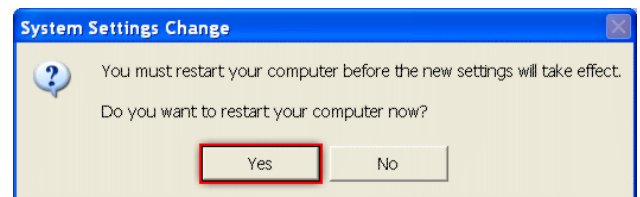
The window here below appears:



Press "Yes".



Press "OK".



Press "Yes".  
The system reboots.

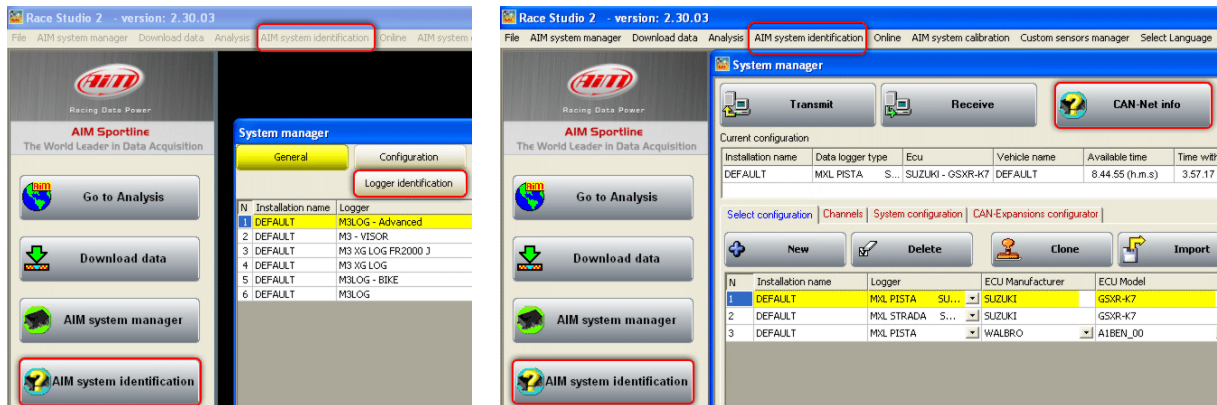
After rebooting run "Race Studio 2" and all works correctly.

## Chapter 3 – System identification

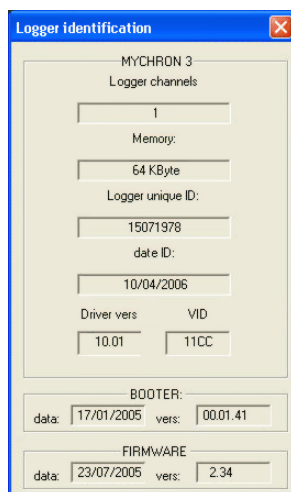
All AIM systems are univocally identified by **Race Studio 2** software. This allows to preliminarily check the communication between PC, software and the logger as to understand if the logger is supported by the software.

It is suggested to make a logger identification before starting any configuration. The procedure is:

- run **Race Studio 2**
- connect the USB cable to the PC and to the logger USB port
- switch the logger on
- press “System identification”. It is on **Race Studio 2** menu bar, in the left vertical keyboard and in system manager window (the button is labelled “System Identification” for all MyChron3 loggers and “CAN-net Info” for the other systems).



If all works correctly, “System identification/CAN-NET info” window, shown below, appears.

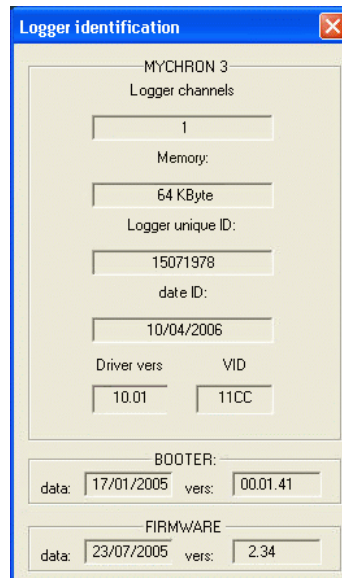


MyChron3 logger identification window



CAN-net info window (other systems)

### 3.1 – System identification of MyChron3



The window shows:

- **Logger channels:** number of channels of the logger
- **Memory:** memory size of the logger (no matter how much of it has already been used)
- **Logger unique ID:** logger serial number
- **Date ID:** logger production date
- **Driver vers. and VID:** information concerning the USB driver
- **Booter (date and vers.):** logger booter date and version
- **Firmware (date and vers.):** logger firmware date and version. It is suggested to check on [www.aimshop.com](http://www.aimshop.com) that the logger firmware version is the latest available; if not, pls. download the latest one, install it and follow instructions that appear on the PC monitor.

## 3.2 – System identification of other loggers.



N	Category of Logger	Type of Logger	Expansion Name	Logger ID	ID Date	Firmware ...	Firmware D...
1	MASTER	MXL PISTA	Master	12345	16/01/2008	14.86.23	19/12/2007
2	CAN EXPANSION	DaVid		47111881	18/01/2008	22.03	09/11/2007
3	CAN EXPANSION	LCU-ONE	LC	111111	13/12/2007	25.09	19/11/2007
4	CAN EXPANSION	GPS		902499	14/01/2008	35.13	17/12/2007
5	CAN EXPANSION	MEMORY KEY		7613105	17/12/2007	37.05	18/12/2007

The window shows:

- **N**: index of the item in the list. This window recognizes all loggers in their order starting always from the Master one (in the figure above an MXL Pista);
- **Category of logger**: role of the logger in the CAN net (master or CAN expansion)
- **Type of logger**: type of device connected
- **Expansion Name**: role of the logger in the CAN network
- **Logger ID**: logger univocal serial number
- **ID Date**: logger production date
- **Firmware Version**: firmware version installed on the logger. It is suggested to check on [www.aim-sportline.com](http://www.aim-sportline.com) website that the firmware version is the latest available; if not, pls. download the latest one, install it and follow the instructions that appear on the PC monitor.
- **Firmware Date**: firmware date.



## Chapter 4 – How to configure MyChron3 kart Plus/Gold/Extreme

To correctly configure, **MyChron3 Kart (Plus, Gold, Extreme)** use a PC and **Race Studio 2** software.

MyChron3 Kart can be configured both via keyboard and via software but some parameters can be set only via software. To measure lateral acceleration (to create track maps), for instance, it is necessary to calibrate the internal accelerometer via software.

Before starting the configuration install **Race Studio 2** and the USB driver as explained in Chapter 2.

Run the software clicking on **Race Studio 2** icon and the window below appears.



In the title bar – white on a blue background in the figure above – you can see the version of **Race Studio 2** installed on the PC.

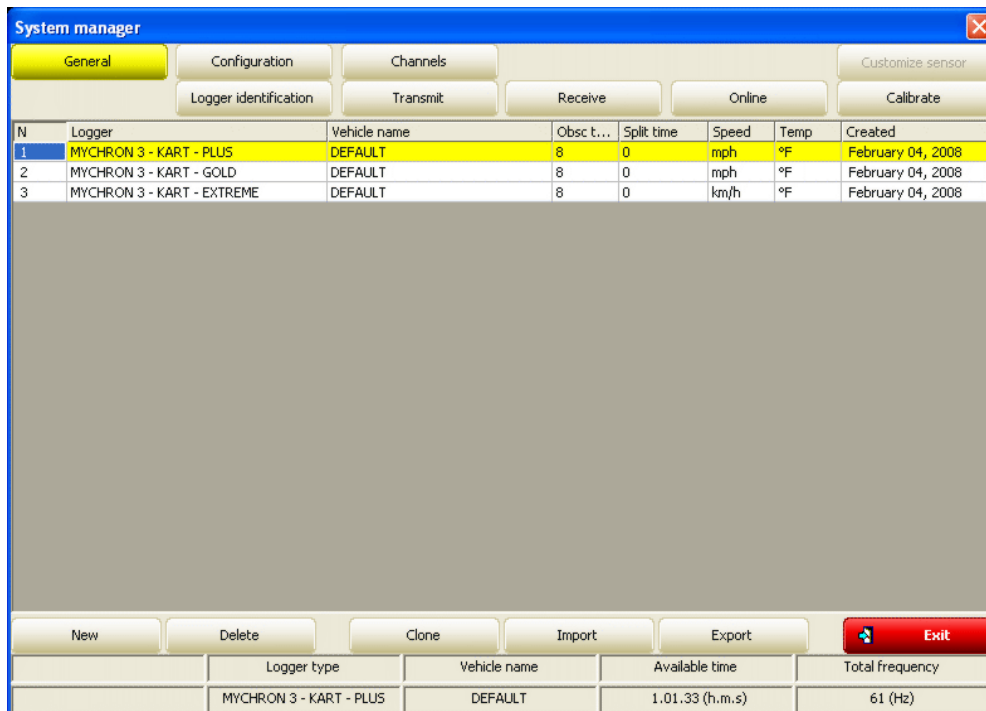
Immediately under there is the menu bar, that is shown in a more immediate way on the left thanks to the graphic buttons: Go to Analysis (this button runs Race Studio Analysis software), Download data, AIM system manager, AIM system Identification, Online, AIM system calibration, Custom sensors manager, Select language.

From this window it is possible to perform all operations necessary to manage all AIM systems.

To enter configuration menu click on “AIM system manager”. A panel showing all systems managed through **Race Studio 2** appears: double click on **MyChron3 Kart Plus/Gold/Extreme** button or click on it and then press “✓Go to” button.



Race Studio 2 “System manager” window appears.



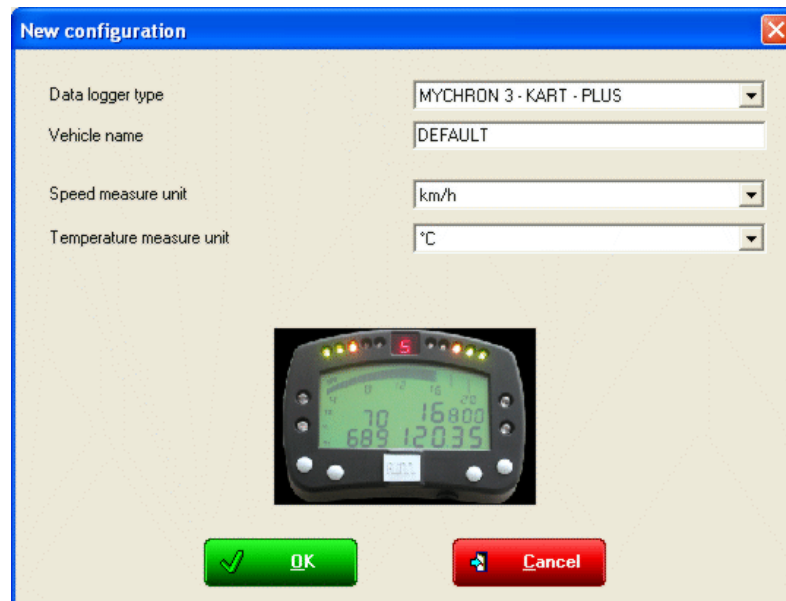
This window has two keyboards.

- **General:** shows “System manager” window. In the central part, with grey background, all configurations currently included in the software database are listed. In case of first configuration, the system shows automatically new configuration window.
- **Configuration:** allows to set or modify an existing configuration. In case of first configuration the central table shows up empty.
- **Channels:** sets all logger channels.
- **System Identification:** identifies the logger connected to the PC.
- **Transmit:** transmits a configuration. Needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger connected to the PC.
- **Online:** allows to verify that the configuration is correct and has been correctly transmitted to the logger and that all works properly.
- **Calibrate:** activates calibration/auto-calibration procedure of the sensors that need it.
- **New:** creates a new configuration
- **Delete:** deletes a configuration
- **Clone:** clones a configuration.
- **Import:** imports a configuration from a file.
- **Export:** exports a configuration to a file.
- **Exit:** quits “System manager” window.

To work on a configuration click on any cell of that configuration row and the entire row is selected (highlighted in yellow).

## 4.1 – Creating a new configuration

Pressing “New” button in system manager window, this window appears:



Some parameters need to be set:

- **Data logger type:** select the logger to be configured.
- **Vehicle name:** insert the vehicle name.
- **Speeds unit of measure:** choose between km/h and Mph;
- **Temperatures unit of measure:** choose between °C and °F;

Press “OK” to save (“Cancel” to quit without saving).

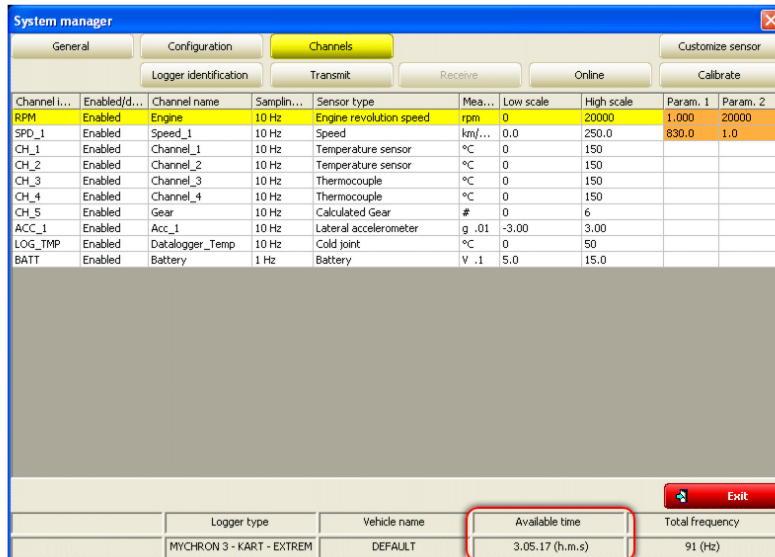
The system comes back to system manager window.



The next step is channels setting. Press “Channels” button.

## 4.2 – Channels

Pressing Channels button the window here below appears.



Channel name	Enabled/d...	Channel name	Sampln...	Sensor type	Mea...	Low scale	High scale	Param. 1	Param. 2
RPM	Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000	1.000	20000
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/...	0.0	250.0	830.0	1.0
CH_1	Enabled	Channel_1	10 Hz	Temperature sensor	°C	0	150		
CH_2	Enabled	Channel_2	10 Hz	Temperature sensor	°C	0	150		
CH_3	Enabled	Channel_3	10 Hz	Thermocouple	°C	0	150		
CH_4	Enabled	Channel_4	10 Hz	Thermocouple	°C	0	150		
CH_5	Enabled	Gear	10 Hz	Calculated Gear	#	0	6		
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00		
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50		
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0		

Logger type	Vehicle name	Available time	Total frequency
MYCHRON 3 - KART - EXTREM	DEFAULT	3:05.17 (h.m.s)	91 (Hz)

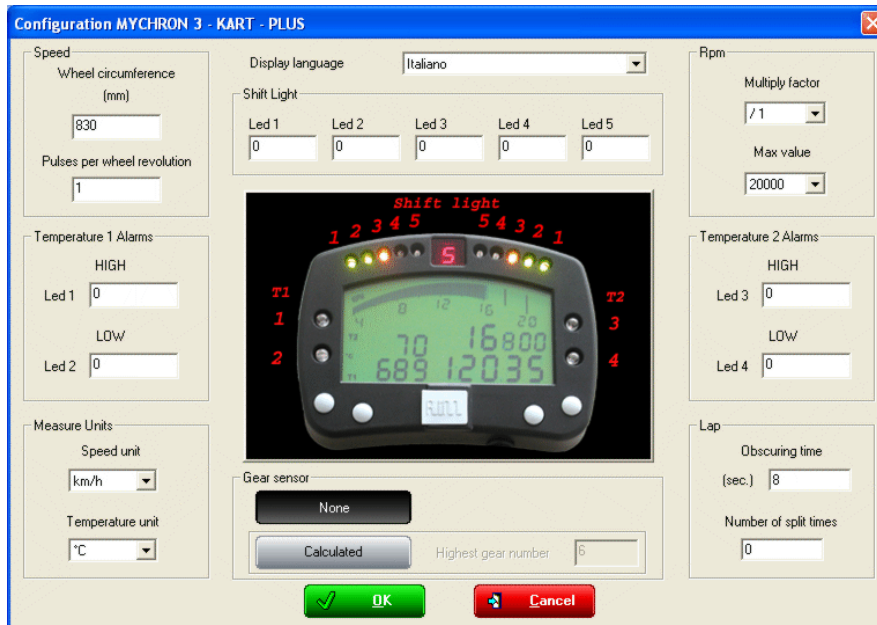
It shows all loggers channels with the related characteristics:

- **Channel identifier:** shows the channel label.
- **Enabled/Disabled:** shows the channel status (enabled/disabled). It can be modified double clicking on the cell except for RPM and SPD that can be modified only through system configuration window.
- **Channel name:** allows to name the channel.
- **Sampling Frequency:** sets each channel sampling frequency. This last one influences the total available time – highlighted by a box in the figure above – that diminishes increasing the sampling frequency because the memory fills up faster.
- **Sensor type:** allows to select the sensor installed on that channel from the drop down menu that appears clicking on that cell. Channels CH\_1 and CH\_2 are temperature channels: the logger can distinguish automatically a thermocouple from a thermo resistor and no configuration is needed. Channels CH\_3 and CH\_4 can be temperature or pressure channels: it is thereby necessary to configure them. CH\_5 is the gear sensor installed in the gearbox that allows **MyChron3** to measure the engaged gear; **MyChron3 Gold/Extreme** has got an internal accelerometer to measure lateral “g”. It allows to create track maps.
- **Measure unit:** show the selected unit of measure for each channel. It is possible to change it double clicking on the cell.
- **High/Low scale:** shows the range of values shown by the graph that will be created in Race Studio Analysis after data download.
- **Param.1/Param2:** values of RPM and speed set in system configuration window.

When all parameters have been set, it is necessary to transmit the configuration to the logger.

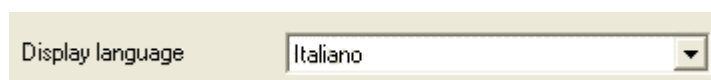
## 4.3 – System configuration

**MyChron3 Kart Plus/Gold/Extreme** has got 14 fully configurable coloured led; the 2 on the left and on the right of the display represent the 4 max and min alarm of the analog channels (temperatures and pressures), while the other 10 led on top of the display are the Shift lights that inform the pilot to shift gear.



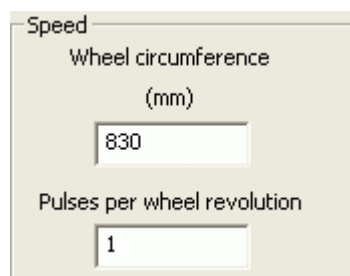
To set alarms, high/low threshold values and configuration parameters it is necessary to complete the window shown here above.

### 4.3.1 – Display language box



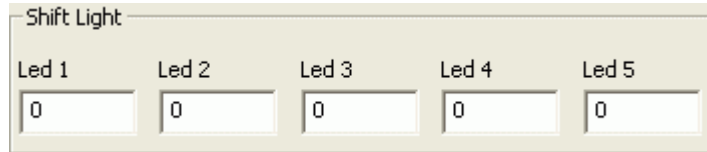
It allows to select the display language from the drop down menu.

### 4.3.2 – Speed box



- **Wheel circumference:** fill in the kart wheel circumference (in mm or in inches); this value is fundamental to correlate the wheel revolution speed to the kart one.
- **Pulses per wheel revolution:** fill in the number of magnets installed on the wheel. When the magnet passes in face of the sensor it generates an electric pulse.

### 4.3.3 – Shift Lights box

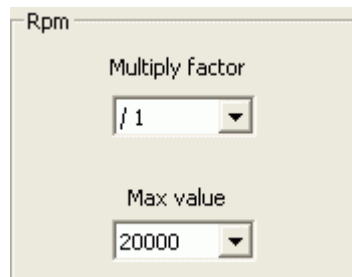


The 'Shift Light' window contains five input fields labeled 'Led 1' through 'Led 5', each with the value '0' entered.

Sets the 5 RPM values, each one corresponding to two of the coloured led placed on top of MyChron3.

Led colours: the first two on the left and on the right are green, the central two are orange and the last four are red. To set the RPM threshold values fill in the cases. The led switches progressively on and when the engine reaches RPM value set in the fifth case all led start blinking, warning the pilot to shift gear. If a value is set on 0 the corresponding led is disabled.

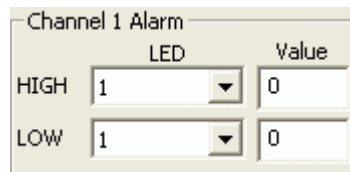
### 4.3.4 – RPM box



The 'Rpm' window has two dropdown menus: 'Multiply factor' set to '/ 1' and 'Max value' set to '20000'.

- **Multiply factor:** it is possible to choose among different values: for a one cylinder two strokes kart the proper value is /1.
- **Max value:** set the RPM high scale.

### 4.3.5 – Channels alarm boxes

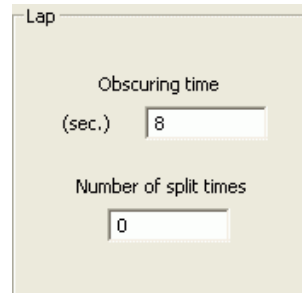


The 'Channel 1 Alarm' window has two rows: 'HIGH' and 'LOW'. Each row has an 'LED' dropdown menu set to '1' and a 'Value' input field set to '0'.

These boxes (2 for **MyChron3 Plus/Gold**, 4 for **MyChron3 Extreme**) allow to set the channels threshold values linking them to the four lateral led of the system.

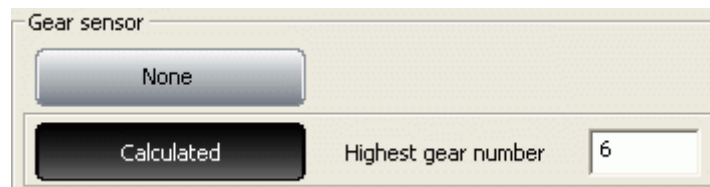
For **MyChron3 Plus** and **Gold** it is possible to connect the min and max threshold values to different Led while for **MyChron3 Extreme** max and min threshold values have to be connected to the same led. Insert max and min value corresponding to the sensors installed on the kart.

### 4.3.6 – Lap box



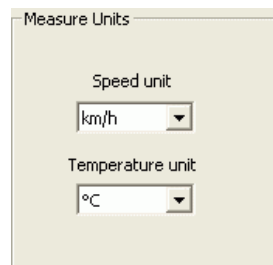
- **Obscuring time:** is a time period during which the lap receiver installed on the kart, after having sampled a lap signal, is “blind” (it does not record signals). This function is useful for split times management on tracks with more magnetic strips/optical transmitters: set obscuring time on a minimum value to sample split times; not to record split times, set obscuring time on a value lower than best lap time and higher then the time elapsed between last split and start/finish line.
- **Number of split times:** is the number of splits the track is divided in and corresponds to the number of magnetic strips/optical transmitters installed there.

### 4.3.7 – Gear sensor box



- **None:** not to see the engaged gear number.
- **Calculated:** to calculate the engaged gear number (see the related chapter for further information). In this last case, “Highest gear number” case is enabled: fill in the kart number of gears.

### 4.3.8 – Unit of measure box



- **Speed Unit:** choose between km/h and mph
- **Temperature unit:** choose between °C and °F.

When all configuration parameters have been set, click on “OK” button to save (“Cancel” to quit without saving). It is now necessary to transmit the configuration to the logger.



## **4.4 – Transmitting the configuration**

The procedure to transmit the configuration to the logger is the same for all AIM loggers. See chapter 13 for further information.

## **4.5 – Auto calibration of the accelerometer (Gold/Extreme only)**

The auto-calibration procedure is the same for all AIM loggers. See paragraph 14.2 for further information.

## **4.6 – Gear Calculation**

See chapter 15 for further information.

## **4.7 – Online**

Online function is very useful to check the logger proper working. See chapter 18 for further information.

## Chapter 5 – How to configure MyChron3 Car/Bike Plus/Gold/Extreme

To correctly configure **MyChron3 Car/Bike Plus/Gold/Extreme** use a PC and Race Studio 2 software.

**MyChron3 Car/Bike** can be configured both via keyboard and via software but some channels, like these with temperature or pressure sensors, accelerometer or gyroscope, cannot be set via keyboard.

Before starting the configuration install **Race Studio 2** and the USB driver as explained in Chapter 2.

Run the software clicking on **Race Studio 2** icon and the window below appears:



In the title bar – white on a blue background in the figure – you can see the version of **Race Studio 2** installed on the PC.

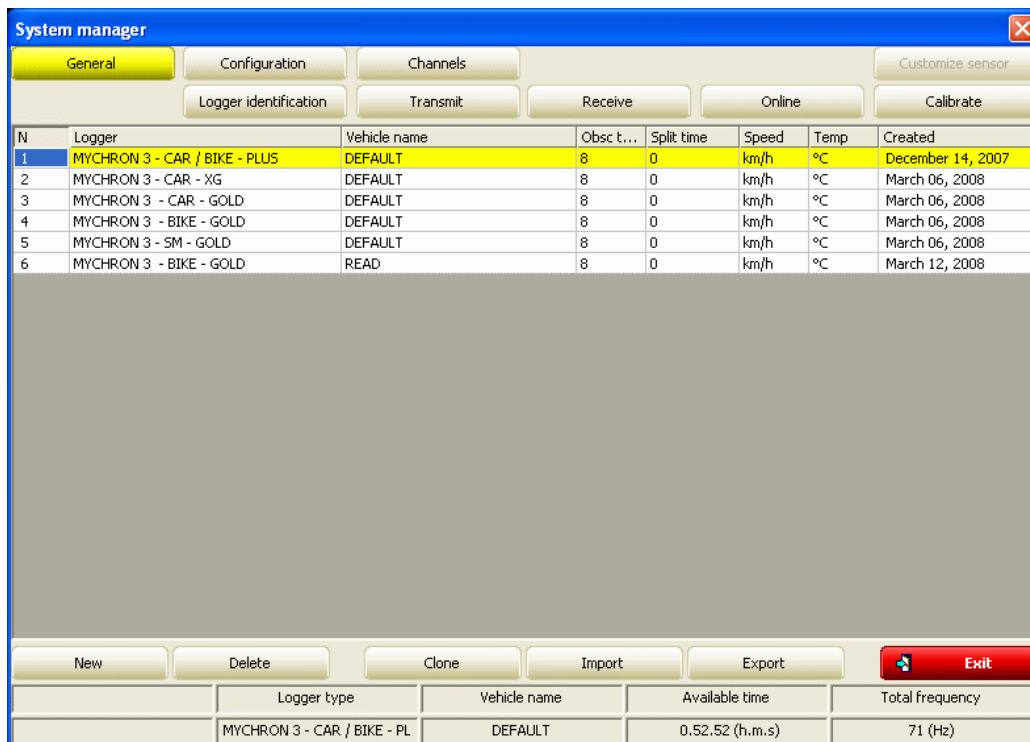
Immediately under there is the menu bar, that is shown in a more immediate way on the left thanks to graphic buttons: Go to Analysis (this buttons runs the analysis software Race Studio Analysis), Data download, AIM system manager, AIM system identification, Online, AIM System Calibration, Custom sensors management, Select language.

Through this window it is possible to perform all operations necessary to manage all AIM systems.

To enter configuration menu click on “AIM System manager”. A panel showing all systems managed through **Race Studio 2** appears: double click on **MyChron3 Car/Bike Plus/Gold/Extreme** button or select it and click on “✓Go to” button.



Race Studio 2 System manager window appears.



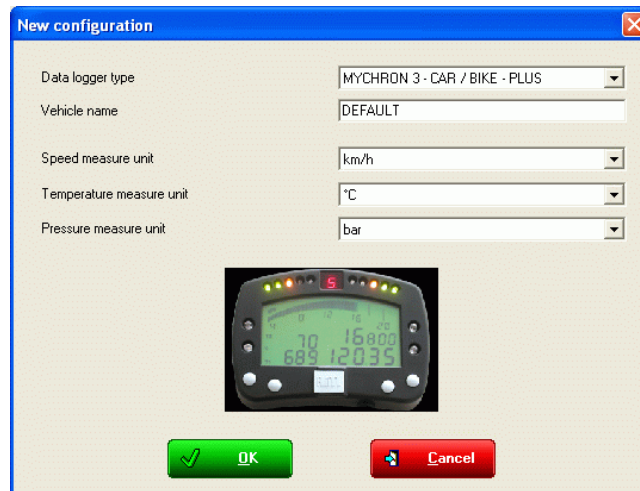
This window has two keyboards.

- **General:** shows “System manager window”. In the central part, with grey background, all configurations currently included in the software database are listed. In case of first configuration the software shows directly “New configuration” window.
- **Configuration:** allows to set or modify a configuration.
- **Channels:** allows to set all loggers channels.
- **System Identification:** identifies the logger connected to the PC.
- **Transmit:** transmits a configuration to the logger. It needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger connected to the PC.
- **Online:** allows to check that the configuration is correct and has been correctly transmitted to the logger and that all works properly.
- **Calibrate:** activates calibration/auto-calibration procedure of the sensors that need it.
- **New:** creates a new configuration.
- **Delete:** deletes a configuration.
- **Clone:** clones a configuration.
- **Import:** imports a configuration from a database or from a file.
- **Export:** exports a configuration in a file.
- **Quit:** quits “System Manager” window.

To work on a configuration click on any cell of that configuration row and the entire row is selected (highlighted in yellow).

## 5.1 – Creating a new configuration

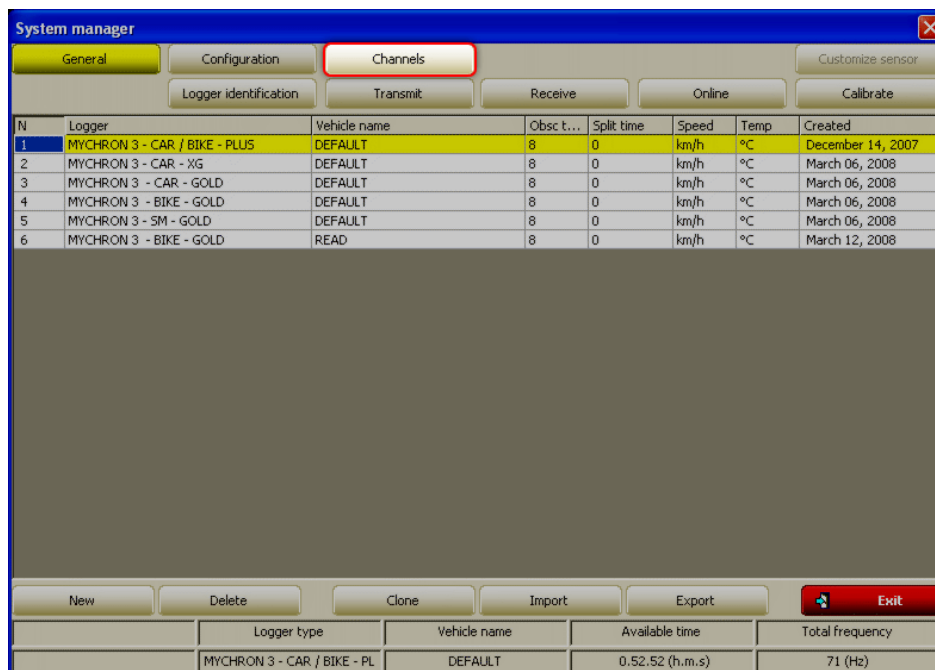
Pressing “New” button in “System Manager” window, this window appears.



Some parameters need to be set:

- **Data Logger type:** select the logger to be configured.
- **Vehicle Name:** insert the vehicle name.
- **Speeds unit of measure:** choose between km/h and Mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (“Cancel” to quit without saving).  
 The system comes back to system manager window.

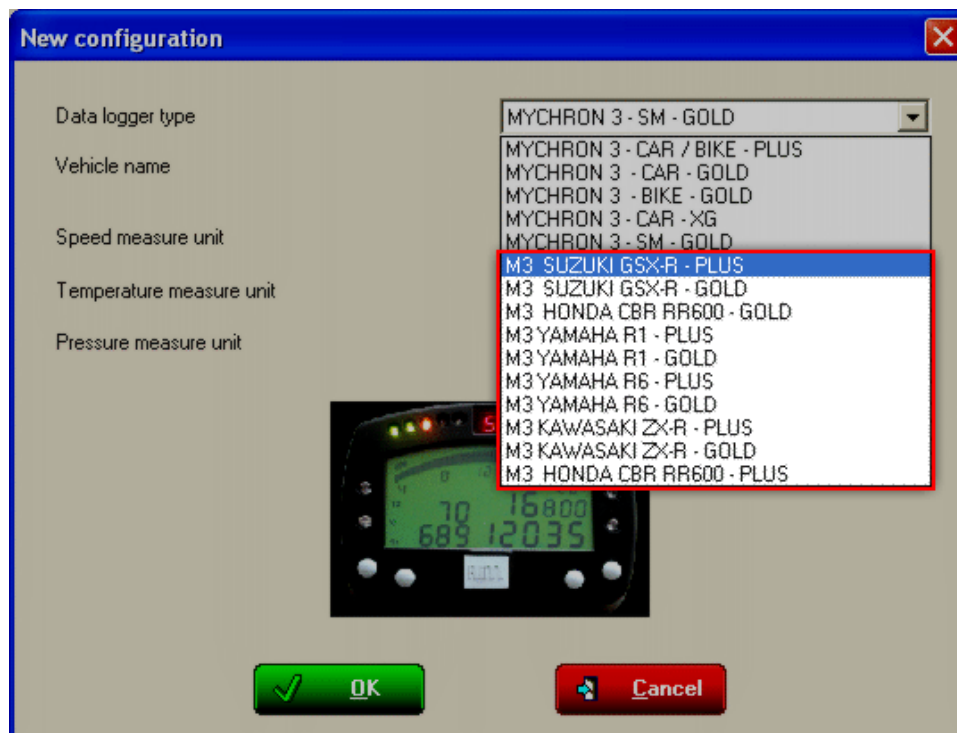


The next step is channels setting. Press “Channels”.

### 5.1.1 – MyChron3 Plus/Gold Bike Plug&Play configurations

**MyChron3 Plus/Gold Plug&Play** kits for Bike installations include, beside the logger, all what is needed for an easy installation on the bike (wiring, bracket, screws, washers, etc.). At present, the most important models/brands have got their kits available. All information are on AIM website at [www.aim-sportline.com](http://www.aim-sportline.com) clicking “Special Applications”.

When the kit has been correctly installed (see each kit user manual for further information) just power on the bike. Should any configuration problem occur select the proper configuration in “New configuration” window, shown here below. The red box highlights Plug&Play configurations now available.



If the bike is completely corresponding to the stock one sold by the manufacturer, selecting the related configuration is enough to transmit it to the logger. In case, on the contrary, additional sensors have been installed, they need to be configured following the procedures here described.

**Warning:** all parameters set in Plug&Play configurations have been tested to work correctly. Refer to each kit user manual for any information concerning the configuration and to modify it.

### 5.1.2 – MyChron3 Gold Snow Mobile configuration

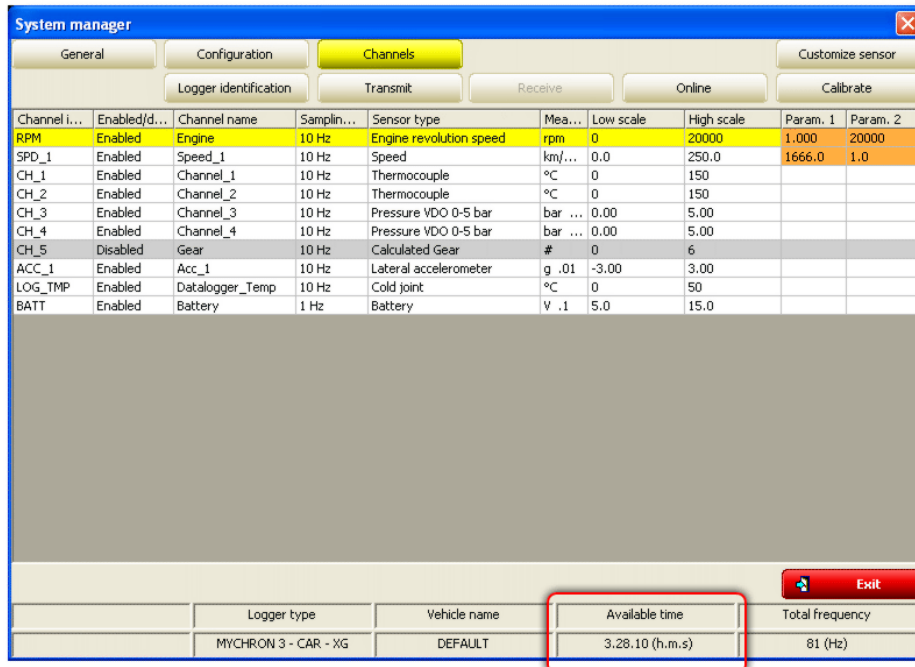
AIM produces a particular version of **MyChron3 Gold** for **Snowmobile** installations. This particular MyChron3 application is supported by the configuration labelled “MyChron3 – SM – Gold”. When the logger has been correctly installed and the eventual additional sensors connected (refer to the related documentation for further information), it is necessary to configure the logger. Select the logger between these available in “New configuration” window.



Pressing “OK” the system comes back to System manager window. The next step is channels setting; press “Channels”.

## 5.2 – Channels

Pressing Channels button this window appears.



Channel i...	Enabled/d...	Channel name	Sampl...	Sensor type	Mea...	Low scale	High scale	Param. 1	Param. 2
RPM	Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000	1.000	20000
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/...	0.0	250.0	1666.0	1.0
CH_1	Enabled	Channel_1	10 Hz	Thermocouple	°C	0	150		
CH_2	Enabled	Channel_2	10 Hz	Thermocouple	°C	0	150		
CH_3	Enabled	Channel_3	10 Hz	Pressure VDO 0-5 bar	bar ...	0.00	5.00		
CH_4	Enabled	Channel_4	10 Hz	Pressure VDO 0-5 bar	bar ...	0.00	5.00		
CH_5	Disabled	Gear	10 Hz	Calculated Gear	#	0	6		
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00		
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50		
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0		

Logger type	Vehicle name	Available time	Total frequency
MYCHRON 3 - CAR - XG	DEFAULT	3.28.10 (h.m.s)	81 (Hz)

It shows all channels set on the logger with the related characteristics:

- **Channel Identifier:** shows channel label.
- **Enabled/Disabled:** shows channel status (enabled/disabled). It is modifiable with a double click on the cell except for RPM, Speed and Gear that can be modified only through System configuration window.
- **Channel name:** names the channel.
- **Sampling Frequency:** sets each channel sampling frequency. This last one influences the total available sampling time – highlighted by a box in the figure above – that diminishes increasing the sampling frequency because the memory fills up faster.
- **Sensor type:** allows to select the sensor installed on that channel from the drop down menu that appears clicking on that cell. Channels CH\_1-CH\_4 support temperature or pressure sensors (MyChron3 Plus), potentiometers and Lambda probe (MyChron3 Gold/Gold XG). User can set the desired sensor selecting it from the drop down menu. Channel CH\_5 is gear channel. MyChron3 Gold Bike allows to install an external gyroscope on channel CH\_7 to create the track map while MyChron3 Gold/Gold XG (Car) has a lateral internal accelerometer (labelled ACC\_1) for the same purpose.
- **Measure unit:** allows to select the sensor unit of measure.
- **High/Low scale:** shows the range of values visualized by the graph that will be created by Race Studio Analysis after data download.
- **Param.1/Param2:** the values of RPM and speed parameters set in system configuration window.

When all parameters have been set it is necessary to transmit the configuration to the logger.

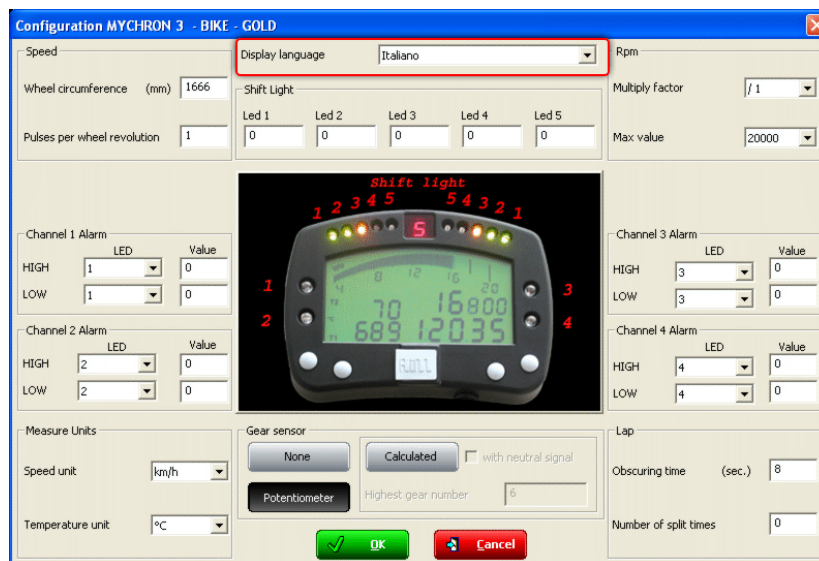


## 5.3 – Creating a custom sensor

The procedure to create a custom sensor is the same for all AIM loggers. Refer to the related chapter for further information.

## 5.4 – System configuration

**MyChron3 Car/Bike Plus/Gold/Extreme** has 14 fully configurable alarm led; the 2 on the left and on the right of the display are the 4 high/low alarm led of the analog channels (temperatures and pressures), while the other 10 on top of the display are the Shift lights that warn the pilot to shift gear.



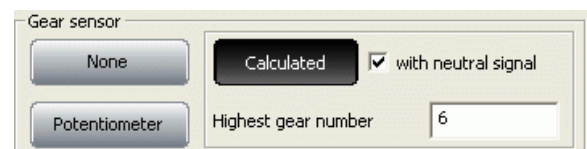
To set alarms, high/low threshold values and configuration parameters it is necessary to fill in the above reported window.

First of all select the display language red circled in the figure above.

**Note:** in case of a Plug&Play kit this window is already configured.

This window is to be completed like that of MyChron3 Kart (see paragraph 4.2.) except for Gear sensor box, shown here below. Available options are:

- **“None”**: not to see the engaged gear on the display.
- **“Potentiometer”**: a gear potentiometer<sup>1</sup> is available.
- **“Calculated”**: to calculate the engaged gear<sup>2</sup>; specify whether a neutral sensor is available or not if required.

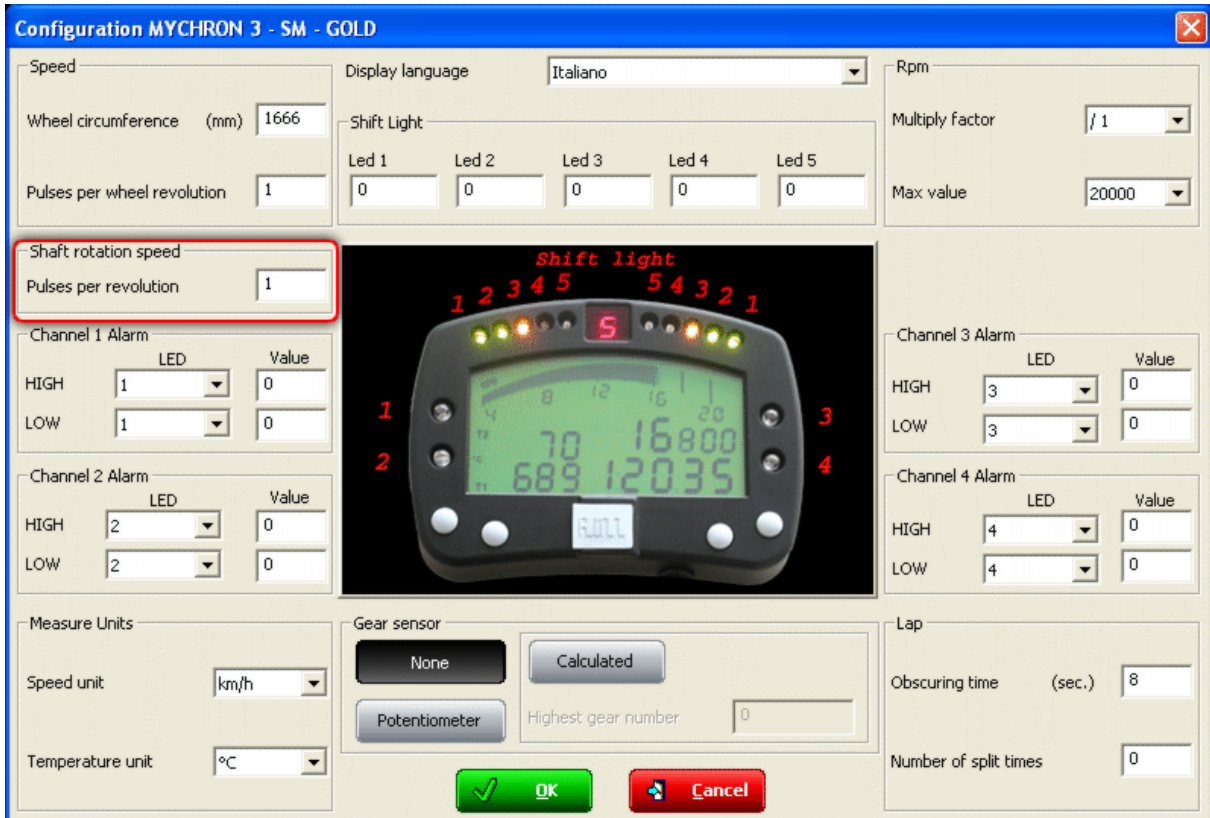


<sup>1</sup> See paragraph 14.3 for further information.

<sup>2</sup> See chapter 15 for further information.

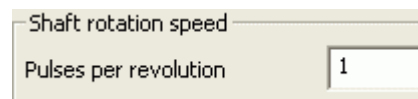
### 5.4.1 – System configuration of MyChron3 Gold Snow Mobile

In case of a **MyChron3 Gold Snowmobile**, configuration window is slightly different, as shown below. It has an additional box labelled “Shaft rotation speed”.



The window is to be completed like the other MyChron3 of this group (see paragraphs 4.2 and 5.2) except for Shaft rotation speed box, reported here below.

Fill in the pulses for shaft revolution. This value corresponds to the number of magnets installed on the snowmobile transmission shaft.



## 5.5 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 13 for further information.

## 5.6 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, to say auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate the gear sensor, the mid zero potentiometer and the zero based potentiometer installed on the vehicle.

See chapter 14 for further information.

**Warning:** if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.

## 5.7 – Gear calculation

Refer to chapter 15 for further information.

## 5.8 – Online

Online function is very useful to check the logger proper working. See chapter 18 for further information.

## Chapter 6 – How to configure MyChron3 Log/Visor/XGLog

To correctly configure **MyChron3 Log/Visor/XGLog**, use a PC and **Race Studio 2** software.

**MyChron3 Log/Visor/XGLog** can be configured both via keyboard and via software but some channels can only be set via software. Temperature or pressure sensors, as well as ECU signals cannot be set via keyboard, exactly like accelerometers, potentiometers, the gyroscope etc....

Before starting the configuration, install **Race Studio 2** and the USB driver as explained in chapter 2.

Run the software clicking on the related icon and the window here below appears.



In the title bar – white on a blue background in the figure – you can see the **Race Studio 2** version installed on the PC .

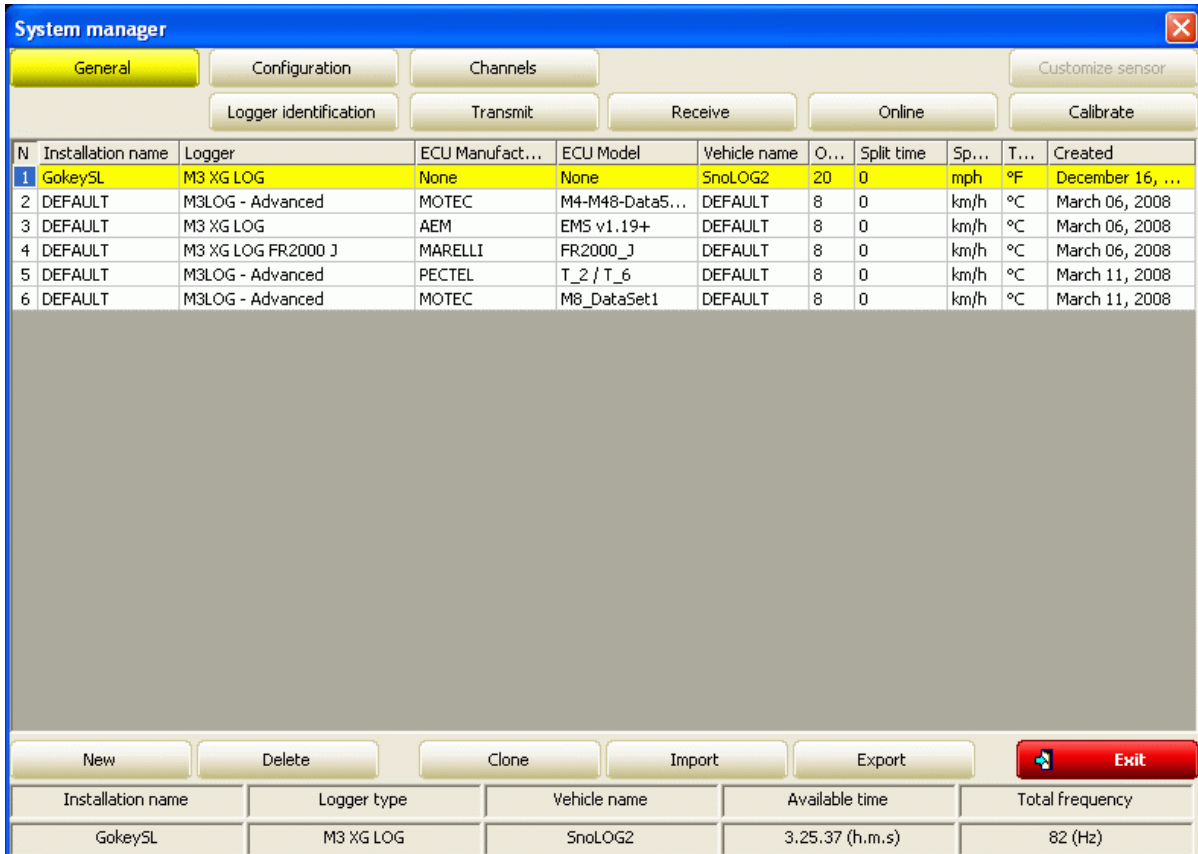
Immediately under there is menu bar, shown in a more intuitive way on the left thanks to the graphic buttons: Go to Analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

From this window it is possible to perform all operations necessary to manage all AIM systems.

To enter configuration menu click on “AIM system manager” button . A panel showing all systems managed through **Race Studio 2** software appears: double click on “**M3Log/Visor XGLog**” or select it and click on “✓Go to” button.



Race Studio 2 “System manager” window appears.



The screenshot shows the 'System manager' window with a blue title bar and a close button. Below the title bar are several tabs: 'General' (selected), 'Configuration', 'Channels', 'Customize sensor', 'Logger identification', 'Transmit', 'Receive', 'Online', and 'Calibrate'. The main area contains a table with the following data:

N	Installation name	Logger	ECU Manufact...	ECU Model	Vehicle name	O...	Split time	Sp...	T...	Created
1	GokeySL	M3 XG LOG	None	None	SnoLOG2	20	0	mph	°F	December 16, ...
2	DEFAULT	M3LOG - Advanced	MOTEC	M4-M48-Data5...	DEFAULT	8	0	km/h	°C	March 06, 2008
3	DEFAULT	M3 XG LOG	AEM	EMS v1.19+	DEFAULT	8	0	km/h	°C	March 06, 2008
4	DEFAULT	M3 XG LOG FR2000 J	MARELLI	FR2000_J	DEFAULT	8	0	km/h	°C	March 06, 2008
5	DEFAULT	M3LOG - Advanced	PECTEL	T_2 / T_6	DEFAULT	8	0	km/h	°C	March 11, 2008
6	DEFAULT	M3LOG - Advanced	MOTEC	M8_DataSet1	DEFAULT	8	0	km/h	°C	March 11, 2008

Below the table are buttons for 'New', 'Delete', 'Clone', 'Import', 'Export', and a red 'Exit' button. At the bottom, there is a summary table:

Installation name	Logger type	Vehicle name	Available time	Total frequency
GokeySL	M3 XG LOG	SnoLOG2	3.25.37 (h.m.s)	82 (Hz)

Top and bottom keyboards allows the user to perform all needed operations to manage an AIM system. For further information concerning each button refer to the introductory paragraph of chapter 5.

Central is the database of the available configurations. To work on one of them click on any cell of that configuration and the entire row is selected (highlighted in yellow). In case of very first configuration, when selecting this logger the system shows “New configuration” window and not “General” window.

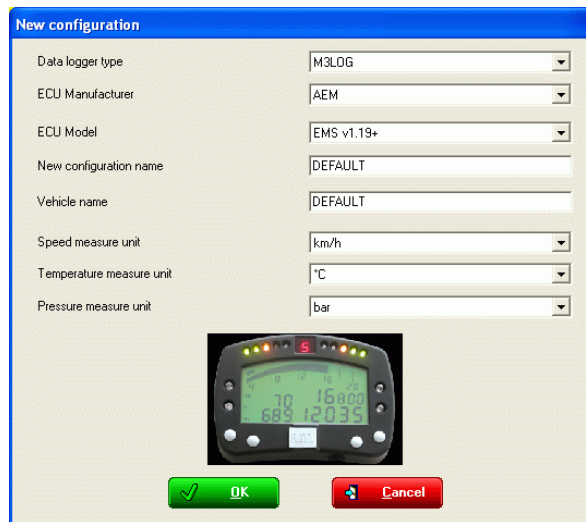
## 6.1 – Premise on MyChron3 Log/Visor/XGLog

Systems managed through this button are: **MyChron3 LOG Advanced**, **MyChron3 Visor**, **MyChron3 XG LOG FR2000J** (configuration properly created for Japanese Formula Renault 2000 championship), **MyChron3 XG LOG**, **MyChron3 LOG Bike** and they differ from these previously explained because they can be connected to the engine control unit (**from here onward ECU**) of the vehicle.

For any information regarding the ECUs currently supported by AIM loggers, the procedures for a proper communication and connection between ECUs and AIM loggers, please refer to “Download Area” of AIM corporate at [www.aimshop.com](http://www.aimshop.com).

## 6.2 – Creating a new configuration

Pressing “New” button in system manager window this window appears.

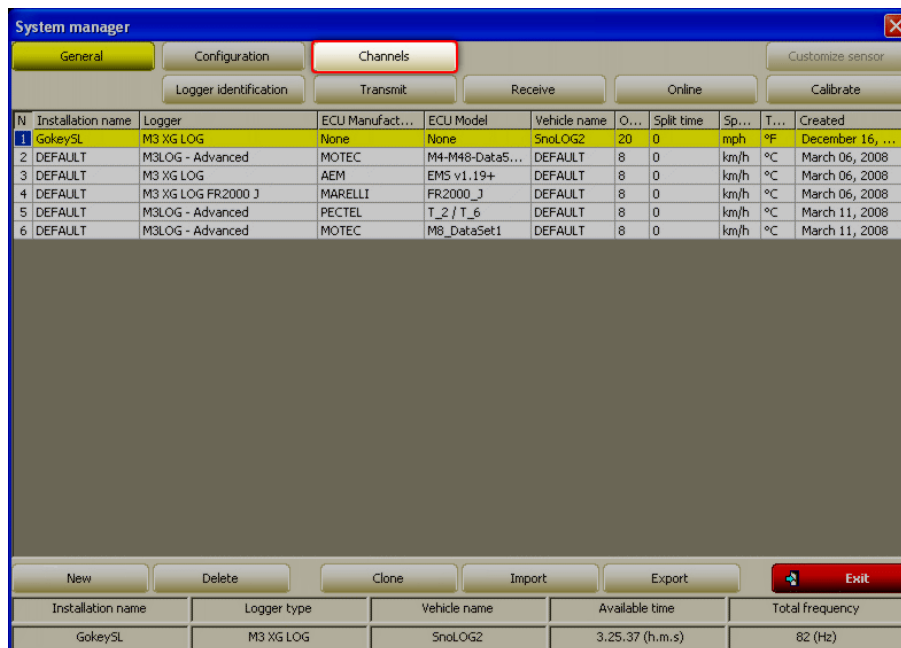


Some parameters need to be set:

- **Data logger type:** select the logger to be configured (please note: logger labelled M3 XG LOG FR2000J creates a configuration properly developed for Japanese Formula Renault 2000 championship);
- **ECU Manufacturer:** select the manufacturer of the ECU installed on the vehicle or none.<sup>3</sup>
- **ECU Model:** select the ECU model or none.
- **New configuration name:** fill in the configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Speeds unit of measure:** choose between km/h and Mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressure unit of measure:** choose between Bar and PSI.

Press “OK” to save (“Cancel” to quit without saving).  
 The system comes back to system manager window.

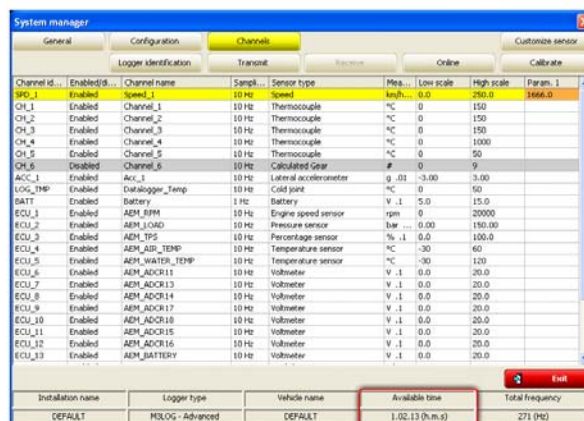
<sup>3</sup> This last option is only available for **MyChron3 XG Log** and **MyChron3 Log Bike**, the only loggers of this group that can work also without being connected to an ECU.



The next step is channels setting. Press “Channels”.

### 6.2.1 – MyChron3 XG Log FR2000J configuration

AIM produces a particular version of MyChron3 XG Log properly created for Japanese Formula Renault 2000 championship and labelled MyChron3 XG Log FR2000J. This particular application is supported by a configuration included in the available configurations database in MyChron3 Log/Visor XG Log menu. When the logger has been correctly installed and the sensors connected it is necessary to configure the logger. Select the logger between these available in “New Configuration” window.

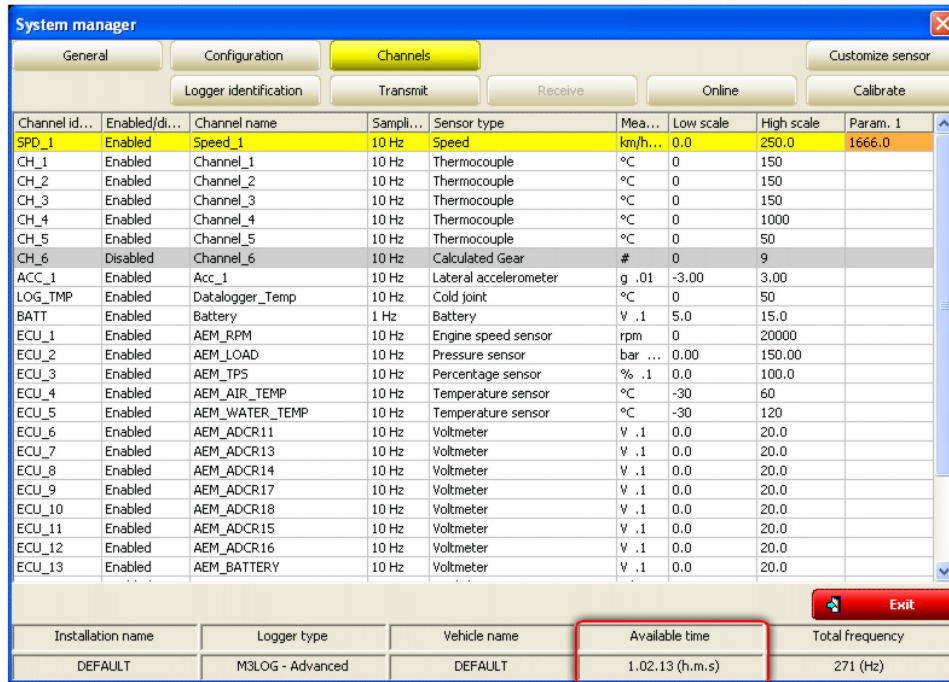


Pressing “OK” the system comes back to System manager window. The next step is channels setting, press “Channels”.



## 6.3 – Channels

Pressing Channels button this window appears.



Channel id...	Enabled/di...	Channel name	SAMPLI...	Sensor type	Mea...	Low scale	High scale	Param. 1
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/h...	0.0	250.0	1666.0
CH_1	Enabled	Channel_1	10 Hz	Thermocouple	°C	0	150	
CH_2	Enabled	Channel_2	10 Hz	Thermocouple	°C	0	150	
CH_3	Enabled	Channel_3	10 Hz	Thermocouple	°C	0	150	
CH_4	Enabled	Channel_4	10 Hz	Thermocouple	°C	0	1000	
CH_5	Enabled	Channel_5	10 Hz	Thermocouple	°C	0	50	
CH_6	Disabled	Channel_6	10 Hz	Calculated Gear	#	0	9	
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00	
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50	
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0	
ECU_1	Enabled	AEM_RPM	10 Hz	Engine speed sensor	rpm	0	20000	
ECU_2	Enabled	AEM_LOAD	10 Hz	Pressure sensor	bar ...	0.00	150.00	
ECU_3	Enabled	AEM_TPS	10 Hz	Percentage sensor	% .1	0.0	100.0	
ECU_4	Enabled	AEM_AIR_TEMP	10 Hz	Temperature sensor	°C	-30	60	
ECU_5	Enabled	AEM_WATER_TEMP	10 Hz	Temperature sensor	°C	-30	120	
ECU_6	Enabled	AEM_ADCR11	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_7	Enabled	AEM_ADCR13	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_8	Enabled	AEM_ADCR14	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_9	Enabled	AEM_ADCR17	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_10	Enabled	AEM_ADCR18	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_11	Enabled	AEM_ADCR15	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_12	Enabled	AEM_ADCR16	10 Hz	Voltmeter	V .1	0.0	20.0	
ECU_13	Enabled	AEM_BATTERY	10 Hz	Voltmeter	V .1	0.0	20.0	

Installation name	Logger type	Vehicle name	Available time	Total frequency
DEFAULT	M3LOG - Advanced	DEFAULT	1.02.13 (h.m.s)	271 (Hz)

It shows all channels set on the logger with the related characteristics:

- **Channel identifier:** shows channel label. “ECU\_X” are the ones received from the vehicle ECU.
- **Enabled/Disabled:** shows channel status (enabled/disabled). It can be modified with a double click on the cell except for RPM, speed and gear channel that are only modifiable through system configuration window.
- **Channel name:** names the channel.
- **Sampling frequency:** sets each channel sampling frequency. This last one influences the total available sampling time, highlighted by a box in the figure above, that diminishes increasing the sampling frequency because the memory fills up faster.
- **Sensor type:** allows to select the sensor installed on that channel selecting it from the drop down menu that appears clicking on that cell. On channels from CH\_1 to CH\_4 (for MyChron3 XG Log FR2000J, MyChron3 Log Bike) or CH\_5 (for MyChron3 Log Advanced, MyChron3 XG Log) it is possible to connect temperature or pressure sensors, potentiometers, Lambda probe and gyroscopes (except for MyChron3 Log Bike that has channel CH\_7 devoted to the gyroscope). To set the desired sensor select it from the available sensors list. Channel CH\_6 is the gear channel.
- **Measure unit:** allows to select the sensor unit of measure.
- **High/Low scale:** shows the range of values shown by the graph that will be created by Race Studio Analysis software after data download.
- **Param.1:** is the value of RPM or speed parameters set in system configuration window.

When all parameters have been set transmit the configuration to the logger.

### 6.3.1 – MyChron3 Visor and MyChron3 XG Log FR2000J channels

**MyChron3 Visor**, being just a dash, does not allow sensor installation on the different channels but only receives ECU signals.

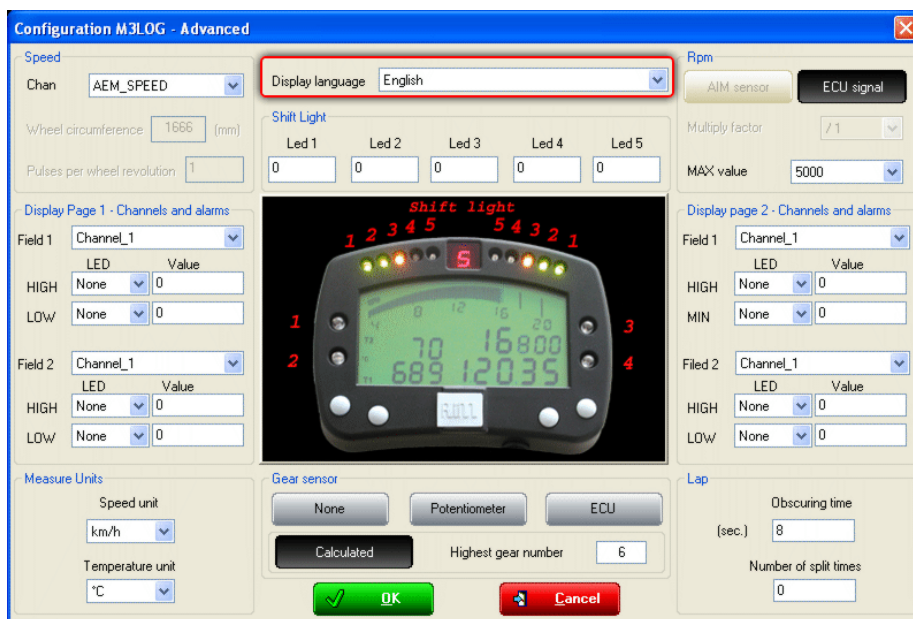
**MyChron3 XG Log FR2000J** channels are already set but it is possible to set additional temperature and pressure sensors, potentiometers, gyroscope and Lambda probe on channels from CH\_1 to CH\_4.

### 6.4 – Creating a custom sensor

The procedure to create a custom sensor is the same for all AIM loggers. Refer to chapter 12 for further information.

### 6.5 – System configuration

**MyChron3 Log/Visor/XGLog** has 14 fully configurable coloured led; the 2 on the left and on the right of the display are the four high/low alarm led of the analog channels (temperatures and pressures), while the other 10 led on top of the display are the Shift lights that warn the pilot to shift gear.



To set alarms, high/low threshold values and all configuration parameters it is necessary to complete the window shown here above.

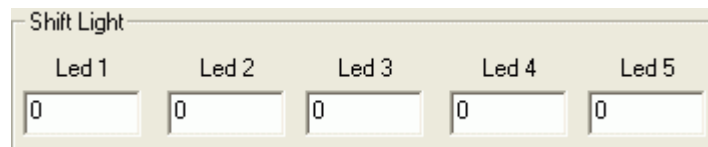
First of all select the display language red circled in the figure above.

### 6.5.1 – Speed box



- **Channel:** select the speed channel to be used as reference and that will be shown by the logger display, used for gear calculation (chapter 15), for some Race Studio Analysis computations etc. Available options are: speed coming from the speed sensor (“Speed\_1 in the above image), speed coming from the ECU and none.
- **Wheel circumference:** fill in the vehicle wheel circumference;
- **Number of pulses per wheel revolution:** fill in the number of pulses per wheel revolution (that corresponds to the number of magnets installed on the wheel).

### 6.5.2 – Shift Light box



Sets 10 led placed on top of MyChron3. Led colors: the first two on the left and on the right are green, the central two are orange and the last four are red. To set RPM threshold value fill in the cases. Led switches progressively on and when the engine reaches the RPM value set for Led 5 all led start blinking warning the pilot to shift gear. If a value is set on 0 the corresponding led is disabled.

### 6.5.3 – RPM box

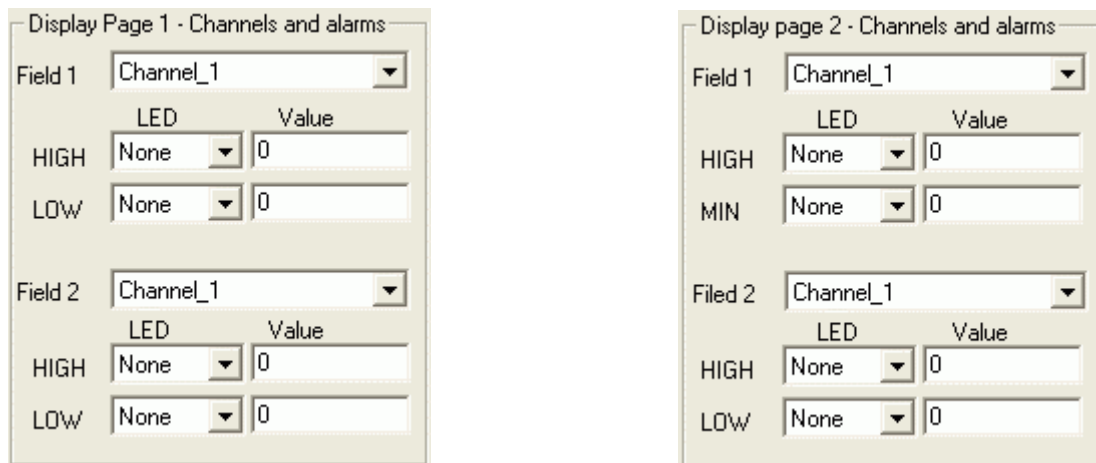


This box layout depends on the logger and on the settings defined by the user when creating a new configuration.

**MyChron3 XG Log e MyChron3 Log Bike** are the only loggers of this group that can work also without the connection with the ECU. So, setting ECU parameters of the new configuration on “none”, the button labelled AIM sensor is enabled – figure above on the left. Ensure that RPM sensor is correctly installed and connected and insert Multiply factor and RPM Max value.

All other loggers can work only if connected to the vehicle ECU, which means that their system configuration window always shows this box with the only ECU signal button enabled (figure above on the right). Fill in RPM max value.

### 6.5.4 – Display Pages 1/2 – Channels and alarms box

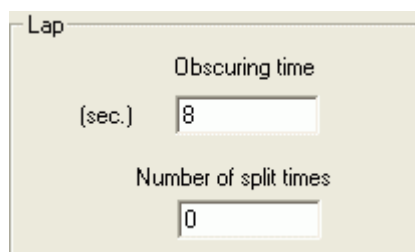


These boxes are connected to the field shown by the logger display. Each logger of this family shows two pages and each of them is configurable as follows:

- match each case labelled as field (1, 2, 3 e 4) with a channel
- match, if needed, a led to that channel max/min values and insert these values.

Available led for these function are the four logger lateral led. Each of them can be associated to each channel no matter its position and can work as minimum or maximum alarm.

### 6.5.5 – Lap box



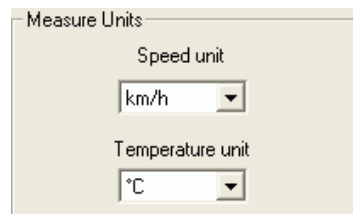
- **Obscuring time:** it's a time period during which the optical receiver installed on the vehicle, after having recorded a lap signal, is "blind": it does not record signals. This function is useful for split times management on tracks with more magnetic strips/optical transmitters: set obscuring time on a minimum value to sample split times; not to sample split times set obscuring time on a value lower than best lap time and higher then the time elapsed between last split and start finish line.
- **Number of split times:** is the number of segments the track is divided in and corresponds to the number of transmitters there installed.

### 6.5.6 – Gear sensor box



- **None:** not to see the engaged gear on the display.
- **Potentiometer** (except for MyChron3 Visor): there is a gear potentiometer (see – paragraph 14.3 for its calibration procedure).
- **ECU:** to sample gear signal from the ECU (assuming it can transmit it).
- **Calculated:** to calculate gears; fill in highest gear number. See chapter 15 for further information.

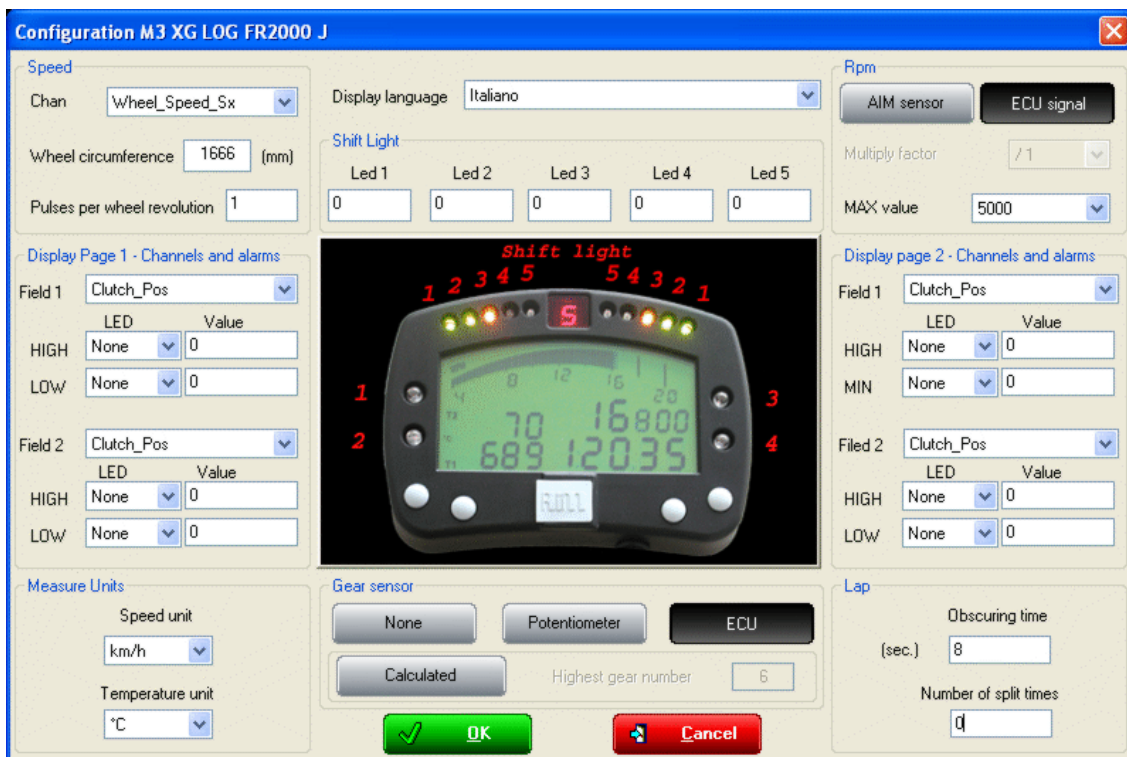
### 6.6.7 – Measure unit box



Choose the unit of measure for speeds (km/h or mph) and Temperatures (°C or °F).

### 6.5.8 – System configuration of MyChron3 XG Log FR2000J

In case of a **MyChron3 XG Log FR2000J**, configuration window – shown below – is partially set.



This window is to be completed following the same procedure explained for all other MyChron3 of this group.

## 6.6 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 13 for further information.

## 6.7 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, to say auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate the gear sensor, the mid zero potentiometer and the zero based potentiometer installed on the vehicle.

See chapter 14 for further information.

**Warning: if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.**

## 6.8 – Gear calculation

Refer to chapter 15 for further information.

## 6.9 – Online

Online function is very useful to check the logger proper working. Refer to chapter 18 for further information.

## Chapter 7 – How to configure MXL Strada/Pista/Pro/Pro05

To correctly configure **MXL Strada/Pista/Pro/Pro05** (from here onward **MXL**), use a PC and Race Studio 2 software. This logger can only be configured via software.

Before starting the configuration install **Race Studio 2** and the USB driver, as explained in chapter 2.

Run the program clicking on **Race Studio 2** icon: the window below appears.



In the title bar – white on a blue background in the figure – you can see the **Race Studio 2** version installed on the PC.

Immediately under there is the menu bar, shown in a more intuitive way on the left thanks to the graphic keys buttons: Go to Analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

From this window it is possible to perform all necessary operations to manage all AIM systems.

To enter configuration menu click on “AIM system manager” button. A panel showing all systems managed through **Race Studio 2** software appears: double click on “**MXL**” or select it and click on “✓Go to”.



Race Studio 2 system manager window appears.



## 7.1 – System manager window



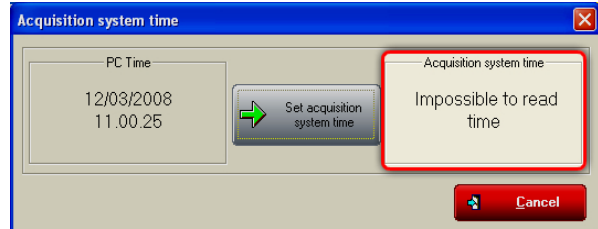
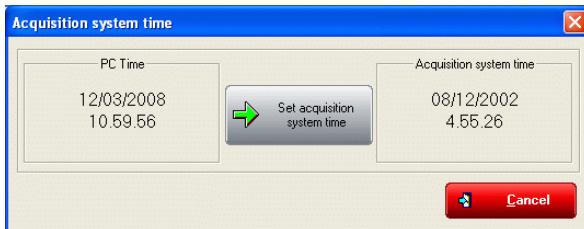
Using the keyboards and the layers (highlighted in the figure here above) it is possible to perform all necessary operations to manage AIM systems. The **top keyboard** of system manager window, shown here below, is made up of five buttons:



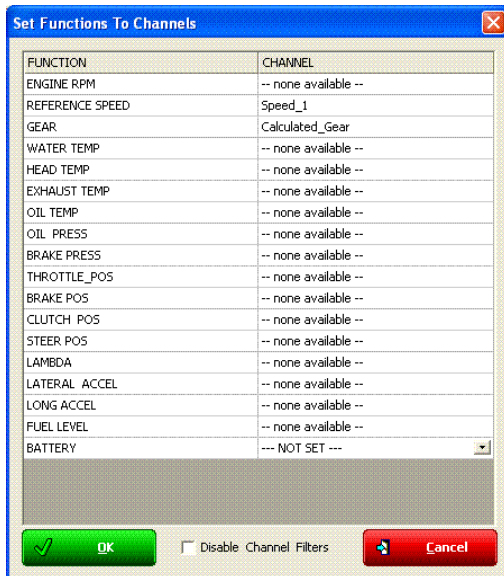
- **Transmit:** transmits a configuration to the logger and is active in any layer; needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger and is active only in “Select configuration” layer.
- **CAN-Net info:** identifies the CAN network connected to the PC, that means the logger and its eventual peripherals. Pressing it a waiting window appears and – once the connection established – “CAN-Net info” window shown here below appears. It shows all the CAN network components. In the example below the CAN network is made of an MXL Pista Master and four CAN expansions: DaVid, LCU-ONE, GPS and Memory Key.

N	Category of Logger	Type of Logger	Expansion Name	Logger ID	ID Date	Firmware ...	Firmware D...
1	MASTER	MXL PISTA	Master	12345	16/01/2008	14.86.23	19/12/2007
2	CAN EXPANSION	DaVid		47111881	18/01/2008	22.03	09/11/2007
3	CAN EXPANSION	LCU-ONE	LC	1111111	13/12/2007	25.09	19/11/2007
4	CAN EXPANSION	GPS		902499	14/01/2008	35.13	17/12/2007
5	CAN EXPANSION	MEMORY KEY		7613105	17/12/2007	37.05	18/12/2007

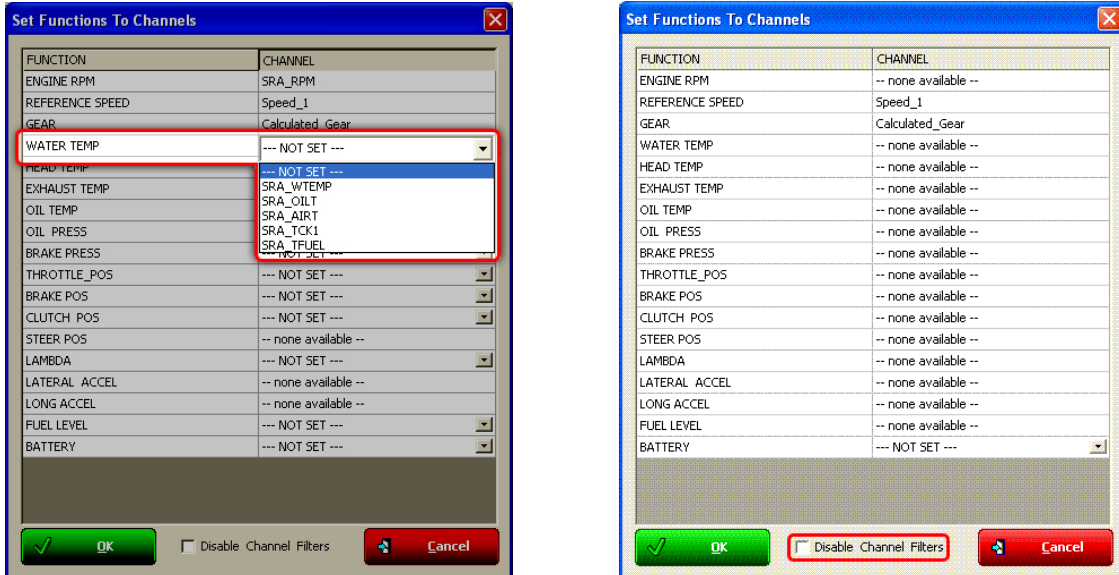
- Set acquisition system time:** makes the logger time matching the PC one. Pressing it “Acquisition system time” window – below on the left – appears with PC clock on the left and MXL one on the right. Pressing the central button, PC and MXL will have the same time. This operation does not modify data sampled by the logger nor influence its peripherals. In case the window on the right appears it means that PC-logger connection is wrong. Check it and try again.



- SmartyCam functions settings:** allows to set SmartyCam channels. Pressing it the related panel appears. With reference to the images here below, each function available options depends on the fact whether the all network is connected to the vehicle ECU or not. This means that if there is no ECU all functions not managed directly by SmartyCam are shown as “none available” and cannot be set while in case an ECU is available all function supported by that ECU are shown as “Not set” and can be set.



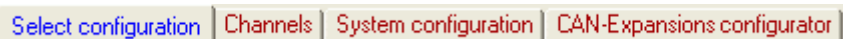
In case an ECU is available it is necessary to decide which channel to associate with each function. To set SmartyCam water temperature channel – for example – click the arrow right of the function and a drop down menu opens showing all available temperature channels. Select the one that will be shown on SmartyCam video and press OK. In case the channel is not shown it is possible to enable “Disable channel filters” checkbox and all available channels will be shown no matter if they are temperature channels or not.



**Current Configuration Table**, immediately under the keyboard and shown here below, shows the main information concerning the configuration user is working on.

Current configuration									
Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	MXL PISTA	None - None	DEFAULT	9.32.39 (h.m.s)	4.06.35 (h.m.s)	121 (Hz)	121 (Hz)	0 (Hz)	0

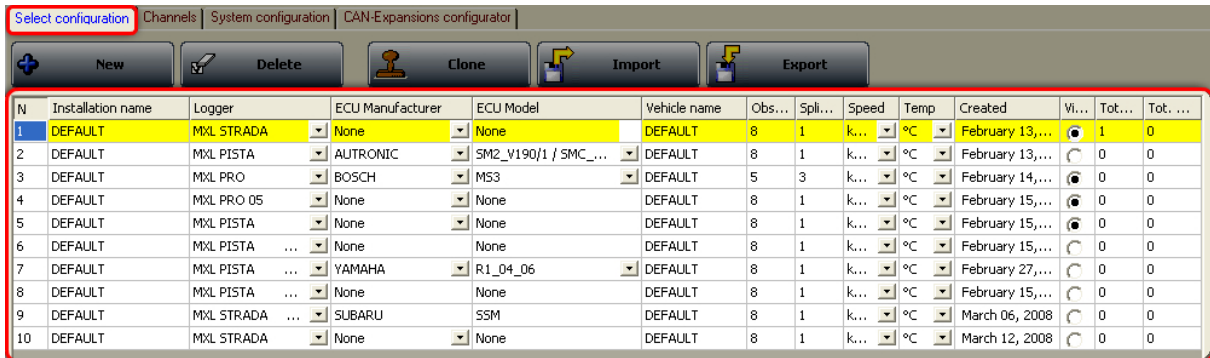
Again under this table are **four layers**:



- **Select configuration:** allows the user to select the configuration to work on; it is always active.
- **Channels:** allows to set MXL channels. It is active only if there are configurations in “Select configuration” layer.
- **System configuration:** allows to set or modify MXL configuration. It is active only if there are configurations in “Select configuration” layer.
- **CAN-expansions configurator:** allows to configure the expansions connected through the CAN bus to MXL, DaVid Slave video system included. It is active only if there are configurations in “Select configuration” layer; if not, it doesn’t even appear. Refer to chapter 16 for further information concerning their configuration. **Note:** if the connected expansion in a DaVid slave expansion refer to paragraph 8.6 (DaVid Master) for information concerning its configuration.

### 7.1.1 – Select configuration layer

“Select configuration” layer shown here below, is made as follows:



N	Installation name	Logger	ECU Manufacturer	ECU Model	Vehicle name	Obs...	Spli...	Speed	Temp	Created	Wi...	Tot...	Tot. ...
1	DEFAULT	MXL STRADA	None	None	DEFAULT	8	1	k...	°C	February 13,...	1	0	0
2	DEFAULT	MXL PISTA	AUTRONIC	SM2_V190/1 / SMC_...	DEFAULT	8	1	k...	°C	February 13,...	0	0	0
3	DEFAULT	MXL PRO	BOSCH	MS3	DEFAULT	5	3	k...	°C	February 14,...	0	0	0
4	DEFAULT	MXL PRO 05	None	None	DEFAULT	8	1	k...	°C	February 15,...	0	0	0
5	DEFAULT	MXL PISTA	None	None	DEFAULT	8	1	k...	°C	February 15,...	0	0	0
6	DEFAULT	MXL PISTA ...	None	None	DEFAULT	8	1	k...	°C	February 15,...	0	0	0
7	DEFAULT	MXL PISTA ...	YAMAHA	R1_04_06	DEFAULT	8	1	k...	°C	February 27,...	0	0	0
8	DEFAULT	MXL PISTA ...	None	None	DEFAULT	8	1	k...	°C	February 15,...	0	0	0
9	DEFAULT	MXL STRADA ...	SUBARU	SSM	DEFAULT	8	1	k...	°C	March 06, 2008	0	0	0
10	DEFAULT	MXL STRADA	None	None	DEFAULT	8	1	k...	°C	March 12, 2008	0	0	0

On top is a keyboard made up of five buttons.

- **New:** creates a new configuration;
- **Delete:** deletes a configuration;
- **Clone:** clones a configuration;
- **Import:** imports a new configuration from a file;
- **Export:** exports a configuration to a file;

Central is the available configurations database. To work on one of them click on any cell of its row and the entire row is selected (highlighted in yellow).

In case of first configuration central table shows up empty.

## 7.2 – Creating a new configuration

Pressing “New” button in select configuration layer this window appears:



Some parameters need to be set:

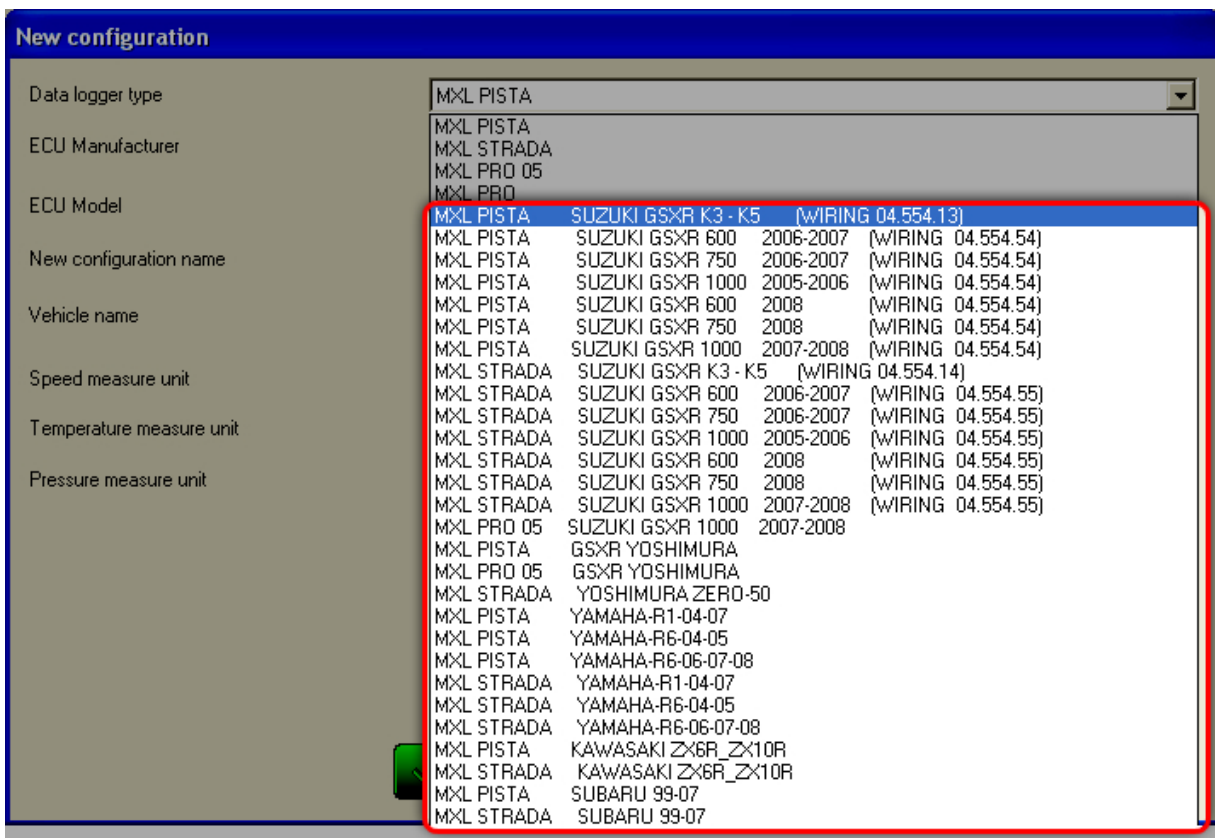
- **Data logger type:** select the logger to be configured.
- **ECU Manufacturer:** select the Manufacturer of the ECU installed on the vehicle if supported or none.
- **ECU Model:** select the ECU model.
- **New configuration name:** fill in the new configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Speeds unit of measure:** choose between km/h and mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (“Cancel” to quit without saving).  
The system comes back to system manager window.

### 7.2.1 – MXL Strada/Pista and Pro05 Plug&Play configurations

**MXL Strada/Pista/Pro05 Plug&Play** kits for Car or Bike installations include, beside the logger, all what is needed for an easy installation on the vehicle (wiring, bracket, screws, washers, user manuals etc..). Currently the most common models/brands are available. All information are available on AIM website at [www.aimshop.com](http://www.aimshop.com) clicking “Special Applications” button in the home page.

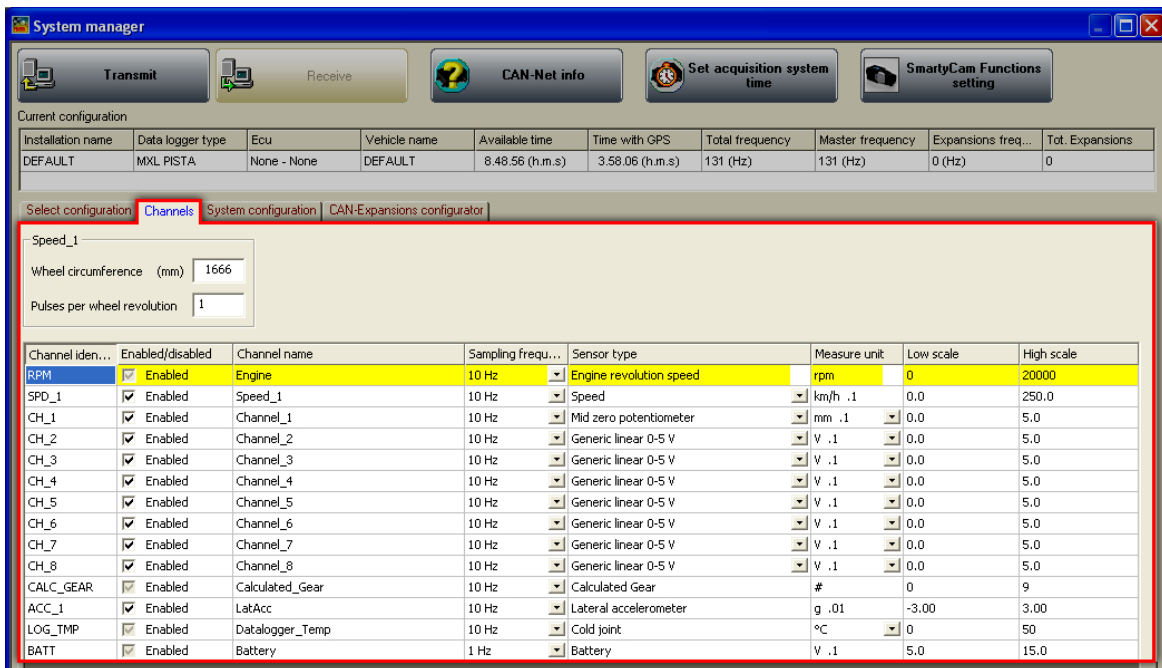
Once correctly installed the kit (see the kits user manuals for further information) just switch the vehicle on. Should configuration problem occur select the correct configuration in “New configuration” window shown here below. The red box highlights Plug&Play configurations currently available.



**Warning: all parameters set in Plug&Play configurations have been tested to work properly with vehicles completely corresponding to the stock ones sold by the manufacturers. Refer to the kits user manuals for further information.**

## 7.3 – Channels

Enable “Channels” layer.

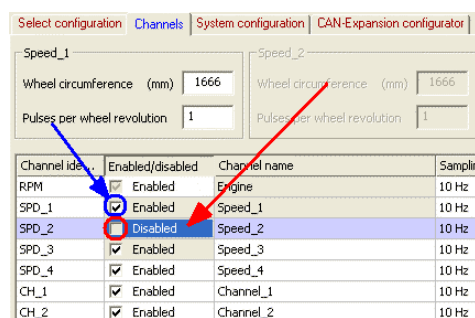


This layer sets all channels sampled by the logger and its layout depends on the logger version.

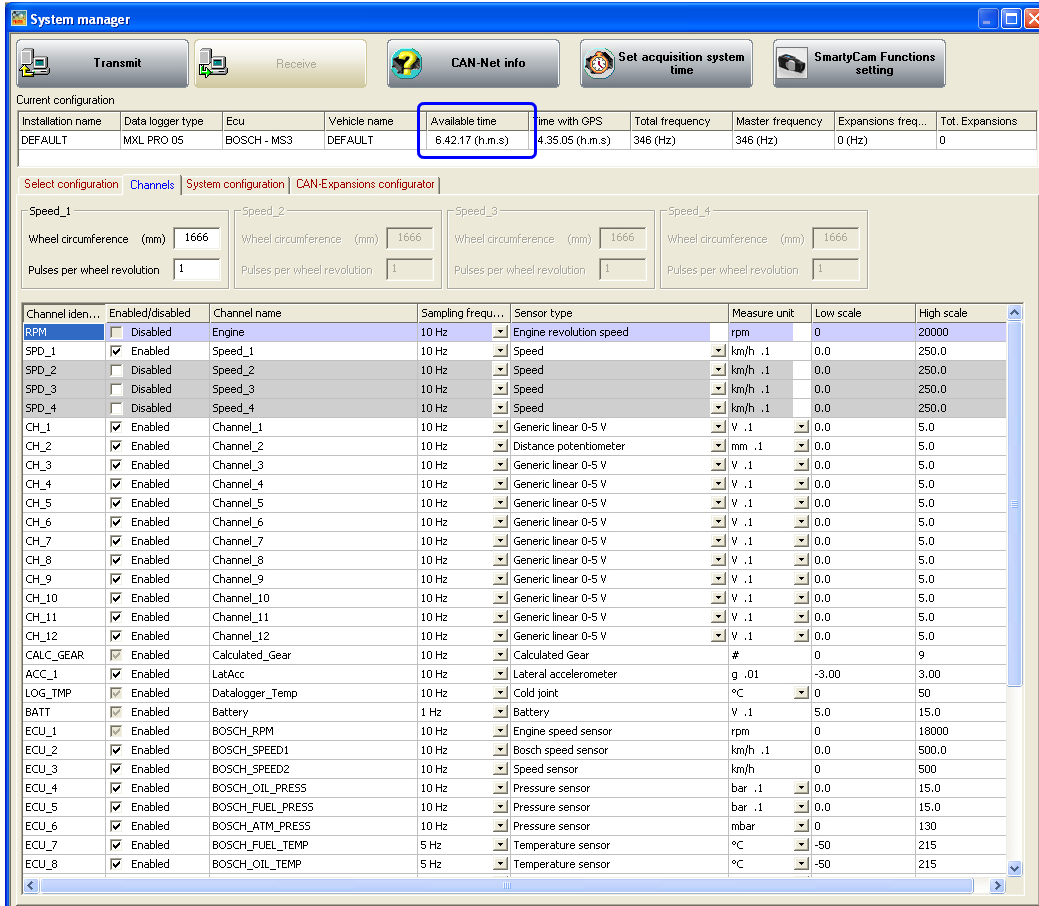
### 7.3.1 – Speed panels

On top of the layer you see the panels concerning speeds (1 for **MXL Strada** and **Pista** and 4 for **MXL Pro** and **Pro05**). They are labelled like speed channels in the table below. Changing the channel name in the tables the panel label is modified live.

The panels are enabled through the related checkbox as shown in the figure below. Fill in wheel circumference and number of pulses per wheel revolution (corresponding to the number of magnets installed on the vehicle wheel). Enable and set the speeds to be used and disable the ones not to be used.



### 7.3.2 – Channels table



Channel identifier	Enabled/disabled	Channel name	Sampling frequency	Sensor type	Measure unit	Low scale	High scale
RPM	<input type="checkbox"/> Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input type="checkbox"/> Disabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Distance potentiometer	mm .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CALC_GEAR	<input checked="" type="checkbox"/> Enabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	LatAcc	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0
ECU_1	<input checked="" type="checkbox"/> Enabled	BOSCH_RPM	10 Hz	Engine speed sensor	rpm	0	18000
ECU_2	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED1	10 Hz	Bosch speed sensor	km/h .1	0.0	500.0
ECU_3	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED2	10 Hz	Speed sensor	km/h	0	500
ECU_4	<input checked="" type="checkbox"/> Enabled	BOSCH_OIL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0
ECU_5	<input checked="" type="checkbox"/> Enabled	BOSCH_FUEL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0
ECU_6	<input checked="" type="checkbox"/> Enabled	BOSCH_ATIM_PRESS	10 Hz	Pressure sensor	mbar	0	130
ECU_7	<input checked="" type="checkbox"/> Enabled	BOSCH_FUEL_TEMP	5 Hz	Temperature sensor	°C	-50	215
ECU_8	<input checked="" type="checkbox"/> Enabled	BOSCH_OIL_TEMP	5 Hz	Temperature sensor	°C	-50	215

This table shows all logger channels with the related characteristics:

- **Channel identifier:** shows the channel label. “ECU\_X” channels are the ones received from the vehicle ECU.
- **Enabled/disabled:** shows channel status (enabled or disabled). It can be modified double clicking on the cell except for RPM, Speed and Gear that has to be modified through “System Configuration” layer.
- **Channel name:** names the channel.
- **Sampling Frequency:** sets each channel sampling frequency. This last one influences the total available time, highlighted in the figure above, that diminishes growing sampling frequency because the memory fills up faster.
- **Sensor type:** shows the type of sensor installed on that channel; it is selected through the drop down menu that appears clicking on the cell. See the following page for further information.
- **Measure unit:** shows the selected unit of measure for each channel; it is possible to change it double clicking on the cell.
- **High/low scale:** shows high/low scale values of the sensor and can be modified double clicking on the cell.

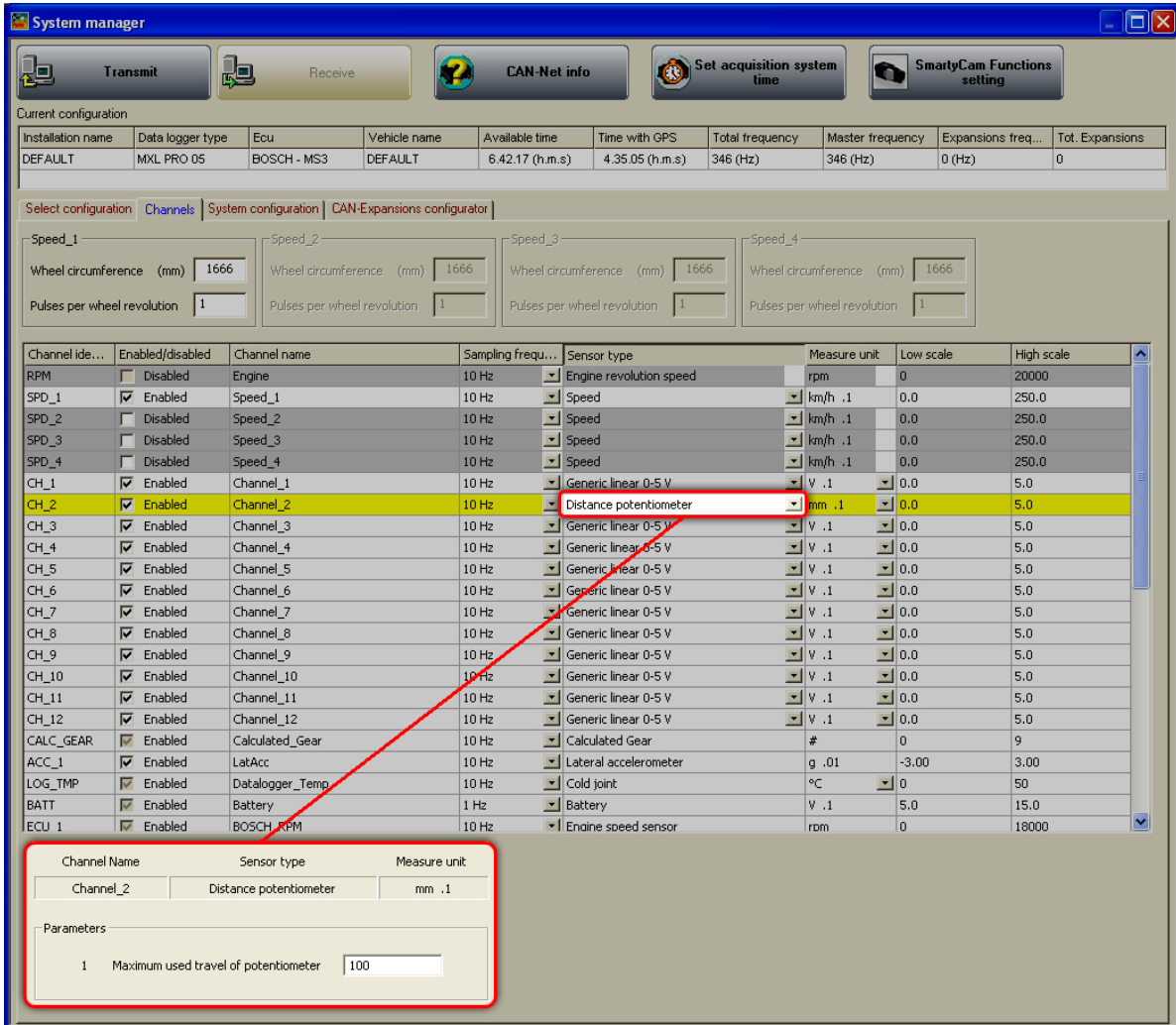


This table shows which sensors can be installed on each channel of MXL.

	Temperatures	Pressures	Potentiometers	Lambda Probe	Gyroscope	Accelerometer
<b>MXL Strada/MXL Pista</b>						
Ch_1	X	X	X	X		
Ch_2	X	X	X	X		
Ch_3	X	X	X	X		
Ch_4	X	X	X	X	X	X
Ch_5	X	X	X	X	X	X
Ch_6	X	X	X	X	X	X
Ch_7	X	X	X	X	X	X
Ch_8* <sup>4</sup>	X	X	X	X	X	X
<b>MXL Pro</b>						
Ch_1	X	X	X	X	X	X
Ch_2	X	X	X	X	X	X
Ch_3	X	X	X	X	X	X
Ch_4	X	X	X	X	X	X
Ch_5	X	X	X	X	X	X
Ch_6	X	X	X	X	X	X
Ch_7	X	X	X	X	X	X
Ch_8 <sup>4</sup>	X	X	X	X	X	X
<b>MXL PRO05</b>						
Ch_1	X	X	X	X		
Ch_2	X	X	X	X		
Ch_3	X	X	X	X		
Ch_4	X	X	X	X		
Ch_5	X	X	X	X		
Ch_6	X	X	X	X		
Ch_7	X	X	X	X	X	X
Ch_8	X	X	X	X	X	X
Ch_9	X	X	X	X	X	X
Ch_10	X	X	X	X	X	X
Ch_11	X	X	X	X	X	X
Ch_12 <sup>4</sup>	X	X	X	X		

<sup>4</sup> Channels CH\_8 (MXL Strada/Pista/Pro) and CH\_12 (Pro05) are gear channels. If system configuration window (paragraph 7.5) sets them on "Potentiometer CH\_8" (MXL Strada/ Pista/Pro), "Potentiometer CH\_12" (Pro05) or on "Calculated+Neutral Signal" channel CH\_8 or CH\_12 sets on calculated gear and it is only possible to set channel name, sampling frequency, high and low scale. If not these channels work as shown in the table.

Setting some sensor on some channels that support them a configuration panel appears (bottom left of Channels layer). The figure below shows distance potentiometer configuration panel.



The screenshot shows the 'System manager' window with the 'Channels' tab selected. A table lists various channels, with 'Channel\_2' highlighted in yellow. A red box highlights the 'Distance potentiometer' sensor type for this channel. A red arrow points from this sensor type to a configuration dialog box at the bottom left.

Channel ide...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input type="checkbox"/> Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input type="checkbox"/> Disabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Distance potentiometer	mm .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CALC_GEAR	<input checked="" type="checkbox"/> Enabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	LatAcc	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0
ECU 1	<input checked="" type="checkbox"/> Enabled	BOSCH RPM	10 Hz	Engine speed sensor	rpm	0	18000

Channel Name	Sensor type	Measure unit
Channel_2	Distance potentiometer	mm .1

Parameters

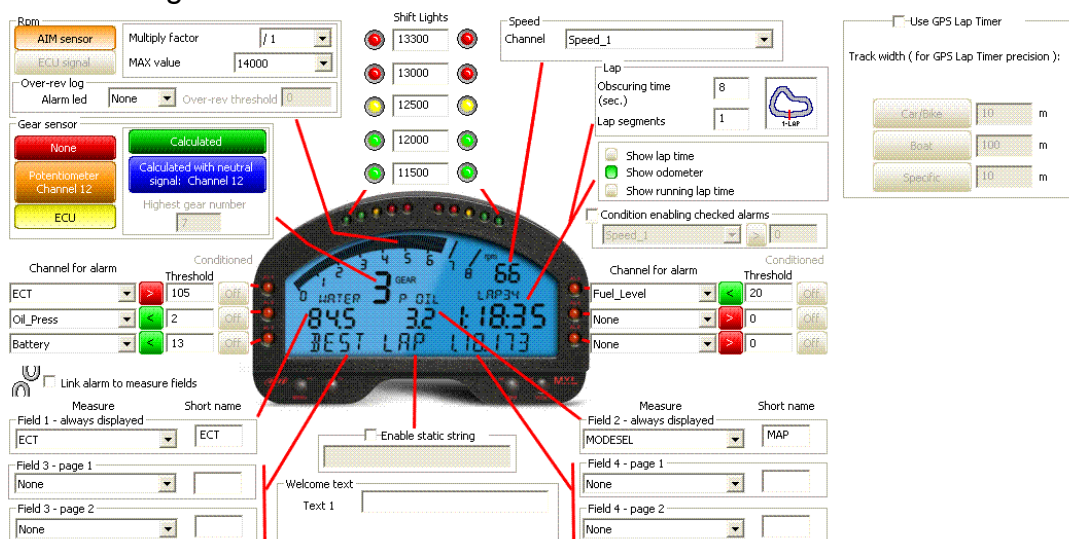
1 Maximum used travel of potentiometer

## 7.4 – Creating a custom sensor

The procedure to create a custom sensor is the same for all AIM loggers. Refer to chapter 12 for further information.

## 7.5 – System configuration

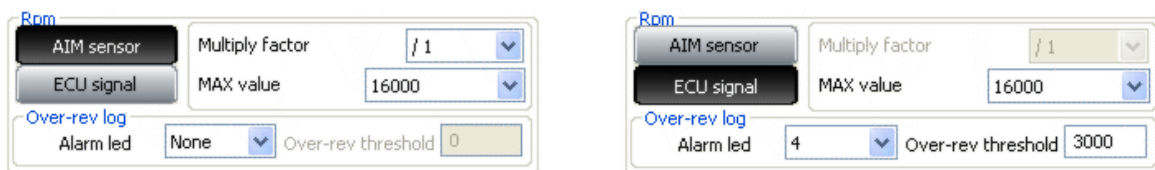
**MXL** has 16 fully configurable coloured led; the 3 on the left and on the right of the display represent the 6 max or min alarms of the analog channels (temperatures and pressures), while the other 10 led on top of the display are the Shift Lights that warn the pilot to shift gear.



To set the alarms, max and min threshold values and all parameters it is necessary to fill in the window above.

**Note:** in case of Plug&Play kit this window is already set.

### 7.5.1 – RPM box



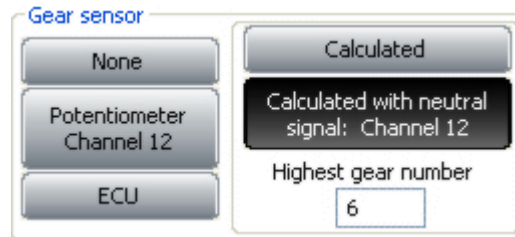
Select **“AIM Sensor”** to sample this value from an RPM sensor installed on the vehicle; fill in multiply factor and RPM max value. RPM row in channel table (see paragraph 7.3) is enabled.

Select **“ECU sensor”** and set RPM max value to sample this value from the ECU, assuming it can transmit it.

It is also possible to connect RPM max value to one of the 6 alarm led (in the figure above on the right it has been linked to led 4) so that it switches on when the engine reaches a fixed RPM value. The led does not switch off until data download is made. In this situation, the channel for alarm corresponding to that led is disabled. It is suggested to set over-rev threshold on a value corresponding to the ECU limiter<sup>5</sup>.

<sup>5</sup> This setting can be very useful to detect over-revs situation without opening Race Studio Analysis.

### 7.5.2 – Gear sensor box



**MXL** can sample the engaged gear from a gear sensor, from the vehicle ECU or can calculate it with an algorithm based on RPM and speed. Available options are:

- **“None”**: there is no gear sensor on the vehicle (or not to see the engaged gear). This option is disabled on the display.
- **“Potentiometer Channel 8/12”**: there is a gear potentiometer installed on channel 8/12. The corresponding row in channel table (see paragraph 7.3) is set on Calculated Gear.
- **“ECU”**: to sample this information from the vehicle ECU (assuming it can transmit it).
- **“Calculated”**: to calculate the engaged gear with an algorithm based on RPM and speed; fill in “Highest gear number” case. See chapter 15 for further information.
- **“Calculated with neutral signal: Channel 8/12”**: there is a neutral sensor to be used to see neutral gear and to calculate gears. “Highest gear number” case enables: fill it in. See chapter 15 for further information.

**Note:** gear channel is always the last one of the logger. This means that it’s Channel 8 for **MXL Strada, Pista** and **Pro** (having 8 channels) and channel 12 for **MXL Pro05** (having 12 channels).

### 7.5.3 – Shift light box

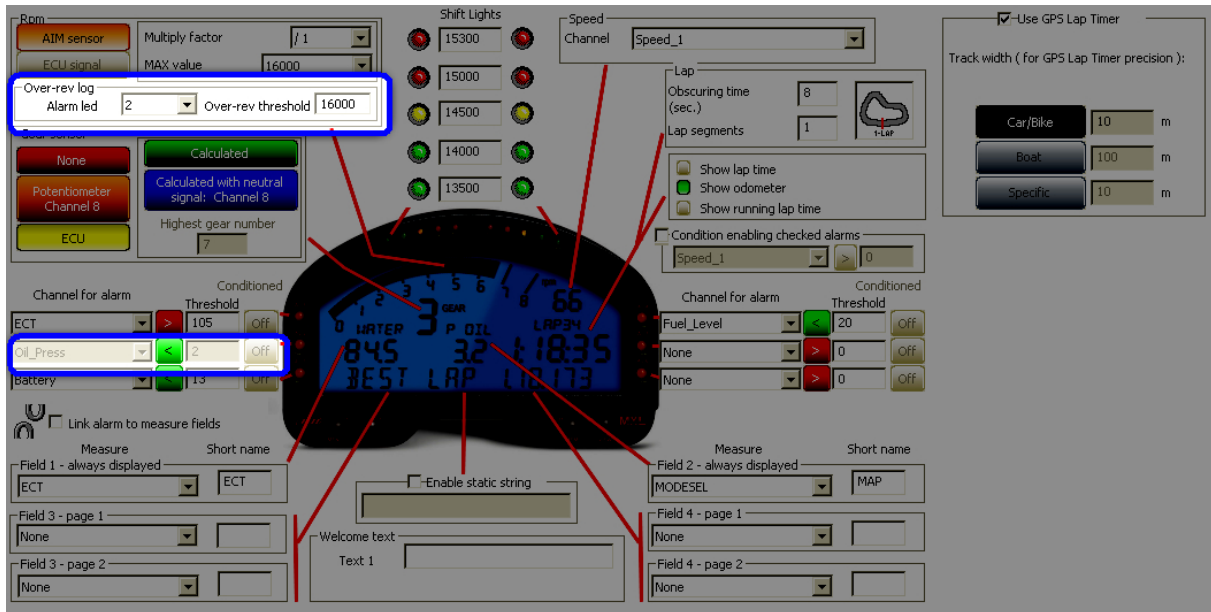


It manages the 10 led placed on top of **MXL**. Led colours: the first two on the left and on the right are green, the central two are orange and the last two are red. To set RPM threshold values fill in the cases. The led switch progressively on and when the engine reaches RPM values set for the top case all led start blinking, warning the pilot to shift gear.

If one case is set on “0” the corresponding led is disabled.

### 7.5.4 – Channel for alarm and measure boxes

Channel for alarm boxes are linked to the 6 alarm led of MXL.

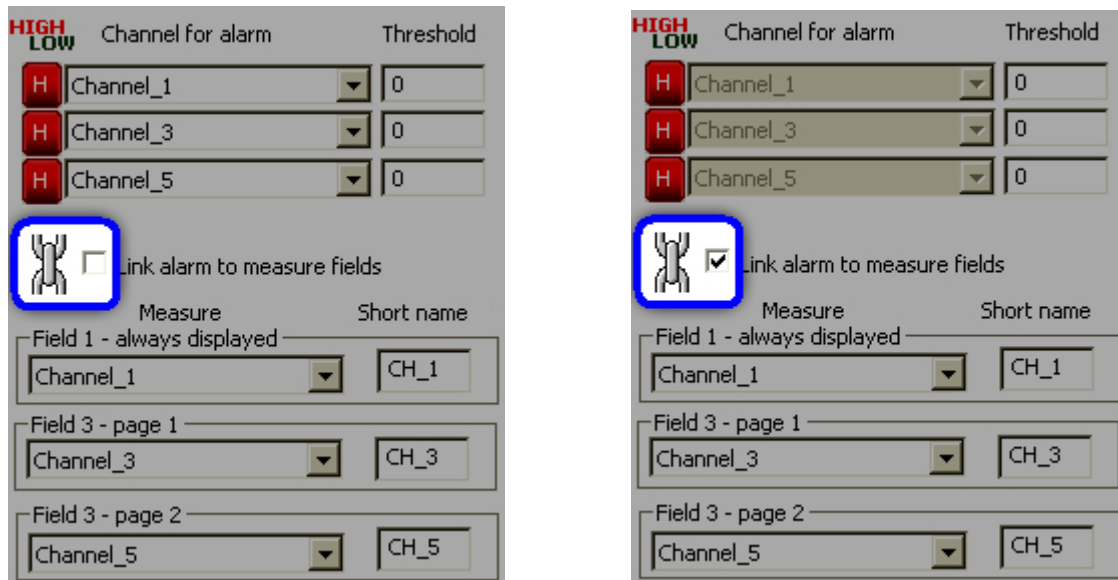


- Set each channel as Max (“>”) or Min (“<”) alarm.
- Fill in the threshold value.
- See paragraph 7.5.8 for further information concerning “status” (grey) button right of “threshold” cases, disabled in the figure above.

**Note:** setting “Over-rev log/alarm led” in RPM box, the channel linked to that channel is completely disabled as shown above.

Channels for alarm cases are linked to the field shown by MXL display. The first on the left and on the right are always shown. The other four channels can be shown two by two on the display static string with the name set in “Short name” case or as “CH\_X”.

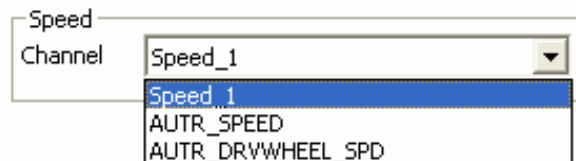
Select the channel to show and fill in its short name.



“Link alarm to measure field” option (enabled in the figure on the right) allows to link the 6 alarm led to the 6 shown alarms.

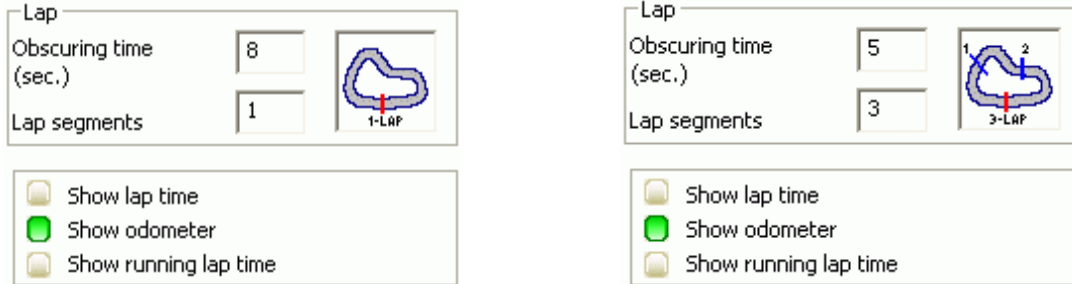
In this case channel for alarm cases disables and it is only possible to set threshold value and “>”/“<” (except if over-rev alarm led has been set as explained before).

### 7.5.5 – Speed box



It is possible to select the reference speed, that will be used for gear calculation and for some Race Studio Analysis computations. Available options are logger speed(s) (1 speed for **MXL Strada/Pista** and up to 4 speeds for **MXL Pro/Pro05**) and ECU speed(s). In the above figure the logger is connected to an Autronic ECU that transmits two speed channels.

### 7.5.6 – Lap box



**Obscuring time:** is a time period during which the optical receiver installed on the vehicle, after having recorded a lap signal, is “blind”: it does not record signals. This function is useful to manage split times on tracks where more optical receivers are installed: set obscuring time on a low value (min accepted value is 3 seconds) to record splits and set it on a value lower than best lap time and higher than the time elapsed between last split and start/finish line (max accepted value is 255 seconds) not to record splits.

**Lap segments:** is the number of segment the track is divided in and corresponds to the number of transmitters there installed.

**Show lap time:** MXL display shows lap time in the related field.

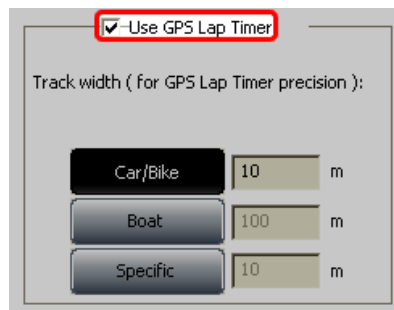
**Show odometer:** MXL display shows odometer in the related field.

**Show running lap time:** MXL display shows running lap time from last lap signal in the related field. The value resets when the logger detects a lap signal.

**Notes:**

- Setting “Show odometer”, the system switches automatically on “Show lap time” when detects a lap signal.
- The logger stores the visualization set.
- Refer to **MXL** user manual for any further information concerning the fields shown by the logger display.

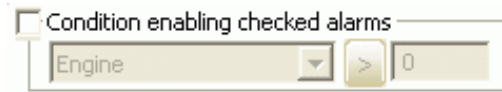
### 7.5.7 – Use GPS Lap timer box



It allows to use GPS lap timer in spite of the track beacon equipment. It is necessary to enable the corresponding checkbox and set the track width. Available options are:

- Car/Bike and Boat whose measures are set by default and
- specific that allows to set a specific track width.

### 7.5.8 – Condition enabling checked alarms box



This box – disabled by default – allows, if enabled, to condition the alarm led to an additional condition that – once set – becomes discriminating. It is very useful to avoid “false alarms”, as explained in the following pages.

**Warning: to set the condition that enables checked alarms it is necessary to have previously set channels for alarm.**

To set channels for alarms follow this procedure:

1. set – selecting from the drop down menu - the channels for alarm to be shown;
2. fill in its threshold value;
3. set the alarm limit (“>”/“<”);
4. enable “Condition enabling selected alarms” case (this operation enables “status” button but shows them all red and set on “Off”);
5. select the channel to use as conditioning one from the drop down menu;
6. fill in its threshold value;
7. set its alarm limit (“>”/“<”);
8. select the alarms to condition setting the related button on “On” (green).
9. this setting implies that the led of the conditioned alarms switches on only if two conditions occur contemporarily: their threshold value is overcome and, at the same time, the threshold value of the conditioning channel is overcome.

The images in the following pages show this procedure.



**Set the channel for alarm to show**  
**Fill in its threshold value**  
**Set alarm limit (">" / "<")**

The screenshot shows the 'Channel for alarm' table with the following data:

Channel for alarm	Threshold	Conditioned
ECT	105	Off
Oil_Press	2	Off
Battery	13	Off

Other visible settings include: Speed Channel: Speed\_1; Over-rev log: Alarm led: None; Over-rev threshold: 0; Gear sensor: Calculated; Potentiometer Channel 8; Highest gear number: 7; Lap: Obscuring time: 8; Lap segments: 1; Show lap time: checked; Show odometer: checked; Show running lap time: checked; Condition enabling checked alarms: Speed\_1 > 0.

**Enable "Condition enabling checked alarms" checkbox.**  
**Select the channel to use as condition.**  
**It enables "status" buttons but sets them all on "Off".**

The screenshot shows the 'Condition enabling checked alarms' checkbox checked. The 'Channel for alarm' table is updated as follows:

Channel for alarm	Threshold	Conditioned
ECT	105	Off
Oil_Press	2	Off
Battery	13	Off

The 'Condition enabling checked alarms' dropdown is set to Speed\_1 > 0.

**Fill in a threshold value for the conditioning channel.**  
**Set its alarm limit (">" / "<").**

The screenshot shows the 'Condition enabling checked alarms' dropdown set to Speed\_1 > 2000. The 'Channel for alarm' table remains the same as in the previous screenshot.

Select which alarms between these set to submit to that condition setting the related "Status" button on "On" (green).

Oil pressure and battery channel have been conditioned to RPM (Engine) channel. The related led will switch on only if:

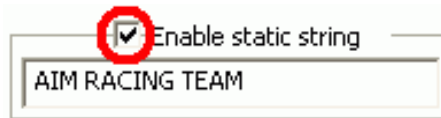
- oil pressure <2 Bar + RPM >2000
- or
- Battery voltage <13Volts + RPM >2000

Water temperature (ECT) and fuel level channels have not been conditioned. The related alarm led will switch on when:

- water temperature >105°C
- fuel level <20% of fuel tank capacity

regardless RPM (Engine) value.

### 7.5.9 – Enable static string and welcome message boxes



The static string is a message that is shown on bottom of MXL display. To enable it enable the related checkbox and fill in the text of the message to show.

When the static string is disabled the corresponding part of the display shows two by two the fields connected to field 3 and 4 of page 1 and 2 of the display.

**Note:** if gear sensor box is set on “Calculated”, **MXL** has to calculate the engaged gear (paragraph 5.7). During this procedure the static string is excluded and the display shows “Running Gear Cal” on its bottom part.



The welcome message is a text shown for some seconds at start up on the bottom of the logger display. To show it fill in the text in the case shown here above.

## 7.6 – Configuring the CAN expansions

**MXL**, like other AIM loggers, can be connected to numerous expansions that communicate with it through the CAN bus. See chapter 16 For further information.

**Note:** in case the expansion is a DaVid Slave refer to paragraph 8.6 (**DaVid** master) to configure it.

## 7.7 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 13 for further information.

## 7.8 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, to say auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate the gear sensor, the mid zero potentiometer and the zero based potentiometer installed on the vehicle. See chapter 14 for further information.

**Warning:** if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.

## 7.9 – Gear calculation

See chapter 15 for further information.

## 7.10 – Online

Online function is very useful to check the logger proper working. Refer chapter 18 for further information.

## Chapter 8 – How to configure DaVid

To configure **DaVid**, use a PC and Race Studio 2 software. This logger can only be configured via software.

Before starting the configuration, install **Race Studio 2** and the USB driver as explained in chapter 2.

Run the software clicking on **Race Studio 2** icon and the window here below appears.



In the title bar – white with blue background in the figure – you can see the **Race Studio 2** version installed on the PC.

Immediately under there is the menu bar, shown in a more intuitive way on the left thanks to the graphic buttons: Go to Analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

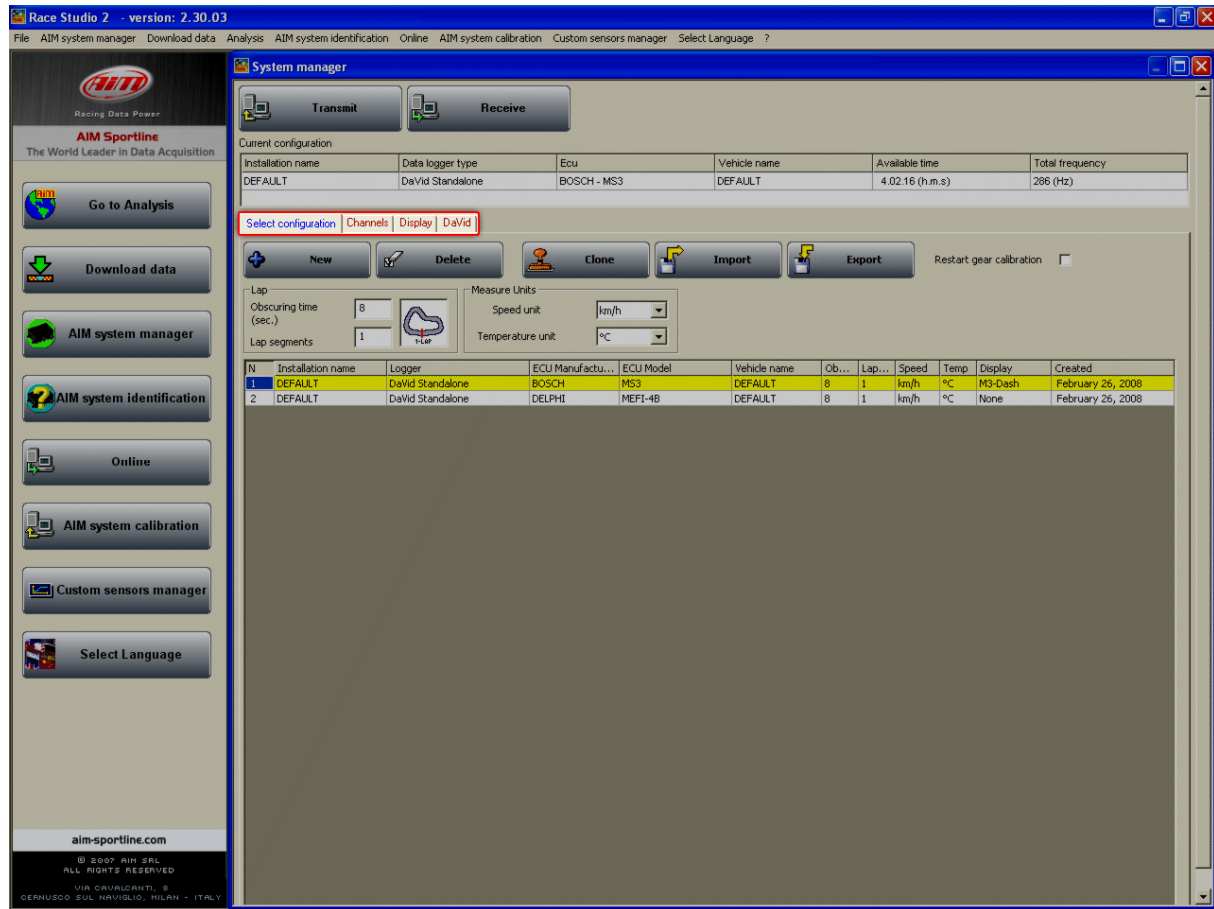
From this window it is possible to perform all operations necessary to manage all AIM systems.

To enter configuration menu press “AIM system manager” button; a panel showing all systems managed through **Race Studio 2** software appears: double click on “MXL” or select it and click on “✓Go to”.



Race Studio 2 system manager window appears.

## 8.1 – System manager window



Using the keyboards and the layers (red circled in the figure above) it is possible to perform all operations needed to manage an AIM system.

The top keyboard, shown below, is made up of two buttons:



- **Transmit:** transmits a configuration to the logger and is active with any layer; it needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger and is active only in “Select Configuration” layer.

Current configuration table, immediately under the keyboard and shown here below, shows the main information concerning the configuration user is working on.

Installation name	Data logger type	Ecu	Vehicle name	Available time	Total frequency
DEFAULT	DaVid Standalone	AUTRONIC - SM2_V190M / SM...	DEFAULT	4.59.57 (h.m.s)	231 (Hz)

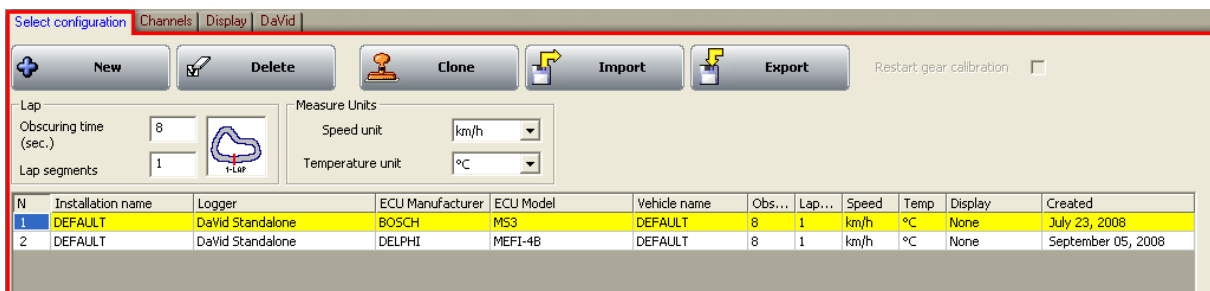
Again, under this table there are **four layers**:



- **Select configuration:** allows to select the configuration to work on; it is always active.
- **Channels:** allows to set DaVid channels. It is active only if there are configurations in “Select Configuration” layer.
- **Display:** allows to set the configuration of DaVid display. It is active only if there are configurations in “Select Configuration” layer. Refer to the related chapter for further information concerning the displays configuration.
- **DaVid:** allows to configure DaVid video. It is active only if there are configurations in “Select Configuration” layer.

### 8.1.1 – Select configuration layer

“Select configuration” layer is shown here below:



**On top** is a keyboard whose buttons are used to:

- **New:** creates a new configuration;
- **Delete:** deletes a configuration;
- **Clone:** clones a configuration;
- **Import:** imports a new configuration from a file.
- **Export:** exports a configuration to a file.

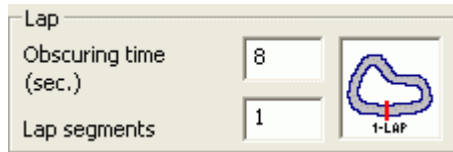
**Beside the keyboard** is a checkbox:

- **Restart gear calibration:** it allows to start/re-start DaVid gear calibration; to do so enable this checkbox, transmit the configuration to the logger and follow the procedure described at chapter 15.



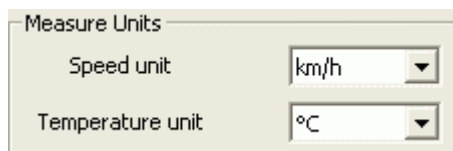
**Under the keyboard** there are two panels:

**Lap box:**



- **Obscuring time:** is a time period during which the optical receiver installed on the vehicle, after having recorded a lap signal, is “blind”: it does not record signals. This function is useful to manage split times on tracks where more optical receivers are installed: set obscuring time on a low value (min accepted value is 3 seconds) to record splits and set it on a value lower than best lap time and higher than the time elapsed between last split and start/finish line (max accepted value is 255 seconds) not to record splits.
- **Lap segments:** is the number of segments the track is divided into and corresponds to the number of transmitters installed there .

**Measure units box:**



- **Speed units:** allows to modify the unit of measure to be used for speed (mph or km/h) in the selected configuration (highlighted in yellow).
- **Temperature unit:** allows to modify the temperatures unit of measures (°C or °F) in the selected configuration (highlighted in yellow).

**Central in the layer** is configurations database. To work on one of them click on any cell of its row and the entire row is selected (highlighted in yellow).

In case of first configuration the central table shows up empty.

## 8.2 – Creating a new configuration

Pressing “New” in “Select configuration” layer of “System manager” window this window appears:



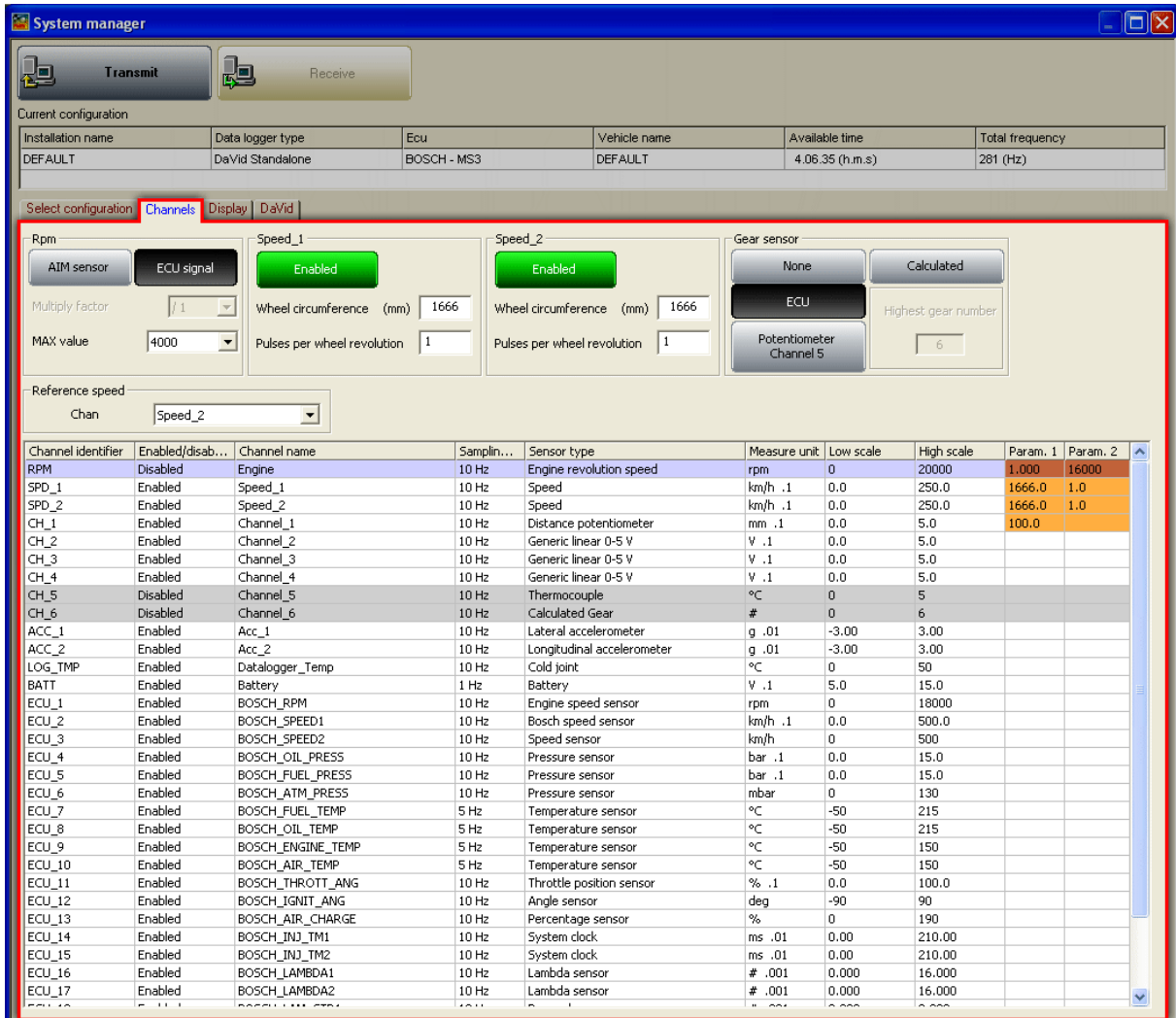
Some parameters need to be set:

- **ECU Manufacturer:** select the manufacturer of the ECU installed on the vehicle or none.
- **ECU Model:** select the ECU model.
- **New configuration name:** fill in the configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Display type:** select the type of display installed and connected to DaVid.
- **Speeds measure unit:** choose between km/h and mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (or “Cancel” to quit without saving).  
The system comes back to “System Manager” window.

## 8.3 – Channels

Activate “Channels” layer.



The screenshot shows the 'System manager' window with the 'Channels' tab selected. The 'Current configuration' table is as follows:

Installation name	Data logger type	Ecu	Vehicle name	Available time	Total frequency
DEFAULT	DaVid Standalone	BOSCH - MS3	DEFAULT	4.06.35 (h.m.s)	281 (Hz)

The 'Channels' configuration panel includes:

- Rpm:** AIM sensor (disabled), ECU signal (selected), Multiply factor (/1), MAX value (4000).
- Speed\_1:** Enabled, Wheel circumference (mm) 1666, Pulses per wheel revolution 1.
- Speed\_2:** Enabled, Wheel circumference (mm) 1666, Pulses per wheel revolution 1.
- Gear sensor:** None (disabled), Calculated (disabled), ECU (selected), Potentiometer Channel 5 (disabled), Highest gear number (6).
- Reference speed:** Chan: Speed\_2.

The channel configuration table is as follows:

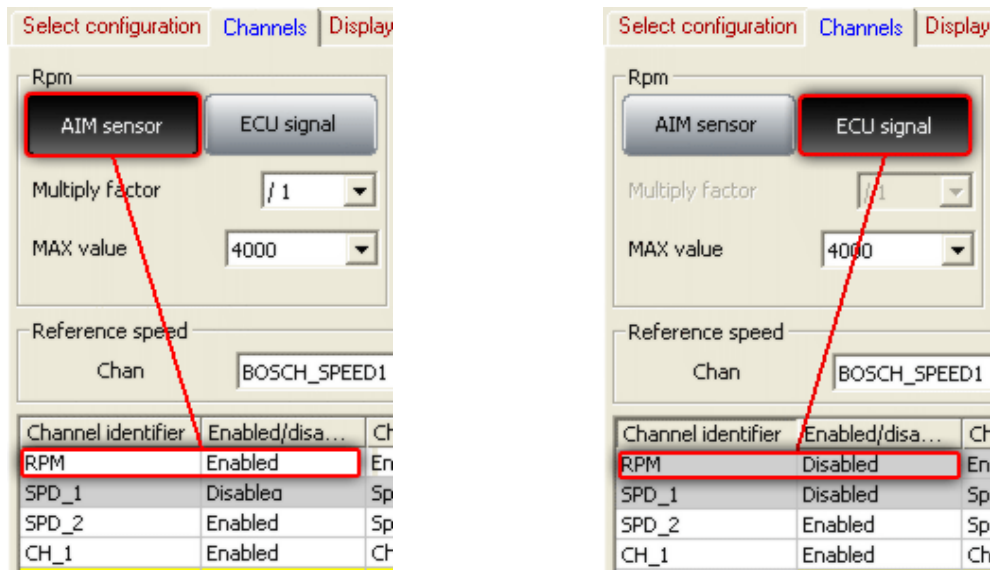
Channel identifier	Enabled/disab...	Channel name	Sampl...	Sensor type	Measure unit	Low scale	High scale	Param. 1	Param. 2
RPM	Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000	1,000	16000
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
SPD_2	Enabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
CH_1	Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0	100.0	
CH_2	Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_3	Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_4	Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_5	Disabled	Channel_5	10 Hz	Thermocouple	°C	0	5		
CH_6	Disabled	Channel_6	10 Hz	Calculated Gear	#	0	6		
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00		
ACC_2	Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00		
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50		
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0		
ECU_1	Enabled	BOSCH_RPM	10 Hz	Engine speed sensor	rpm	0	18000		
ECU_2	Enabled	BOSCH_SPEED1	10 Hz	Bosch speed sensor	km/h .1	0.0	500.0		
ECU_3	Enabled	BOSCH_SPEED2	10 Hz	Speed sensor	km/h	0	500		
ECU_4	Enabled	BOSCH_OIL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_5	Enabled	BOSCH_FUEL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_6	Enabled	BOSCH_ATM_PRESS	10 Hz	Pressure sensor	mbar	0	130		
ECU_7	Enabled	BOSCH_FUEL_TEMP	5 Hz	Temperature sensor	°C	-50	215		
ECU_8	Enabled	BOSCH_OIL_TEMP	5 Hz	Temperature sensor	°C	-50	215		
ECU_9	Enabled	BOSCH_ENGINE_TEMP	5 Hz	Temperature sensor	°C	-50	150		
ECU_10	Enabled	BOSCH_AIR_TEMP	5 Hz	Temperature sensor	°C	-50	150		
ECU_11	Enabled	BOSCH_THROTT_ANG	10 Hz	Throttle position sensor	% .1	0.0	100.0		
ECU_12	Enabled	BOSCH_IGNIT_ANG	10 Hz	Angle sensor	deg	-90	90		
ECU_13	Enabled	BOSCH_AIR_CHARGE	10 Hz	Percentage sensor	%	0	190		
ECU_14	Enabled	BOSCH_INJ_TM1	10 Hz	System clock	ms .01	0.00	210.00		
ECU_15	Enabled	BOSCH_INJ_TM2	10 Hz	System clock	ms .01	0.00	210.00		
ECU_16	Enabled	BOSCH_LAMBDA1	10 Hz	Lambda sensor	# .001	0.000	16.000		
ECU_17	Enabled	BOSCH_LAMBDA2	10 Hz	Lambda sensor	# .001	0.000	16.000		

This layer allows to set the logger sampled channels.

On top of the window are the panels concerning RPM, speed and gear sensor. Their layout depends on the configuration set.

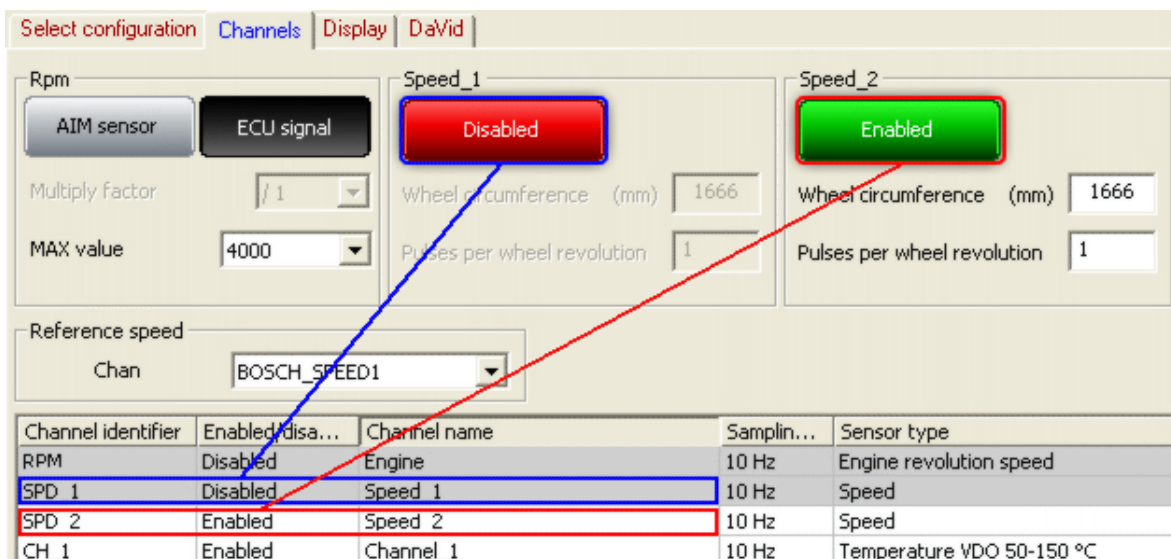
Enable and set the speed to be used and disable the ones not to be used.

### 8.3.1 – RPM panel



- Select “**AIM Sensor**” to sample this information from an RPM sensor installed on the vehicle; set Multiply factor and RPM Max value. RPM row in the table below enables (figure below on the left).
- Select “**ECU Signal**” and set RPM Max value to sample this value from the vehicle ECU. RPM row in the table below disables (figure above on the right).

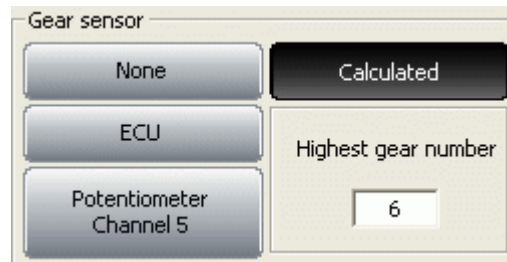
### 8.3.2 – Speed panel



The panels and their channels are enabled/disabled through the related button, as shown here above. The button changes its colour.

Once enabled the speed fill in wheel circumference and number of pulses per wheel revolution (corresponding to the number of magnets installed on the vehicle wheel).

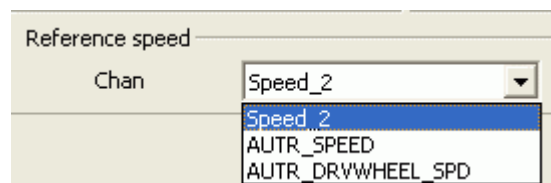
### 8.3.3 – Gear sensor panel



**DaVid** can sample the engaged gear from a gear sensor, from the vehicle ECU or can calculate it with an algorithm based on RPM and speed. Available options are:

- **“None”**: there is no gear sensor on the vehicle (or not to see the engaged gear). This option is disabled on the display and channel table shows row labelled CH\_5 enabled with configurable sensor and row labelled CH\_6 disabled.
- **“ECU”**: to sample this information from the vehicle ECU (assuming it can transmit it); channel table shows row labelled CH\_5 enabled with configurable sensor and row labelled CH\_6 set on calculated gear.
- **“Potentiometer Channel 5”**: there is a gear potentiometer installed on channel 5. Channel table shows row labelled CH\_5 enabled and set on gear potentiometer and row labelled CH\_6 disabled and set on calculated gear.
- **“Calculated”**: to compute the engaged gear with an algorithm based on RPM and speed; fill in “Highest gear number”. Channel table shows row labelled CH\_5 disabled (but can be enabled with configurable sensor) and row labelled CH\_6 enabled and set on calculated gear. See the related chapter for further information.

### 8.3.4 – Reference speed panel

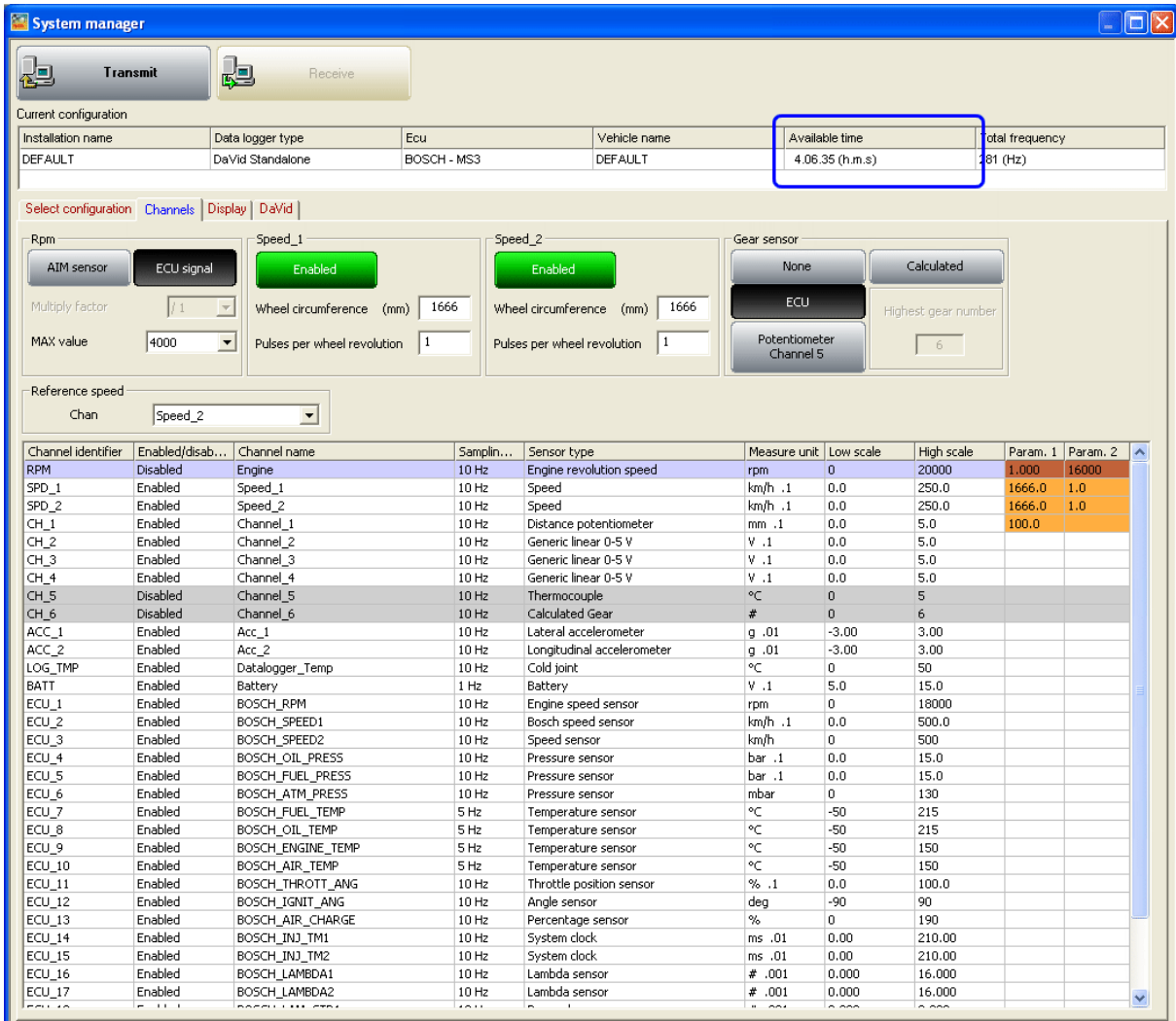


It is possible to select the reference speed, that is used for gear calculation and for some Race Studio Analysis calculation.

Available options are: logger speed/speeds (depending on how many of them were enabled) and speed(s) coming from the vehicle ECU.

In the figure below the logger has one only speed enabled and is connected to an Autronic ECU that transmits two speed channels.

### 8.3.5 – Channel table:



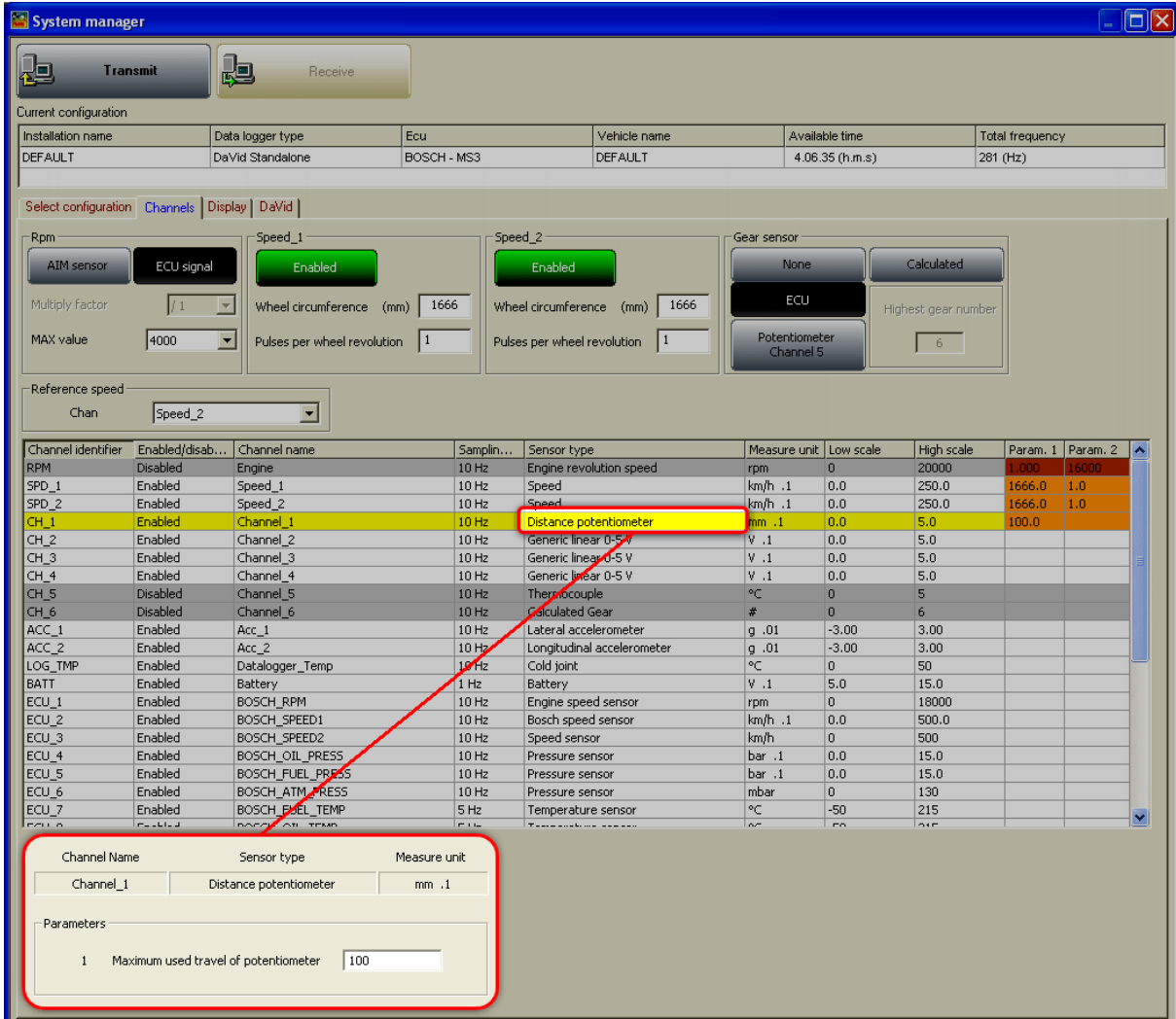
The screenshot shows the 'System manager' window with the 'Channels' tab selected. The 'Current configuration' summary at the top shows 'Available time' as 4.06.35 (h.m.s), which is highlighted with a blue box. Below this are configuration panels for 'Rpm', 'Speed\_1', 'Speed\_2', and 'Gear sensor'. The main part of the window is a table of channels with the following columns: Channel identifier, Enabled/disabled, Channel name, Sampling frequency, Sensor type, Measure unit, Low scale, High scale, Param. 1, and Param. 2.

Channel identifier	Enabled/disabled	Channel name	Sampling frequency	Sensor type	Measure unit	Low scale	High scale	Param. 1	Param. 2
RPM	Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000	1,000	16000
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
SPD_2	Enabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
CH_1	Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0	100.0	
CH_2	Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_3	Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_4	Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_5	Disabled	Channel_5	10 Hz	Thermocouple	°C	0	5		
CH_6	Disabled	Channel_6	10 Hz	Calculated Gear	#	0	6		
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00		
ACC_2	Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00		
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50		
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0		
ECU_1	Enabled	BOSCH_RPM	10 Hz	Engine speed sensor	rpm	0	18000		
ECU_2	Enabled	BOSCH_SPEED1	10 Hz	Bosch speed sensor	km/h .1	0.0	500.0		
ECU_3	Enabled	BOSCH_SPEED2	10 Hz	Speed sensor	km/h	0	500		
ECU_4	Enabled	BOSCH_OIL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_5	Enabled	BOSCH_FUEL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_6	Enabled	BOSCH_ATM_PRESS	10 Hz	Pressure sensor	mbar	0	130		
ECU_7	Enabled	BOSCH_FUEL_TEMP	5 Hz	Temperature sensor	°C	-50	215		
ECU_8	Enabled	BOSCH_OIL_TEMP	5 Hz	Temperature sensor	°C	-50	215		
ECU_9	Enabled	BOSCH_ENGINE_TEMP	5 Hz	Temperature sensor	°C	-50	150		
ECU_10	Enabled	BOSCH_AIR_TEMP	5 Hz	Temperature sensor	°C	-50	150		
ECU_11	Enabled	BOSCH_THROTT_ANGLE	10 Hz	Throttle position sensor	% .1	0.0	100.0		
ECU_12	Enabled	BOSCH_IGNIT_ANGLE	10 Hz	Angle sensor	deg	-90	90		
ECU_13	Enabled	BOSCH_AIR_CHARGE	10 Hz	Percentage sensor	%	0	190		
ECU_14	Enabled	BOSCH_INJ_TM1	10 Hz	System clock	ms .01	0.00	210.00		
ECU_15	Enabled	BOSCH_INJ_TM2	10 Hz	System clock	ms .01	0.00	210.00		
ECU_16	Enabled	BOSCH_LAMBDA1	10 Hz	Lambda sensor	# .001	0.000	16.000		
ECU_17	Enabled	BOSCH_LAMBDA2	10 Hz	Lambda sensor	# .001	0.000	16.000		

This table shows all loggers channels with the related characteristics:

- **Channel identifier:** shows the channel label. “ECU\_X” channels are the ones coming from the ECU.
- **Enabled/disabled:** shows the channel status (enabled or disabled). It can be modified double clicking on the cell except for RPM, Speed and CH\_6 that need to be modified through the above described panels.
- **Channel name:** names the channel.
- **Sampling frequency:** sets each channel sampling frequency. This last one influences the total available time highlighted by a box in the figure above, that diminishes increasing sampling frequency because the memory fills up faster.

- **Sensor type:** allows to select the sensor installed on that channel from the drop down menu that appears clicking on the cell. Channel labelled CH\_5 is always configurable except when “Gear Sensor” panel is set on calculated gear. **N.B.:** setting some sensors on some channels that support them, a configuration panel appears on bottom of the layer. The figure below shows the distance potentiometer configuration panel.



The screenshot shows the 'System manager' window with the 'Channels' tab selected. A table lists various channels and their configurations. Channel 1 is highlighted in yellow, and its sensor type is 'Distance potentiometer'. A red box highlights the 'Distance potentiometer' text in the table. Below the table, a configuration panel for Channel 1 is shown, with a red box around it. The panel includes fields for 'Channel Name', 'Sensor type', and 'Measure unit', and a 'Parameters' section with a list item '1 Maximum used travel of potentiometer' set to '100'.

Channel identifier	Enabled/disab...	Channel name	Sampl...	Sensor type	Measure unit	Low scale	High scale	Param. 1	Param. 2
RPM	Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000	1.000	16600
SPD_1	Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
SPD_2	Enabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0	1666.0	1.0
CH_1	Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0	100.0	
CH_2	Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_3	Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_4	Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0		
CH_5	Disabled	Channel_5	10 Hz	Thermocouple	°C	0	5		
CH_6	Disabled	Channel_6	10 Hz	Calculated Gear	#	0	6		
ACC_1	Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00		
ACC_2	Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00		
LOG_TMP	Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50		
BATT	Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0		
ECU_1	Enabled	BOSCH_RPM	10 Hz	Engine speed sensor	rpm	0	18000		
ECU_2	Enabled	BOSCH_SPEED1	10 Hz	Bosch speed sensor	km/h .1	0.0	500.0		
ECU_3	Enabled	BOSCH_SPEED2	10 Hz	Speed sensor	km/h	0	500		
ECU_4	Enabled	BOSCH_OIL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_5	Enabled	BOSCH_FUEL_PRESS	10 Hz	Pressure sensor	bar .1	0.0	15.0		
ECU_6	Enabled	BOSCH_ATM_PRESS	10 Hz	Pressure sensor	mbar	0	130		
ECU_7	Enabled	BOSCH_FUEL_TEMP	5 Hz	Temperature sensor	°C	-50	215		
ECU_8	Enabled	BOSCH_OIL_TEMP	5 Hz	Temperature sensor	°C	-50	215		

Channel Name: Channel\_1    Sensor type: Distance potentiometer    Measure unit: mm .1

Parameters:

1 Maximum used travel of potentiometer: 100

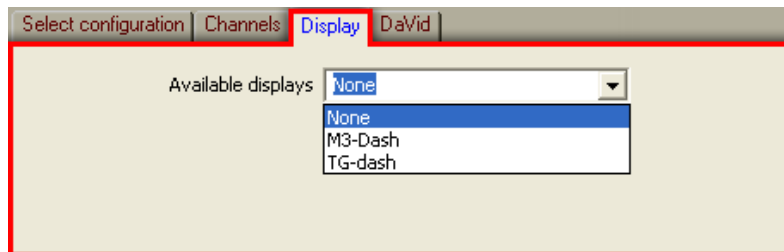
- **Measure unit:** shows the selected unit of measure for each channel; it is possible to change it with a double click on the cell.
- **High/low scale:** shows high/low scale values of the sensor and allows to change them double clicking on the cell.

## 8.4 – Creating a custom sensor

The procedure to create a custom sensor is the same for all AIM loggers. Refer to chapter 12 or further information.

## 8.5 – How to configure DaVid displays

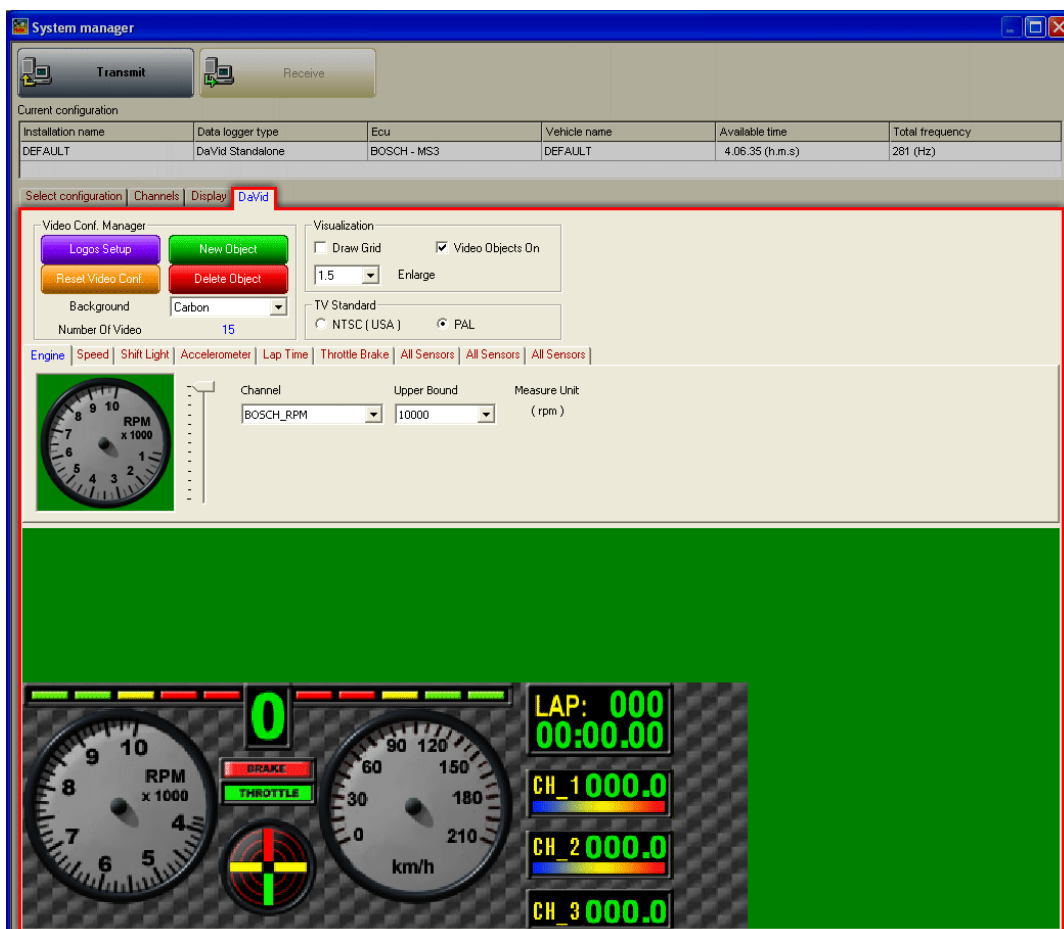
Video recording with data acquisition system **DaVid** can be connected with two kinds of display: **TG-Dash** and **MyChron3 Dash**. To configure them (optional to the logger) activate the related layer (circled here below):



The first time the layer shows up empty. Activate the drop down menu and select the proper display. Refer to chapter 17 for further information.

## 8.6 – How to configure DaVid

Activate “DaVid” layer.

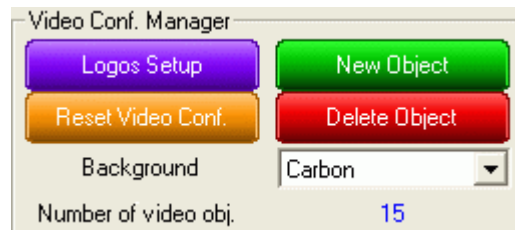




in the figure below video objects preview is highlighted.



### 8.6.1 – Video Configuration Manager box:



Press “**Logos Setup**” button and the window here below appears.



- Using +/- buttons it is possible to resize the logos shown on the video.
- If there are logos shown on the video it is possible to remove them pressing “Delete Logo” button. If there are no logos “Delete Logo” button is disabled (like in the figure above) and pressing “Add Logo” button the window here below appears.



This window allows to both import and remove bitmap logos.

- Pressing “**Import Logo Bitmap**” button windows explorer opens and it will be possible to upload logo bitmaps.
- Pressing “Delete Bitmap Logo” button it is possible to delete bitmap logo.

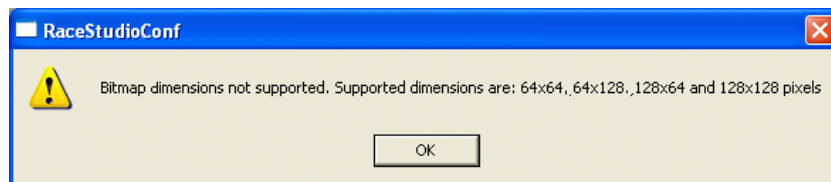
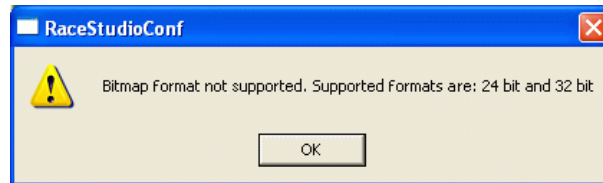
The system allows to import up to 25 bitmaps and in case there are no available logos “Delete bitmap logo” button is disabled.

The logo user is working on is highlighted in yellow in video preview window.

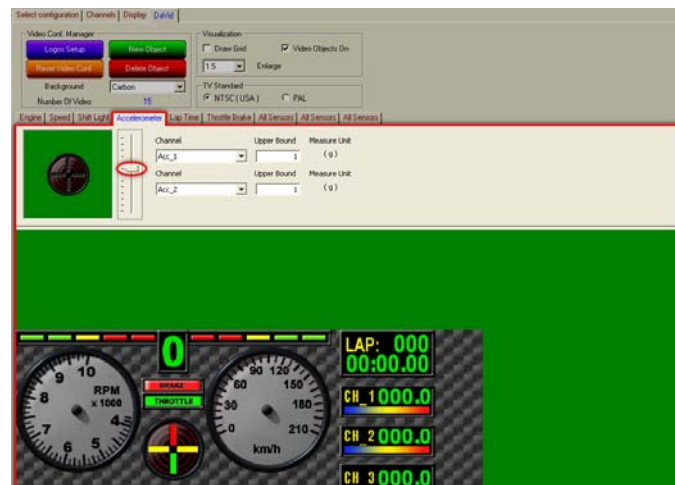
The system supports the following logos:

- **Format:** bitmap 24 bit and bitmap 32 bit
- **Dimensions:** 64x64; 64x128; 128x128;128x64

In case format or dimensions of the Logo Bitmap to import are not supported, the system shows one of the following messages.



### New Object / Delete object:



Video objects preview window can be modified adding or removing objects.

To **add** an object:

- press “New object”;
- use the slider red circled in the figure above, to select that object layout;
- configure the parameters that appear beside the slider;
- a new video object appears in the bottom part of the window; it is possible to displace it using the mouse; pay attention not to over impose more video objects;
- each new object adds a layer to the central part of the layer. In the figure above is highlighted “Accelerometer” layer.

To **delete** an object select the layer corresponding to the object to delete and press “Delete object” layer.

To **modify** an object select its layer, use the slider to select its layout and modify the related fields.

### 8.6.2 – Video objects limits

**The number of objects that can be visualized depends on the type of objects.**

For all objects whose video refreshing frequency is 50Hz (typically RPM and speed, these with the pointer) the max. allowed number of objects is two.

Some objects – like the accelerometer, Lap Time box, etc. – are considered as one only object but are made up of more active parts. Accelerometer, for example, has two active parts that shows lateral and longitudinal acceleration.

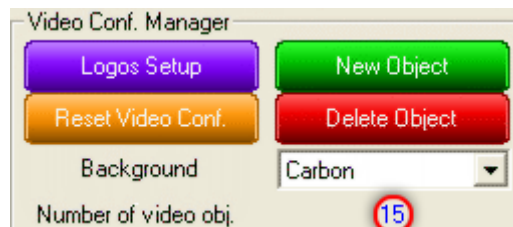
Lap Time box – shown here below – is considered as one only object but is made up of six active parts.



- Lap Number (1)
- Lap Time (2)
- Split Number (3)
- Split Time (4)
- Best lap number (5)
- Best lap time (6)

**The total number of objects and active parts that can be shown is 16.**

This information is written in “Video Configuration Manager” box shown here below and is labelled as “Number of video obj.” (red circled).



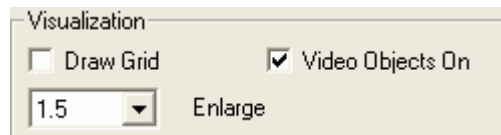
In case the maximum allowed number of objects is overcome, the related digit turns into red.

**It is possible to create up to 22 video objects in the same configuration before the warning message shown here below appears.**

It is anyway necessary that the number of object/active parts included in a configuration is not higher than 16. If higher, the system shows again this message and does not transmit the configuration.



### 8.6.3 – Visualization box:



This box modifies objects preview window shown here below.

- “**Draw Grid**”: shows a grid in the preview window to help positioning the objects.
- “**Video Objects On**”: enabled or disabled shows or hides the video objects preview.
- “**Zoom**”: sets the dimensions of the video objects preview. Available options are: from 1 (real dimensions) to 4.



**Warning:** these functionalities only influence the layout of the configuration shown by Race Studio 2 and not that of the real Video.

### 8.6.4 – TV Standard box:



This box allows sets the video TV standard.

To know the TV standard of the camera connected to the Video system refer to that object user manual.

In general, anyway, NTSC television standard is mainly used in the USA while PAL television standard is mainly used in Europe.

### 8.6.5 – Possible graphical visualization problems.

The PC monitor may show the grey scale non homogeneous (exactly like in the figure below).



A possible solution to this problem is working on the video board properties, “OpenGL” settings.

- Close **Race Studio 2** and follow this path: “Start / Settings/ Control Panel / Display / Settings / Advanced”.
- Video board properties panel appears. Its layout depends on the type of board.
- Open GL settings can be on a dedicated layer, in 3D layer of that panel on PC that do not have a specific “OpenGL” layer or on a layer labelled with the name of the video board pressing graphic settings button.
- It is necessary to increase 3D quality in “OpenGL” settings. This operation can sometimes solve the problem.

It is also suggested to check if video board driver is the last available from the manufacturer. If not, pls. update it.

### 8.6.6 – Sampling frequency

With reference to system manager window – Channel layer – it is reminded that from that window it is possible to set each channel sampling frequency.

As far as RPM and shown speed channels it is suggested to set them on 50 Hz because this is the refreshing frequency of the image on the video.

## 8.7 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 13 for further information.

## 8.8 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, to say auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate the gear sensor, the mid zero potentiometer and the zero based potentiometer installed on the vehicle.

See chapter 14 for further information.

**Warning: if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.**

## 8.9 – Gear calculation

Refer to chapter 15 for further information.

## 8.10 – Online

Online function is very useful to check the logger proper working. Refer to chapter 18 for further information.

## Chapter 9 – How to configure EVO3 Pro/Pista

To correctly configure **EVO3 Pro/Pista** (from here onward **EVO3**), use a PC and **Race Studio 2** software. This logger can only be configured via software.

Before starting the configuration, install **Race Studio 2** and the USB driver as explained in chapter 2.

Run the software, clicking on **Race Studio 2** icon and the window here below appears.



In the title bar – white on a blue background in the figure – you can see the **Race Studio 2** version installed on the PC.

Immediately under there is the menu bar, shown in a more intuitive way on the left thanks to the graphic buttons: Go to Analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

From this window it is possible to perform all needed operations to manage all AIM systems.



To enter configuration menu press “AIM system manager” button; a panel showing all systems managed through **Race Studio 2** software appears: double click on “EVO3” or select it and click on “✓Go to”.



Race Studio 2 system manager window appears.

## 9.1 – System manager window



Using the keyboard and the layers, circled in the figure, it is possible to perform all operations necessary to manage an AIM system.

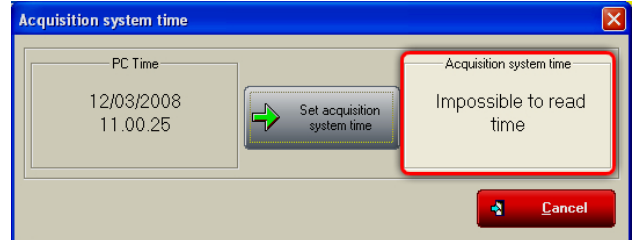
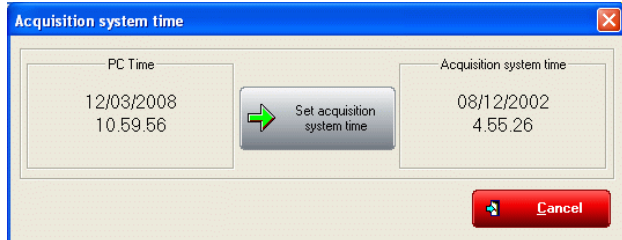
The top keyboard, shown here below, is made up of five buttons:



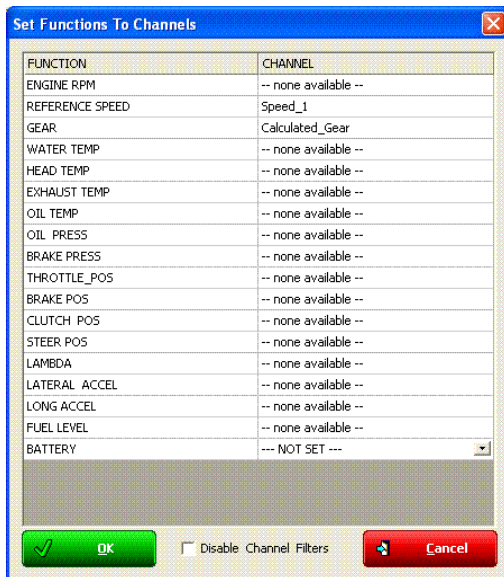
- **Transmit:** transmits a configuration to the logger and is active with any layer; it needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger and is active only in “Select Configuration” layer.
- **CAN-Net Info:** identifies the CAN network connected to the PC, that means the logger and its peripherals. Pressing it a waiting window appears and – when the connection has been established – “CAN-Net info” window, shown here below, appears. It shows all the CAN Network components. In the example below the CAN network includes an EVO3 Pro Master and four expansions: DaVid, LCU-ONE, GPS and MemoryKey.

N	Category of Logger	Type of Logger	Expansion Name	Logger ID	ID Date	Firmware ...	Firmware Date
1	MASTER	EVO3 PRO	Master	12345	16/01/2008	28.07.11	21/12/2007
2	CAN EXPANSION	DaVid		47111881	18/01/2008	22.03	09/11/2007
3	CAN EXPANSION	LCU-ONE	LC	1111111	13/12/2007	25.09	19/11/2007
4	CAN EXPANSION	GPS		902499	14/01/2008	35.13	17/12/2007
5	CAN EXPANSION	MEMORY KEY		7613105	17/12/2007	37.05	18/12/2007

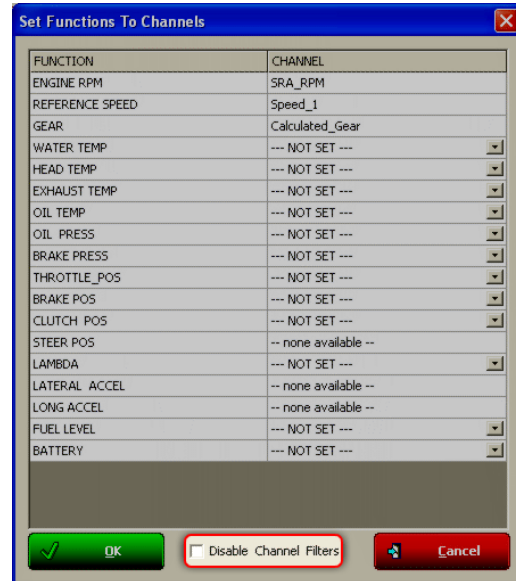
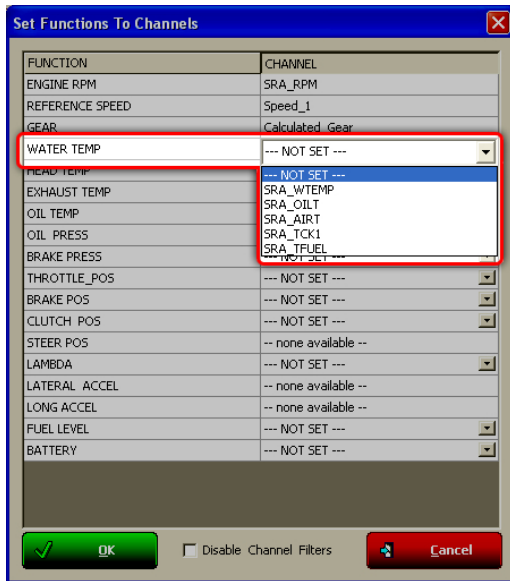
- Set acquisition system time:** makes the logger time matching the PC one. Pressing it “Acquisition system time” window, below on the left, appears with PC clock on the left and EVO3 one on the right. Pressing the central button, PC and EVO3 will have the same time. This operation does not modify data sampled by the logger nor influence its peripherals. In case the window on the right appears it means that PC-logger connection is wrong. Check it and try again.



- SmartyCam functions settings:** allows to set SmartyCam channels. Pressing it the related panel appears. With reference to the images here below, each function available options depends on the fact whether the all network is connected to the vehicle ECU or not. This means that if there is no ECU all functions not managed directly by SmartyCam are shown as “none available” and cannot be set while in case an ECU is available all function supported by that ECU are shown as “Not set” and can be set.



In case an ECU is available it is necessary to decide which channel to associate with each function. With reference to the images here below, for example, to set SmartyCam water temperature channel click on arrow right of the function and a drop down menu opens showing all available temperature channels. Select the one that will be shown on SmartyCam video and press OK. In case the channel is not shown enable “Disable channel filters” checkbox and all available channels will be shown no matter if they are temperature channels or not.



**Current Configuration Table**, immediately under the keyboard, shows the main information concerning the configuration user is working on.

Current configuration									
Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	EVO3 PRO	None - None	DEFAULT	11.29.05 (h.m.s)	6.24.31 (h.m.s)	202 (Hz)	171 (Hz)	31 (Hz)	1

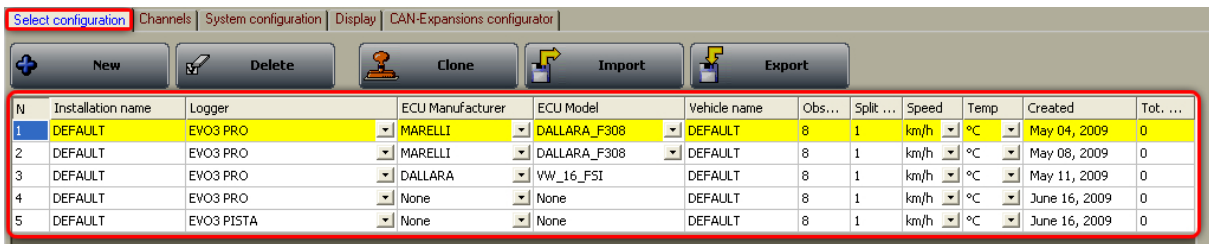
Again, under this table are five layers:



- **Select configuration:** allows the user to select the configuration to work on; it is always active.
- **Channels:** allows to set EVO3 channels. It is active only if there are configurations in "Select configuration" layer.
- **System configuration:** allows to set or modify EVO3 configuration. It is active only if there are configurations in "Select configuration" layer.
- **Display:** allows to set the configuration of EVO3 display. It is active only if there are configurations in "select configuration" layer. Refer to the related chapter for further information concerning AIM displays.
- **CAN-expansions configurator:** allows to configure the expansions connected to EVO3, DaVid Slave included. It is active only if there are configurations in "Select configuration" layer; if not, it doesn't even appear. Refer to chapter 16 for further information. **Note:** if the expansion is a DaVid Slave refer to paragraph 8.6 (David master) for further information.

### 9.1.1 – Select configuration layer

“Select configuration” layer – shown here below – is made of:



N	Installation name	Logger	ECU Manufacturer	ECU Model	Vehicle name	Obs...	Split ...	Speed	Temp	Created	Tot. ...
1	DEFAULT	EVO3 PRO	MARELLI	DALLARA_F308	DEFAULT	8	1	km/h	°C	May 04, 2009	0
2	DEFAULT	EVO3 PRO	MARELLI	DALLARA_F308	DEFAULT	8	1	km/h	°C	May 08, 2009	0
3	DEFAULT	EVO3 PRO	DALLARA	VW_16_FSI	DEFAULT	8	1	km/h	°C	May 11, 2009	0
4	DEFAULT	EVO3 PRO	None	None	DEFAULT	8	1	km/h	°C	June 16, 2009	0
5	DEFAULT	EVO3 PISTA	None	None	DEFAULT	8	1	km/h	°C	June 16, 2009	0

On top is the keyboard made up of five buttons.

- **New:** creates a new configuration;
- **Delete:** deletes a configuration;
- **Clone:** clones a configuration;
- **Import:** imports a configuration from a file;

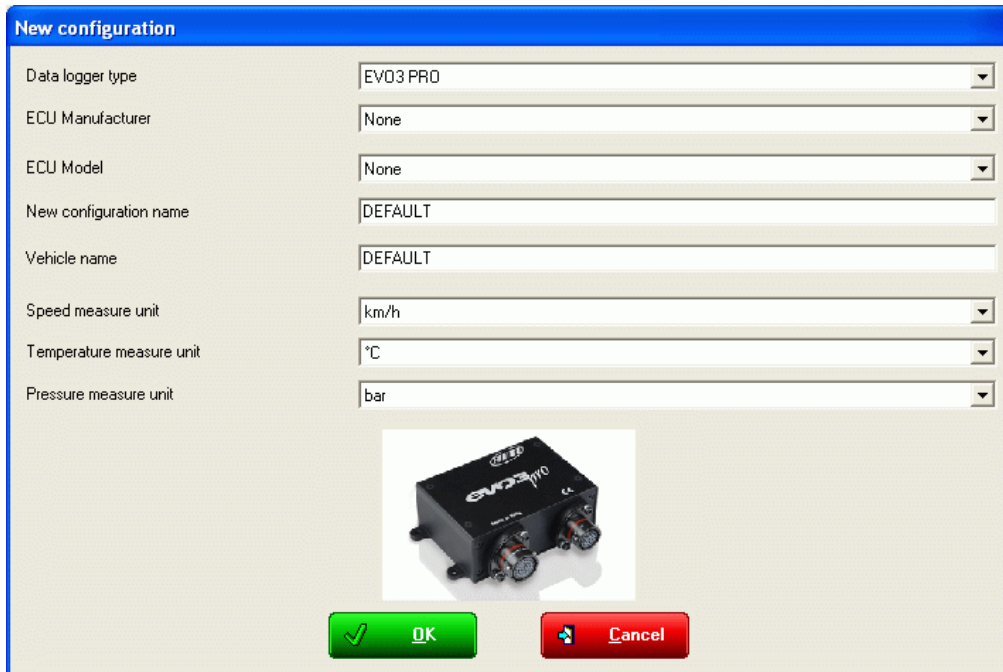
**Export:** exports a configuration to a file.

**Central** is the available configurations database. To work on one of them click on any of its cell and the entire row is selected (highlighted in yellow).

In case of first configuration central table shows up empty.

## 9.2 – Creating a new configuration

Pressing “New” button in “Select Configuration” layer this window appears:



Some parameters need to be set:

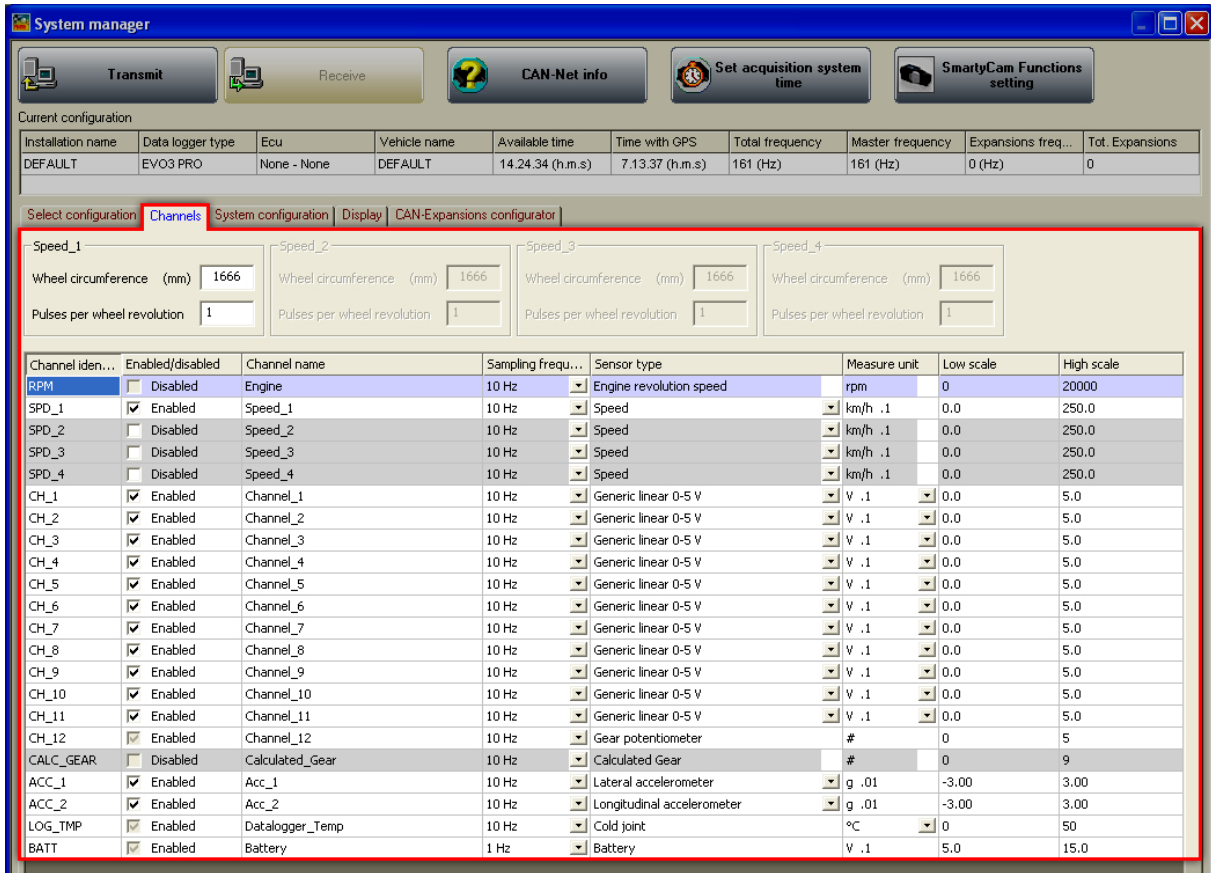
- **Data logger type:** select the logger to be configured.
- **ECU Manufacturer:** select the Manufacturer of the ECU installed on the vehicle if supported or none.
- **ECU Model:** select the ECU model.
- **New configuration name:** fill in the new configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Speeds unit of measure:** choose between km/h and mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (or “Cancel” to quit without saving).

The system comes back to system manager window.

## 9.3 – Channels

Activate “Channels” layer.



System manager

Transmit Receive CAN-Net info Set acquisition system time SmartyCam Functions setting

Current configuration

Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	EVO3 PRO	None - None	DEFAULT	14.24.34 (h.m.s)	7.13.37 (h.m.s)	161 (Hz)	161 (Hz)	0 (Hz)	0

Select configuration Channels System configuration Display CAN-Expansions configurator

Speed\_1 Speed\_2 Speed\_3 Speed\_4

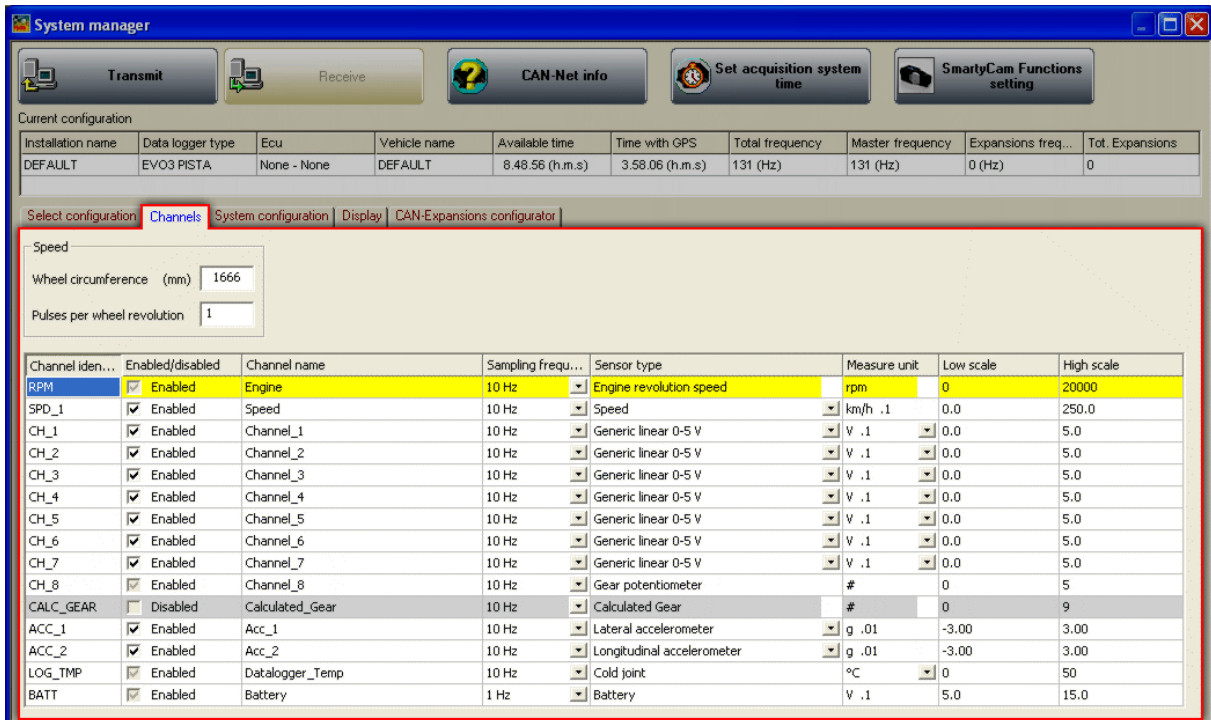
Wheel circumference (mm) 1666 Wheel circumference (mm) 1666 Wheel circumference (mm) 1666 Wheel circumference (mm) 1666

Pulses per wheel revolution 1 Pulses per wheel revolution 1 Pulses per wheel revolution 1 Pulses per wheel revolution 1

Channel iden...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input type="checkbox"/> Disabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input type="checkbox"/> Disabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0

This layer allows to set all channels sampled by the logger and its layout depends on EVO3 version.

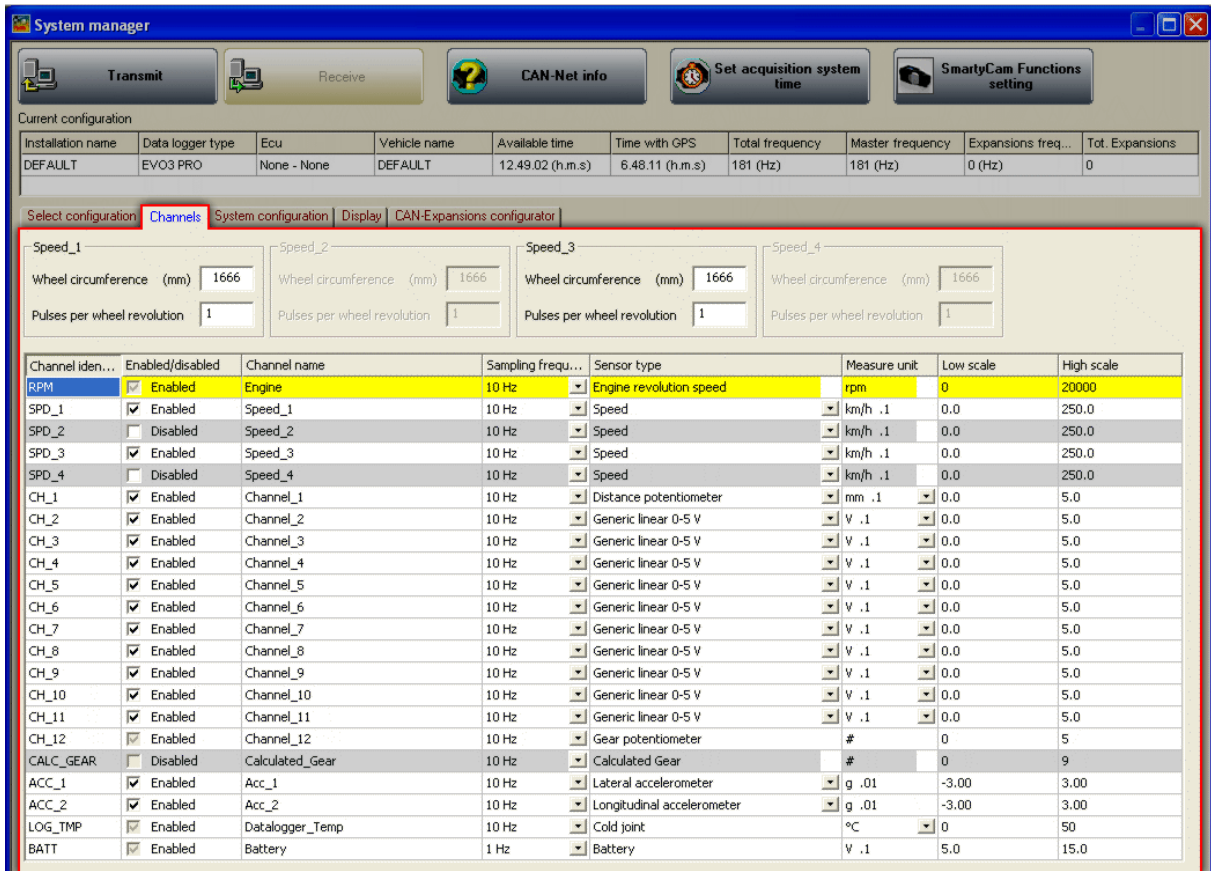
In case of an **EVO3 Pista** configuration this window appears.



The screenshot shows the 'System manager' window with the 'Channels' tab selected. The 'Current configuration' table shows 'EVO3 PISTA' as the data logger type. Below the table, the 'Speed' section has 'Wheel circumference (mm)' set to 1666 and 'Pulses per wheel revolution' set to 1. The main table lists various channels with their status, names, sampling frequencies, sensor types, and scales.

Channel iden...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0

In case of an **EVO3 Pro** configuration this window appears.



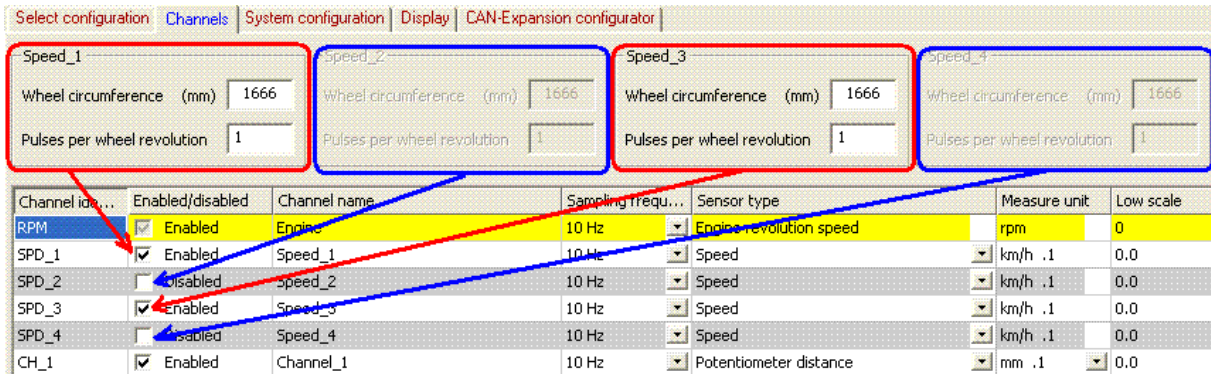
The screenshot shows the 'System manager' window with the 'Channels' tab selected. The 'Current configuration' table shows 'EVO3 PRO' as the data logger type. Below the table, the 'Speed' section has four sub-sections (Speed\_1 to Speed\_4), each with 'Wheel circumference (mm)' set to 1666 and 'Pulses per wheel revolution' set to 1. The main table lists various channels with their status, names, sampling frequencies, sensor types, and scales.

Channel iden...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input checked="" type="checkbox"/> Enabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0



### 9.3.1 – Speed panels

On top of Channels layer can be from one to four panels (depending on **EVO3** version) labelled “Speed”. It is possible to enable/disable them through the channel table below. To enable a Speed channel just enable the checkbox in the corresponding row of channel table. The figure below shows two Speed channels enabled and two of them disabled: so are the related panels.



Channel id...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0
SPD_3	<input checked="" type="checkbox"/> Enabled	Speed_3	10 Hz	Speed	km/h .1	0.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Potentiometer distance	mm .1	0.0

When a panel is enabled it is necessary to set its parameters.

Speed\_1

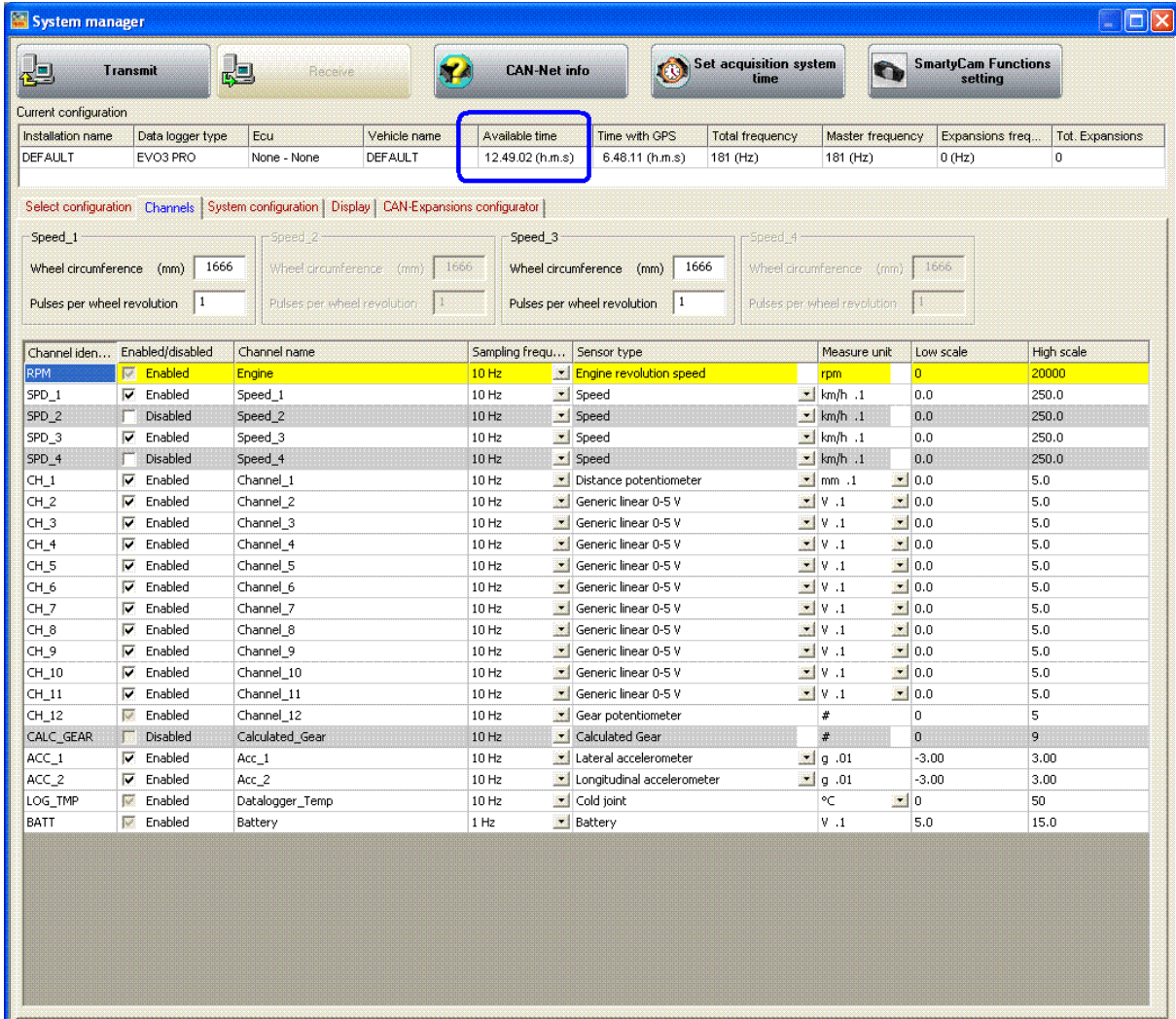
Wheel circumference (mm)

Pulses per wheel revolution

Fill in:

- wheel circumference of the vehicle;
- number of pulses for wheel revolution (that corresponds to the number of magnets installed on the wheel).

### 9.3.2 – Channel Table



The screenshot shows the 'System manager' window with the 'Channels' tab selected. At the top, there are buttons for 'Transmit', 'Receive', 'CAN-Net info', 'Set acquisition system time', and 'SmartyCam Functions setting'. Below these is the 'Current configuration' table, where the 'Available time' cell is highlighted with a blue box and contains the value '12.49.02 (h.m.s)'. Below the configuration table are tabs for 'Select configuration', 'Channels', 'System configuration', 'Display', and 'CAN-Expansions configurator'. The 'Channels' tab is active, showing four speed channel configuration sections (Speed\_1 to Speed\_4) with input fields for wheel circumference and pulses per revolution. Below these is the 'Channel Table' table.

Channel iden...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input checked="" type="checkbox"/> Enabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0

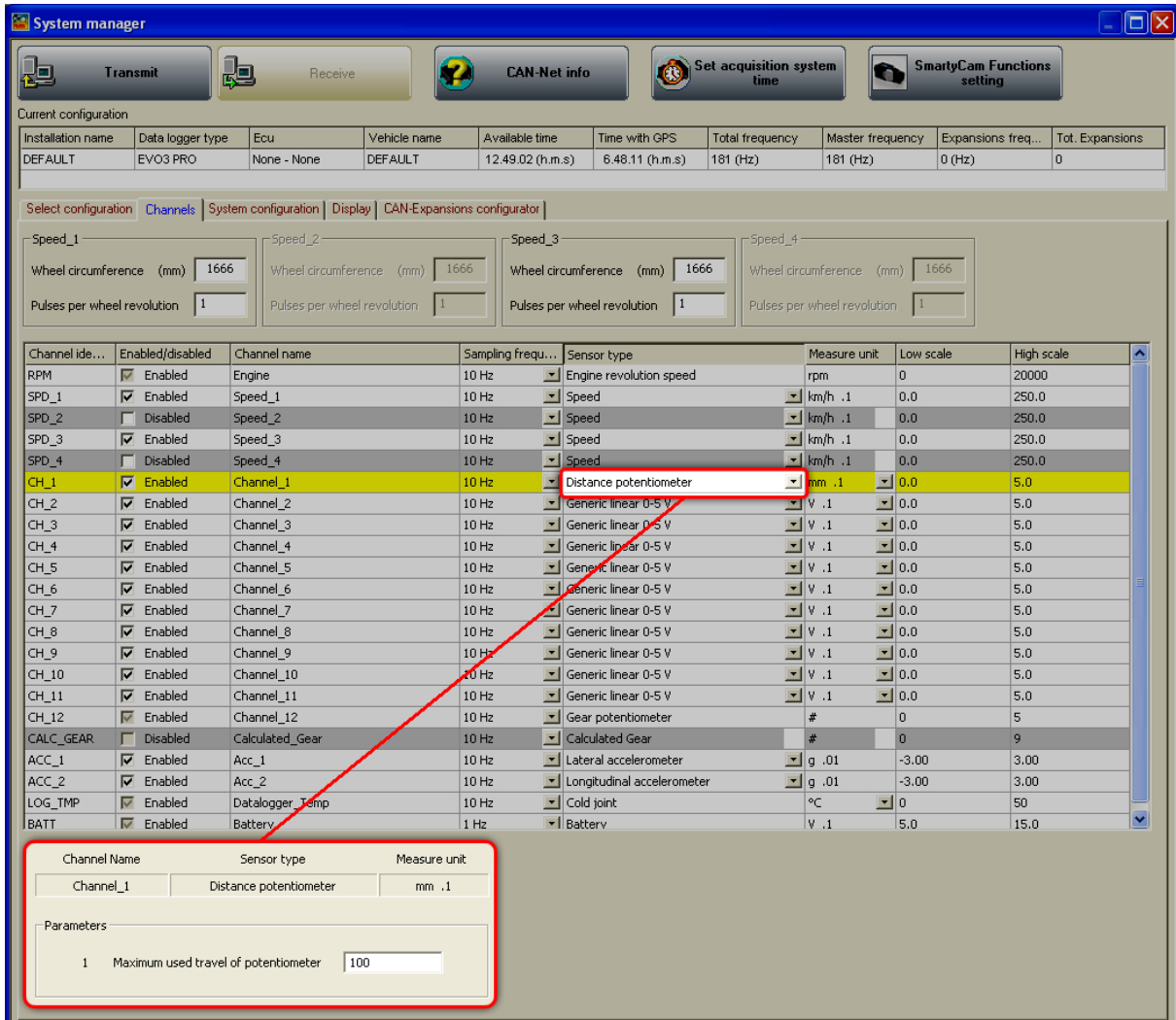
It shows all logger channels with the related characteristics

- **Channel identifier:** shows the channel label. Channels labelled “ECU\_X” are the ones received from the ECU.
- **Enabled/disabled:** shows channel status (enabled or disabled). The status can be modified double clicking on the cell except for RPM, Speed and CH\_12; RPM and CH\_12 needs to be set through “System Configuration” panel, while Speed one is to be set as explained before.
- **Channel name:** names the channel.
- **Sampling frequency:** sets each channel sampling frequency. This last one influences the total available time, highlighted by a box in the figure below, because the memory fills up faster.
- **Sensor type:** shows the type of sensor installed on that channel; it is selected through the drop down menu that appears clicking on the cell. See the following page for further information.
- **Measure unit:** shows the unit of measure selected for each channel; to change it double click on the cell.
- **Low/High scale:** shows high/low scale values of the sensor and allows to change it double clicking on the cell.

	Temperatures	Pressures	Potentiometers	Lambda Probe	Gyroscope	Accelerometer
<b>EVO3 Pista</b>						
Ch_1	X	X	X	X		
Ch_2	X	X	X	X		
Ch_3	X	X	X	X		
Ch_4	X	X	X	X	X	X
Ch_5	X	X	X	X	X	X
Ch_6	X	X	X	X	X	X
Ch_7	X	X	X	X	X	X
Ch_8 <sup>6</sup>	X	X	X	X	X	X
<b>EVO3 Pro</b>						
Ch_1	X	X	X	X		
Ch_2	X	X	X	X		
Ch_3	X	X	X	X		
Ch_4	X	X	X	X		
Ch_5	X	X	X	X		
Ch_6	X	X	X	X		
Ch_7	X	X	X	X		
Ch_8	X	X	X	X	X	X
Ch_9	X	X	X	X	X	X
Ch_10	X	X	X	X	X	X
Ch_11	X	X	X	X	X	X
Ch_12 <sup>6</sup>	X	X	X	X	X	X

<sup>6</sup> Channels CH\_8 (**EVO3 Pista**) and CH\_12 (**EVO3 Pro**) are gear channels and if system configuration layer (paragraph 9.5) sets them on "Potentiometer CH\_8" (**EVO3 Pista**), "Potentiometer CH\_12" (**EVO3 Pro**) or on "Calculated + Neutral Signal" channel CH\_8 or CH\_12 sets on calculated gear and it is only possible to set Channel name, Sampling frequency and High/Low scale. If not they work as shown in the table above but need to be enabled.

Setting some sensors on some channels that support them, a configuration panel appears bottom left of Channels layer. The figure here below shows distance potentiometer configuration panel.



The screenshot shows the 'System manager' window with the 'Channels' tab selected. At the top, there are buttons for 'Transmit', 'Receive', 'CAN-Net info', 'Set acquisition system time', and 'SmartyCam Functions setting'. Below these is a 'Current configuration' table with columns for Installation name, Data logger type, Ecu, Vehicle name, Available time, Time with GPS, Total frequency, Master frequency, Expansions freq..., and Tot. Expansions.

The main area shows four speed sensor configuration sections (Speed\_1 to Speed\_4), each with 'Wheel circumference (mm)' and 'Pulses per wheel revolution' input fields. Below these is a table of channels with columns: Channel id..., Enabled/disabled, Channel name, Sampling frequ..., Sensor type, Measure unit, Low scale, and High scale.

Channel id...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input type="checkbox"/> Disabled	Speed_2	10 Hz	Speed	km/h .1	0.0	250.0
SPD_3	<input checked="" type="checkbox"/> Enabled	Speed_3	10 Hz	Speed	km/h .1	0.0	250.0
SPD_4	<input type="checkbox"/> Disabled	Speed_4	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Distance potentiometer	mm .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_6	<input checked="" type="checkbox"/> Enabled	Channel_6	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_7	<input checked="" type="checkbox"/> Enabled	Channel_7	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_8	<input checked="" type="checkbox"/> Enabled	Channel_8	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_9	<input checked="" type="checkbox"/> Enabled	Channel_9	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_10	<input checked="" type="checkbox"/> Enabled	Channel_10	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_11	<input checked="" type="checkbox"/> Enabled	Channel_11	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_12	<input checked="" type="checkbox"/> Enabled	Channel_12	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Acc_1	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Acc_2	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0

At the bottom left, a configuration panel for 'Channel\_1' is shown, with a red box highlighting it. It contains the following fields:

Channel Name	Sensor type	Measure unit
Channel_1	Distance potentiometer	mm .1

Parameters:

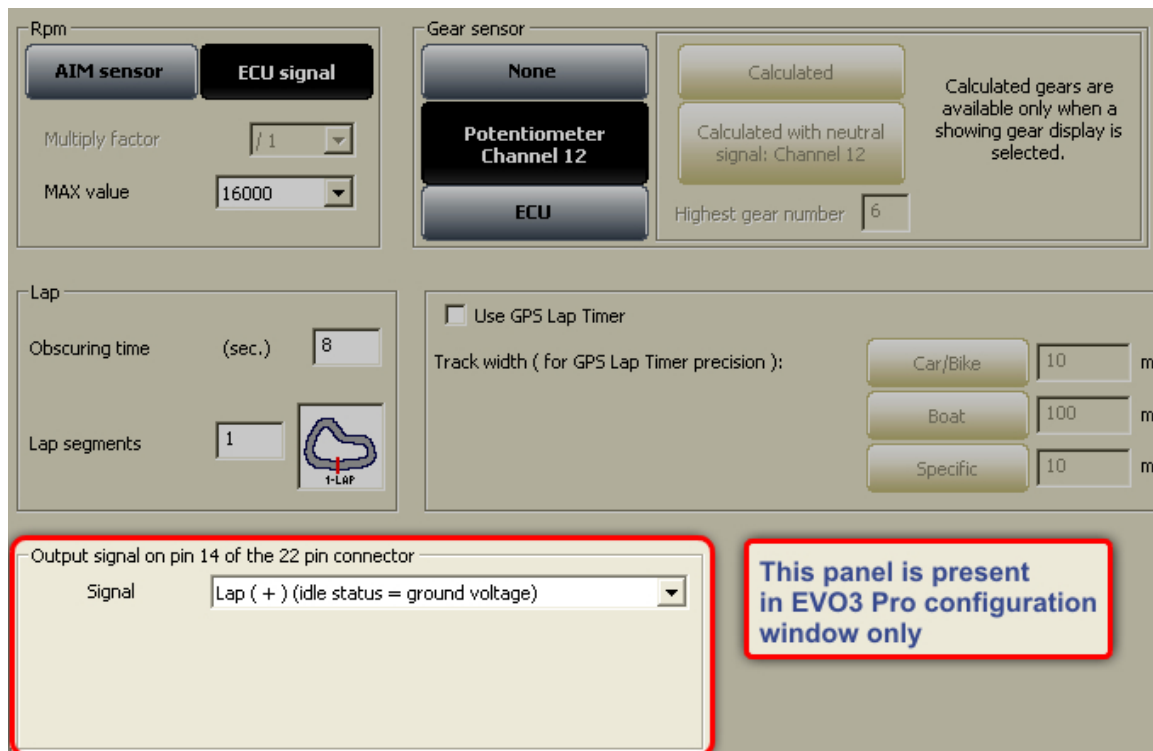
1 Maximum used travel of potentiometer

## 9.4 – Creating a custom sensor

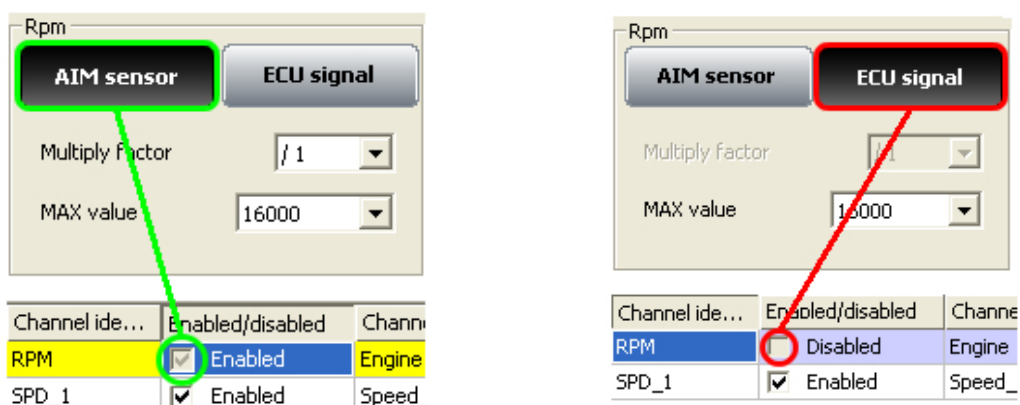
The procedure to create a custom sensor is the same for all AIM loggers. Refer to the related chapter for further information.

## 9.5 – System configuration

Activate “System Configuration” layer:

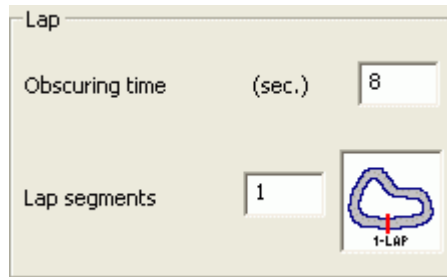


### 9.5.1 – RPM box



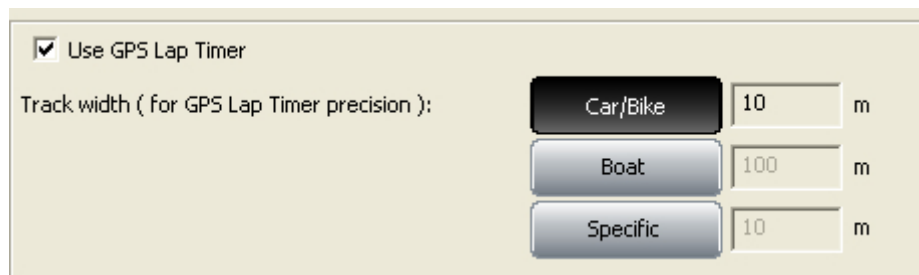
- Select “**AIM Sensor**” to sample this information from an RPM sensor installed on the vehicle. Set Multiply factor and RPM Max value. RPM row in the central table of channels layer enables.
- Select “**ECU signal**” and set RPM Max value to sample this information from the vehicle ECU. RPM row in the central table of channel layer disables.

### 9.5.2 – Lap box



- **Obscuring time:** is a time period during which the optical receiver installed on the vehicle, after having recorded a lap signal, is “blind” and does not record signals. This function is useful to manage split times on tracks where more optical receivers are installed: set obscuring time on a low value (min accepted value is 3 seconds) to record splits and on a value lower than best lap time and higher than the time elapsed between last split and start/finish line (max accepted value is 255 seconds) not to record splits.
- **Lap segments:** is the number of segments the track is divided in and corresponds to the number of transmitters there installed.

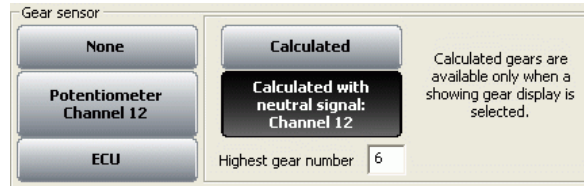
### 9.5.3 – Use GPS lap timer box



It allows to use GPS lap timer in spite of the track beacon equipment. It is necessary to enable the corresponding checkbox and set the track width. Available options are:

- Car/Bike and Boat whose measures are set by default and
- specific that allows to set a specific track width.

### 9.5.4 – Gear sensor box

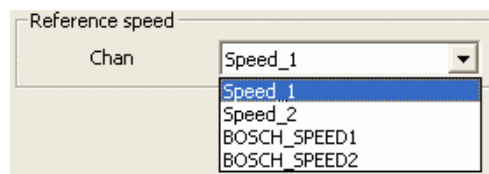


**EVO3Pro/Pista** can sample the engaged gear from a gear sensor, from the ECU but can also calculate it using an algorithm based on RPM and speed. Available options are:

- **None:** there is no gear sensor on the vehicle (or not to see the engaged gear): this option is disabled on the display. Row labelled CH\_8/12 (depending on the logger) on central table of channel layer can be enabled with configurable sensor.
- **Potentiometer Channel 8/12:** there is a gear potentiometer installed on channel 8/12; row labelled CH\_8/12 (depending on the system) in the central table of channels layer is enabled and set on gear potentiometer.
- **ECU:** this information is sampled from the ECU (assuming it can transmit it); row labelled CH\_8/12 (depending on the system) in the central table of channels layer is disabled and can be enabled with configurable sensor.
- **Calculated:** to calculate the engaged gear with an algorithm based on RPM and speed; fill in “Highest gear number”. Row labelled CH\_8/12 (depending on the system) in the central table of channels layer can be enabled with configurable sensor.
- **Calculated + neutral signal:** Channel 8/12 (depending on the system): there is a neutral sensor that can be used to both see neutral gear and calculate the engaged gear. Fill in “Highest gear number”. The central table of channel layer shows row labelled CH\_8/12 enabled and set on calculated gear.

**Note: “Calculated” and “Calculated + neutral signal: Channel 8/12” options are available only if EVO3 Pro/Pista is connected to a display that can show the engaged gear like MyChron3 Dash or Formula Steering Wheel. Refer to chapter 15 for further information on gear calculation.**

### 9.5.5 – Speed reference box



It is possible to select the reference speed used for gear calculation and for some Race Studio Analysis calculation. Available options are the loggers speed(s) (depending on how many have been enabled) and ECU speed(s). In the figure above the logger has two enabled speeds and is connected to a Bosch ECU that transmits two speed channels.

### 9.5.6 – Output signal on pin 14 of Deutsch 22 pin connector

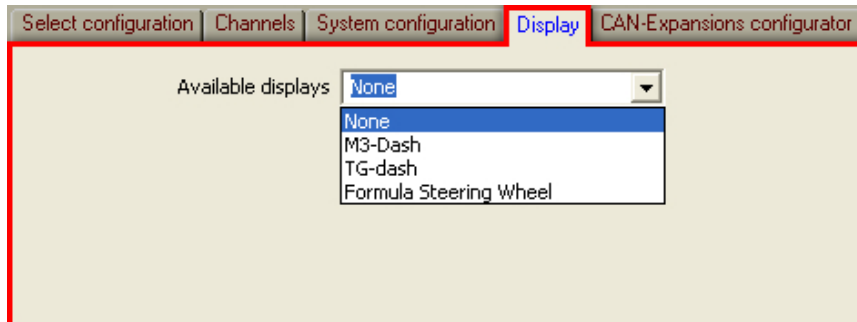
This function allows **EVO3 Pro** to send a signal to an external device, typically a display or an ECU. This output signal is connected to pin 14 of Deutsch 22 pin connector of **EVO3 Pro** and has the following characteristics:

- **Voltage:** Depends on the external pull-up voltage
- **Output duration:** about 0,8 seconds [for Lap (-) and Lap (+)only]
- **Type:** can be type “Lap” or type “Alarm”.
- Available options are:
- **None:** signal disabled.
- **Lap (-) (idle status = external pull up voltage):** when EVO3 Pro receives a lap signal, the signal emitted decreases from pull-up voltage (idle status) to 0V (lap) for about 0,8 seconds.
- **Lap (+) (idle status = ground voltage):** when EVO3 Pro receives a lap signal, the signal emitted grows from 0V (idle status) to pull-up (lap) voltage for around 0,8 seconds.
- **Shift lights:** when RPM are over threshold value, the signal emitted grows from 0V (OFF status) to pull-up voltage (ON status) for the time the threshold value is overcome. This function can be useful to switch on an additional alarm led for over-rev or gear shift indication.



## 9.6 – How to configure EVO3 Pro/Pista displays

**EVO3** available displays are: **MyChron3 Dash**, **TG-Dash** and **Formula Steering Wheel**. To configure the display (optional to the logger) activate the related layer:



The first time the layer shows up empty. Select the proper display through the drop down menu. Refer to chapter 17 for further information.

## 9.7 – Configuring CAN expansions

**EVO3 Pro/Pista**, can be connected to numerous expansions that communicate with it through the CAN bus. See chapter 16 for further information.

**Note:** in case the expansion is a DaVid Slave refer to paragraph 8.6 (**DaVid** master) for information concerning its configuration.

## 9.8 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 13 for further information.

## 9.9 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure: auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate gear sensor, mid zero and zero based potentiometer.

See chapter 14 for further information.

**Warning:** if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.

## 9.10 – Gear calculation

Refer to chapter 15 for further information.

## 9.11 – Online

Online function is very useful to check the logger proper working. Refer to chapter 18 for further information.

## Chapter 10 – How to configure EVO4

To correctly configure **EVO4**, use a PC and **Race Studio 2** software. This logger can only be configured via software.

Before starting the configuration, install **Race Studio 2** and the USB driver as explained in chapter 2.

Run the software, clicking on **Race Studio 2** icon and the window here below appears.



In the title bar – white on a blue background in the figure – you can see the **Race Studio 2** version installed on the PC.

Immediately under there is the menu bar, shown in a more intuitive way on the left thanks to the graphic buttons: Go to Analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

From this window it is possible to perform all needed operations to manage all AIM systems.

To enter configuration menu press “AIM system manager” button; a panel showing all systems managed through **Race Studio 2** software appears: double click on “EVO4” or select it and click on “✓Go to”.



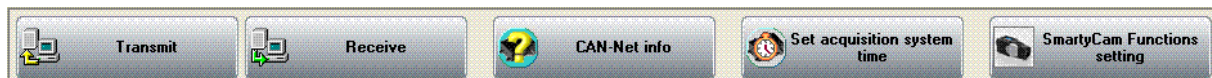
Race Studio 2 system manager window appears.

## 10.1 – System manager window



Using the keyboard and the layers, highlighted in the figure, it is possible to perform all operations necessary to manage an AIM system.

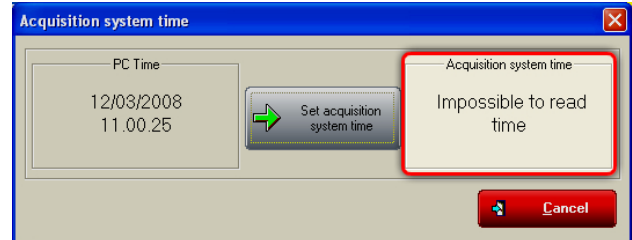
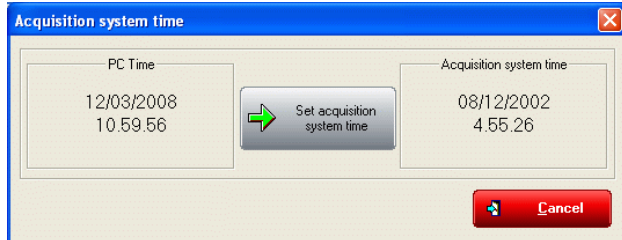
The top keyboard, shown here below, is made up of five buttons:



- **Transmit:** transmits a configuration to the logger and is active with any layer; it needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger and is active only in “Select Configuration” layer.
- **CAN-Net Info:** identifies the CAN network connected to the PC, that means the logger and its peripherals. Pressing it a waiting window appears and – when the connection has been established - “CAN-Net info” window, shown here below, appears. It shows all the CAN Network components. In the example below the CAN network includes an EVO4 Master and four expansions: DaVid, LCU-ONE, GPS and MemoryKey.

N	Category of Logger	Type of Logger	Expansion Name	Logger ID	ID Date	Firmware ...	Firmware Date
1	MASTER	EVO4	Master	12345	06/09/2008	43.01.06	08/09/2008
2	CAN EXPANSION	DaVid	LC	47111881	18/01/2008	22.03	09/11/2007
3	CAN EXPANSION	LCU-ONE	LC	1111111	13/12/2007	25.09	19/11/2007
4	CAN EXPANSION	GPS		902499	14/01/2008	35.13	17/12/2007
5	CAN EXPANSION	MEMORY KEY		7613105	17/12/2007	37.05	18/12/2007

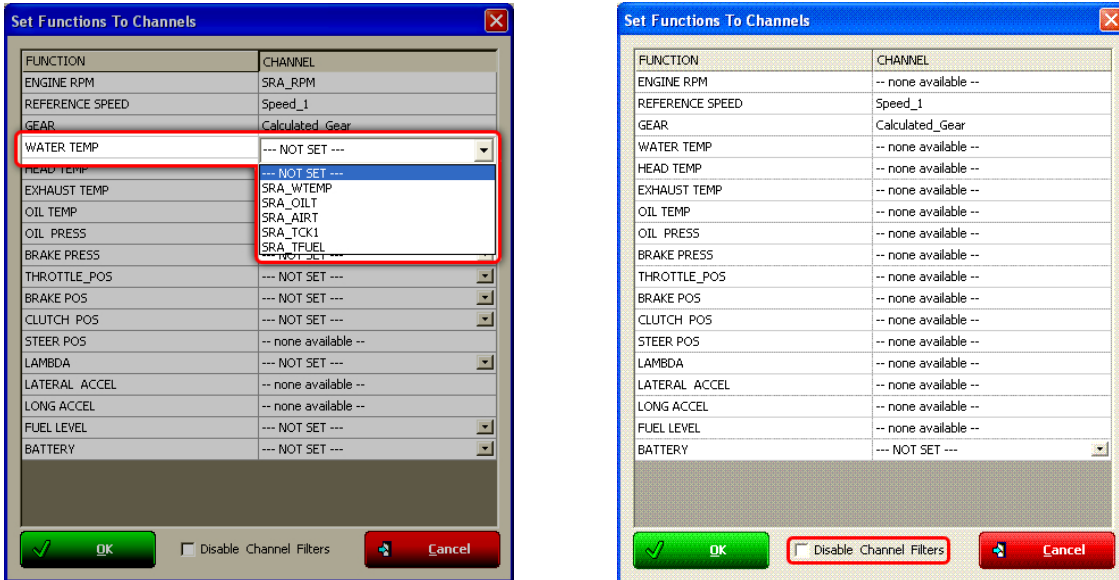
- Set acquisition system time:** makes the logger time matching the PC one. Pressing it “Acquisition system time” window, below on the left, appears with PC clock on the left and EVO3 one on the right. Pressing the central button, PC and EVO3 will have the same time. This operation does not modify data sampled by the logger nor influence its peripherals. In case the window on the right appears it means that PC-logger connection is wrong. Check it and try again.



- SmartyCam functions settings:** allows to set SmartyCam channels. Pressing it the related panel appears. With reference to the images here below, each function available options depends on the fact whether the all network is connected to the vehicle ECU or not. This means that if there is no ECU all functions not managed directly by SmartyCam are shown as “none available” and cannot be set while in case an ECU is available all function supported by that ECU are shown as “Not set” and can be set.



In case an ECU is available it is necessary to decide which channel to associate with each function. With reference to the images here below, for example, to set SmartyCam water temperature channel click on arrow right of the function and a drop down menu opens showing all available temperature channels. Select the one that will be shown on SmartyCam video and press OK. In case the channel is not shown enable “Disable channel filters” checkbox and all available channels will be shown no matter if they are temperature channels or not.



**Current Configuration Table**, immediately under the keyboard, shows the main information concerning the configuration user is working on.

Current configuration									
Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	EVO4 - 5 channels	None - None	DEFAULT	19.10.22 (h.m.s)	8.15.21 (h.m.s)	121 (Hz)	121 (Hz)	0 (Hz)	1

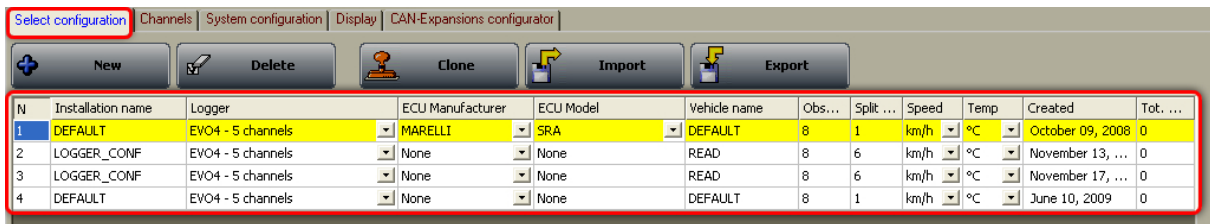
Again, under this table are five layers:



- **Select configuration:** allows the user to select the configuration to work on; it is always active.
- **Channels:** allows to set EVO4 channels. It is active only if there are configurations in “Select configuration” layer.
- **System configuration:** allows to set or modify EVO4 configuration. It is active only if there are configurations in “Select configuration” layer.
- **Display:** allows to set the configuration of EVO4 display. It is active only if there are configurations in “select configuration” layer. Refer to the related chapter for further information concerning AIM displays.
- **CAN-expansions configurator:** allows to configure the expansions connected to EVO4, DaVid Slave video system included. It is active only if there are configurations in “Select configuration” layer; if not, it doesn’t even appear. Refer to the related chapter for further information. **Note:** if the connected expansion is a DaVid Slave Expansion refer to paragraph 8.6 (DaVid master).

### 10.1.1 – Select configuration layer

“Select configuration” layer – shown here below – is made of:



On top is the keyboard made up of five buttons.

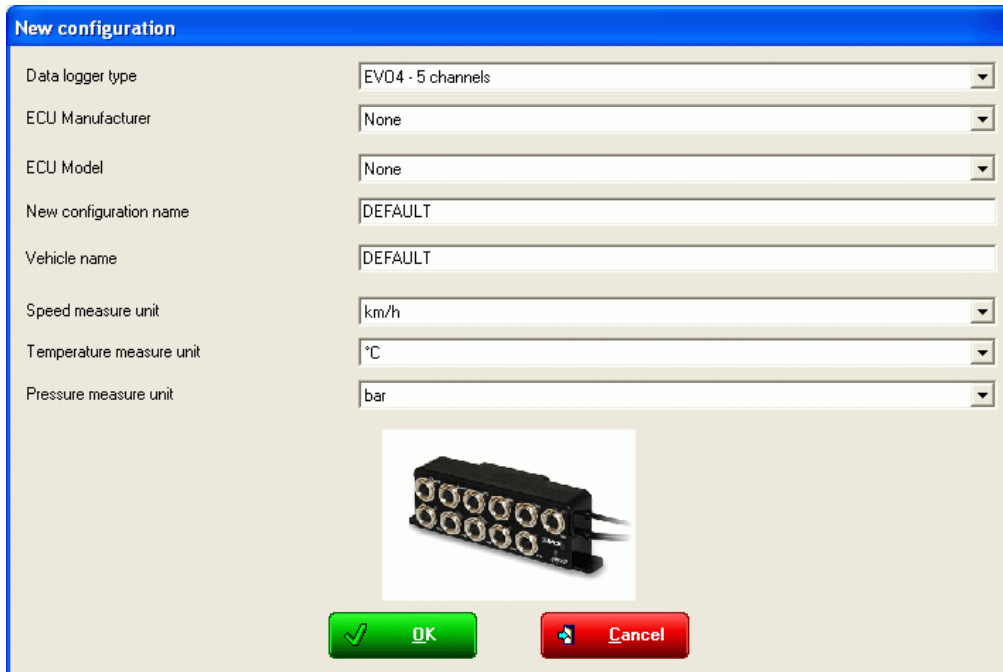
- **New:** creates a new configuration;
- **Delete:** deletes a configuration;
- **Clone:** clones a configuration;
- **Import:** imports a configuration from a file;
- **Export:** exports a configuration to a file.

**Central** is the available configurations database. To work on one of them click on any of its cell and the entire row is selected (highlighted in yellow).

In case of first configuration central table shows up empty.

## 10.2 – Creating a new configuration

Pressing “New” button in “Select Configuration” layer this window appears:



Some parameters need to be set:

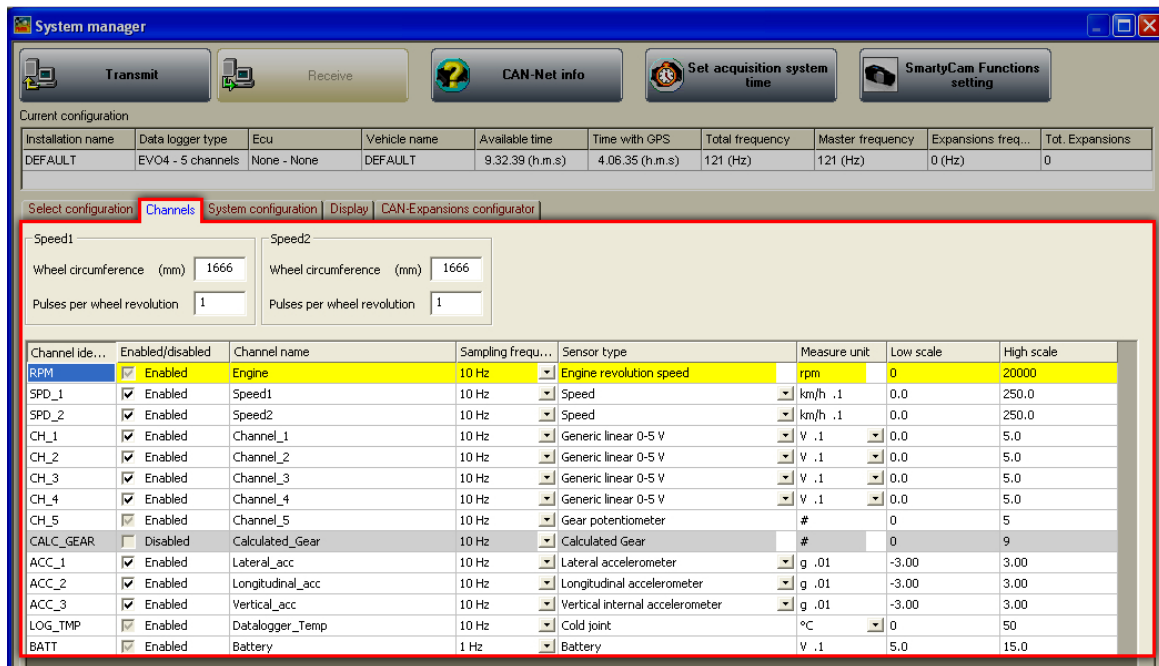
- **Data logger type:** select the logger to be configured.
- **ECU Manufacturer:** select the Manufacturer of the ECU installed on the vehicle if supported or none.
- **ECU Model:** select the ECU model.
- **New configuration name:** fill in the new configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Speeds unit of measure:** choose between km/h and mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (or “Cancel” to quit without saving).  
The system comes back to system manager window.



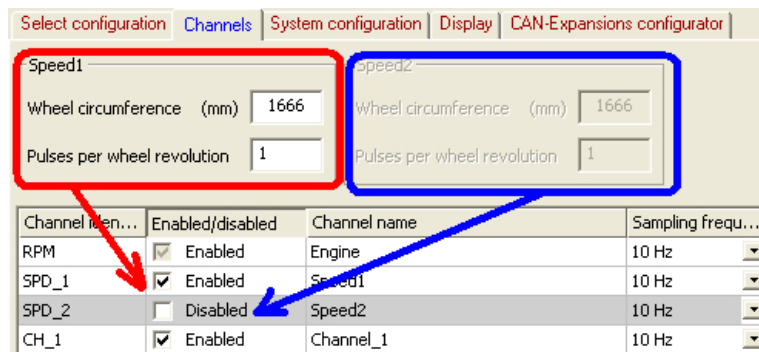
## 10.3 – Channels

Activate “Channels” layer.



### 10.3.1 – Speed panels

On top of Channels layer are Speed panels. They can be enabled/disabled through the channel table below. To enable a Speed channel enable the checkbox in the corresponding row of channel table. Below figure shows one Speed channel enabled and one disabled.



When a panel is enabled it is necessary to set its parameters.

Speed1

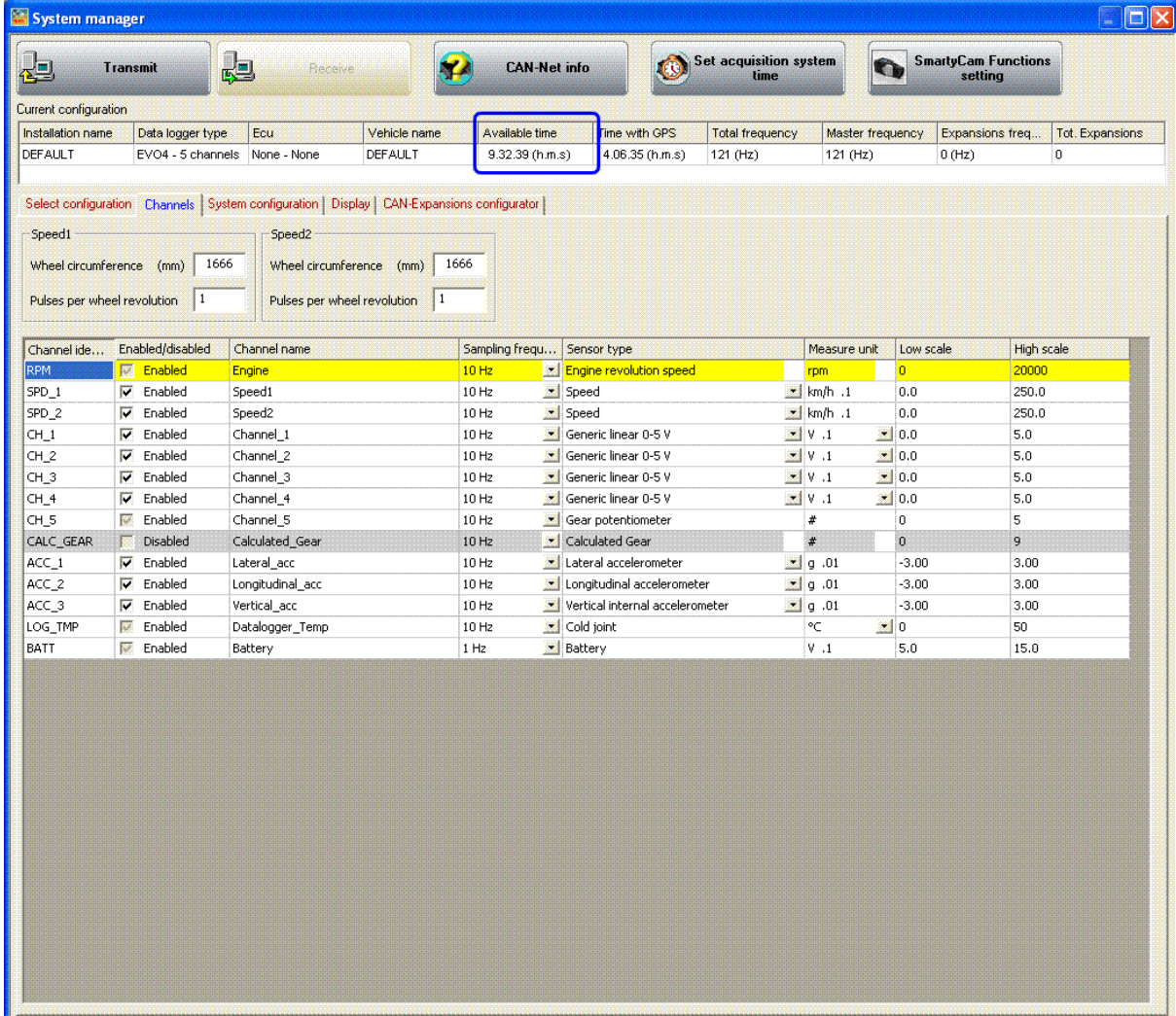
Wheel circumference (mm)

Pulses per wheel revolution

Fill in:

- wheel circumference of the vehicle;
- number of pulses for wheel revolution (that corresponds to the number of magnets installed on the wheel).

### 10.3.2 – Channel Table



The screenshot shows the 'System manager' window with several tabs: Transmit, Receive, CAN-Net info, Set acquisition system time, and SmartyCam Functions setting. The 'Current configuration' table is visible, with the 'Available time' column highlighted. Below this, there are settings for Speed1 and Speed2, and a large table of logger channels.

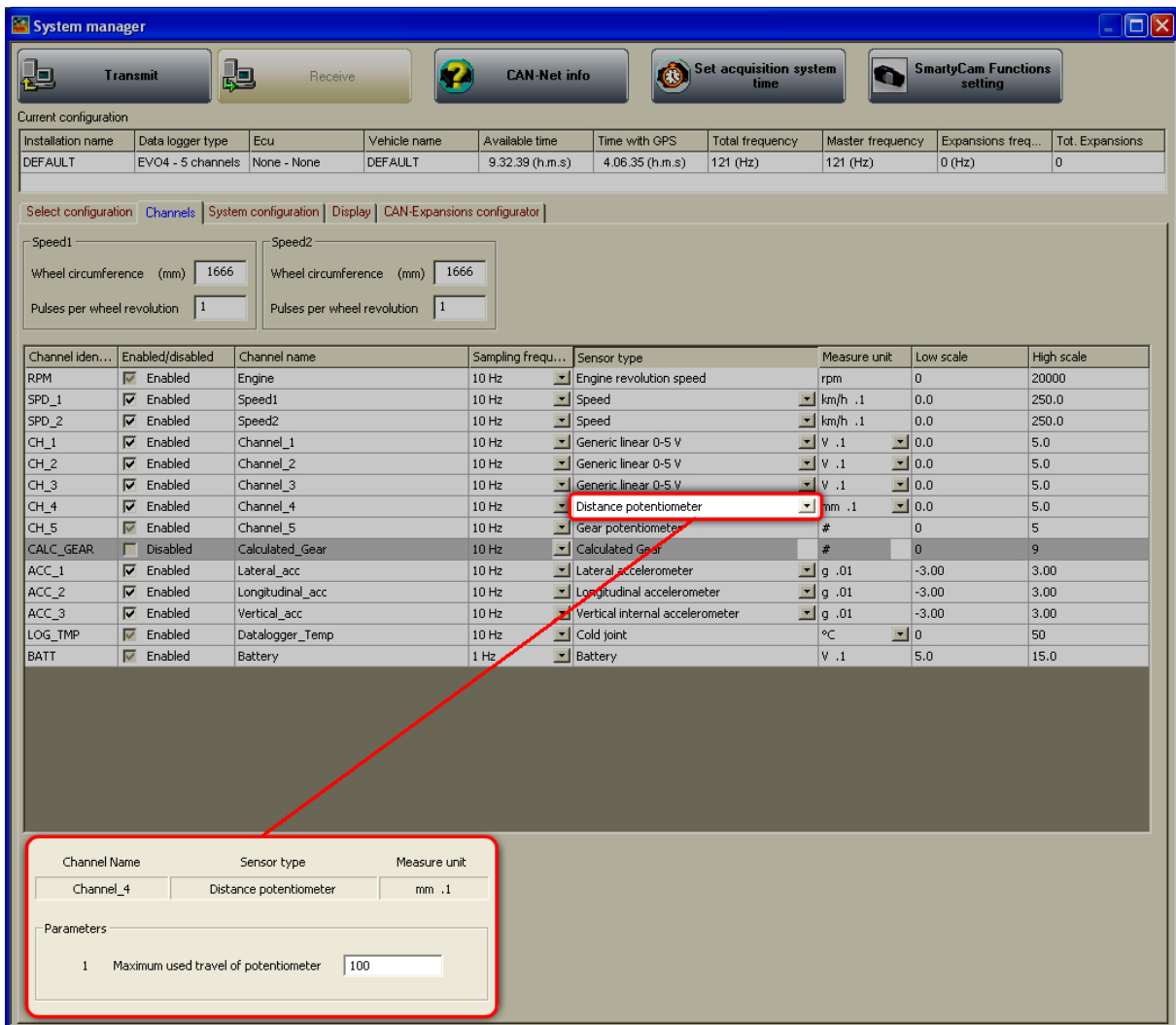
Channel ide...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
RPM	<input checked="" type="checkbox"/> Enabled	Engine	10 Hz	Engine revolution speed	rpm	0	20000
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed1	10 Hz	Speed	km/h .1	0.0	250.0
SPD_2	<input checked="" type="checkbox"/> Enabled	Speed2	10 Hz	Speed	km/h .1	0.0	250.0
CH_1	<input checked="" type="checkbox"/> Enabled	Channel_1	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_2	<input checked="" type="checkbox"/> Enabled	Channel_2	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_3	<input checked="" type="checkbox"/> Enabled	Channel_3	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_4	<input checked="" type="checkbox"/> Enabled	Channel_4	10 Hz	Generic linear 0-5 V	V .1	0.0	5.0
CH_5	<input checked="" type="checkbox"/> Enabled	Channel_5	10 Hz	Gear potentiometer	#	0	5
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	10 Hz	Calculated Gear	#	0	9
ACC_1	<input checked="" type="checkbox"/> Enabled	Lateral_acc	10 Hz	Lateral accelerometer	g .01	-3.00	3.00
ACC_2	<input checked="" type="checkbox"/> Enabled	Longitudinal_acc	10 Hz	Longitudinal accelerometer	g .01	-3.00	3.00
ACC_3	<input checked="" type="checkbox"/> Enabled	Vertical_acc	10 Hz	Vertical internal accelerometer	g .01	-3.00	3.00
LOG_TMP	<input checked="" type="checkbox"/> Enabled	Datalogger_Temp	10 Hz	Cold joint	°C	0	50
BATT	<input checked="" type="checkbox"/> Enabled	Battery	1 Hz	Battery	V .1	5.0	15.0

It shows all logger channels with the related characteristics

- **Channel identifier:** shows the channel label. Channels labelled “ECU\_X” are the ones received from the ECU.
- **Enabled/disabled:** shows channel status (enabled or disabled). The status can be modified double clicking on the cell except for RPM, Speed and CH\_5; RPM and CH\_5 needs to be set through “System Configuration” panel, while Speed one is to be set as explained before.
- **Channel name:** names the channel.
- **Sampling frequency:** sets each channel sampling frequency. This last one influences the total available time, highlighted by a box in the figure below, because the memory fills up faster.
- **Sensor type:** shows the type of sensor installed on that channel; it is selected through the drop down menu that appears clicking on the cell. See the following page for further information.
- **Measure unit:** shows the unit of measure selected for each channel; to change it double click on the cell.
- **Low/High scale:** shows high/low scale values of the sensor and allows to change it double clicking on the cell.

	Temperatures	Pressures	Potentiometers	Lambda Probe	Gyroscope	Accelerometer
<b>EVO3 Pista</b>						
Ch_1	X	X	X	X		
Ch_2	X	X	X	X		
Ch_3	X	X	X	X		
Ch_4	X	X	X	X	X	X
Ch_5 <sup>7</sup>	X	X	X	X	X	X

Setting some sensors on some channels that support them, a configuration panel appears bottom left of Channels layer. The figure below shows distance potentiometer configuration panel.



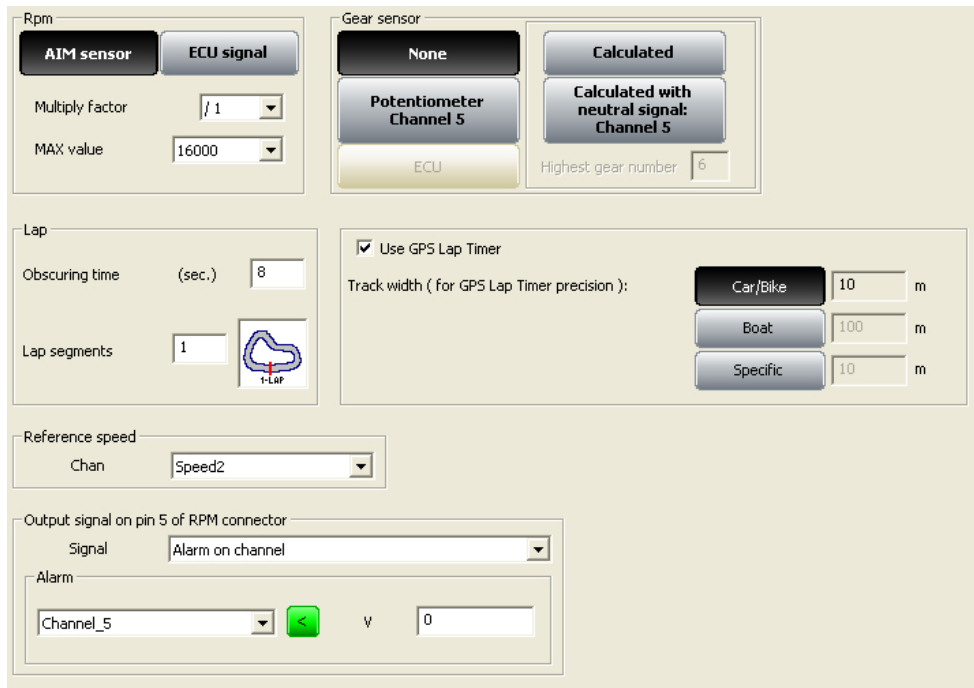
<sup>7</sup> Channel CH\_5 is the gear channel and if system configuration layer (paragraph 10.5) sets it on "Potentiometer CH\_5" row labelled CH\_5 sets on Gear Potentiometer. If it is set on "Calculated + Neutral Signal" channel CH\_5 sets on. In all the other cases it works as shown in the table above. When the setting is "Calculated gear" CH\_5 needs to be enabled and then it works as shown in the table above.

## 10.4 – Creating a custom sensor

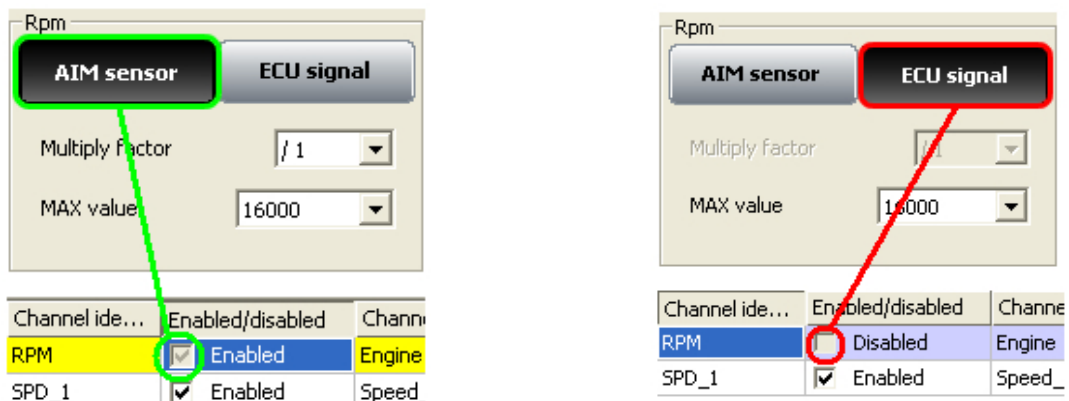
The procedure to create a custom sensor is the same for all AIM loggers. Refer to chapter 12 for further information.

## 10.5 – System configuration

Activate “System Configuration” layer:



### 10.5.1 – RPM box



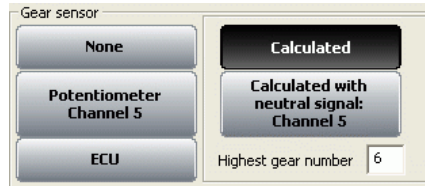
Channel ide...	Enabled/disabled	Channe
RPM	<input checked="" type="checkbox"/> Enabled	Engine
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_

Channel ide...	Enabled/disabled	Channe
RPM	<input type="checkbox"/> Disabled	Engine
SPD_1	<input checked="" type="checkbox"/> Enabled	Speed_

- Select “**AIM Sensor**” to sample this information from an RPM sensor installed on the vehicle. Set Multiply factor and RPM Max value. RPM row in the central table of channels layer enables.
- Select “**ECU signal**” and set RPM Max value to sample this information from the vehicle ECU. RPM row in the central table of channel layer disables.

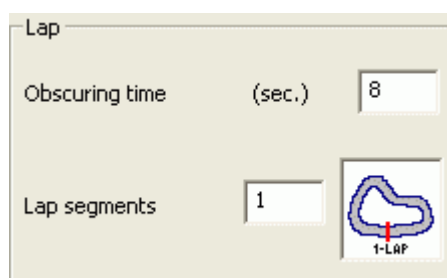
### 10.5.2 – Gear sensor box



**EVO4** can sample the engaged gear from a gear sensor or from the ECU. It can also calculate it using an algorithm based on RPM and speed. Available options are:

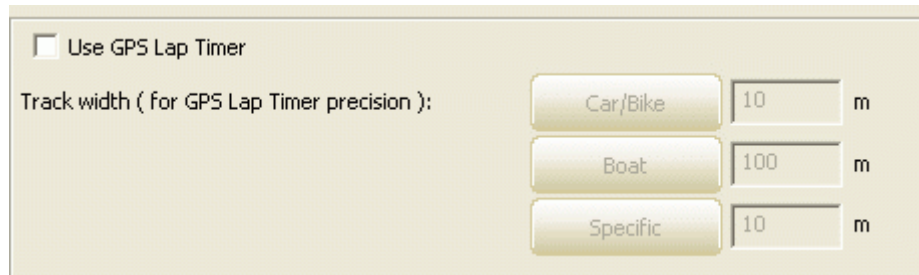
- **None:** there is no gear sensor on the vehicle (or not to see the engaged gear): this option is disabled on the display. Row labelled CH\_5 in central table of channel layer can be enabled with configurable sensor.
- **Potentiometer Channel 5:** there is a gear potentiometer installed on channel 5; row labelled CH\_5 in the central table of channels layer is enabled and set on gear potentiometer.
- **ECU:** this information is sampled from the ECU (assuming it can transmit it); row labelled CH\_5 in the central table of channels layer is disabled and can be enabled with configurable sensor.
- **Calculated:** to calculate the engaged gear with an algorithm based on RPM and speed; fill in “Highest gear number”. Row labelled CH\_5 in the central table of channels layer can be enabled with configurable sensor. Refer to chapter 15 for further information.
- **Calculated + neutral signal:** Channel 5: there is a neutral sensor that can be used to both see neutral gear and calculate the engaged gear. Fill in “Highest gear number”. The central table of channel layer shows row labelled CH\_5 enabled and set on calculated gear. See the related chapter for further information.

### 10.5.3 – Lap box

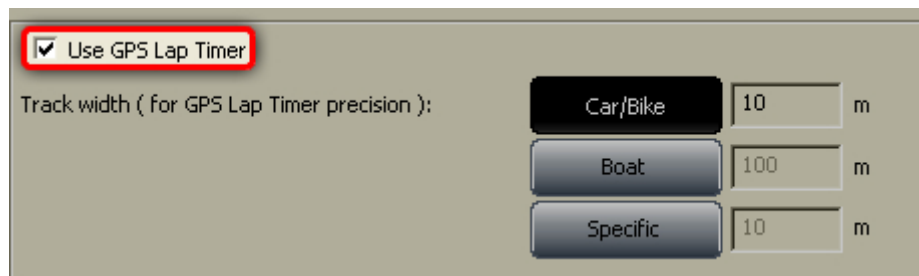


- **Obscuring time:** it is a time period during which the optical receiver installed on the vehicle, after having recorded a lap signal, is “blind”: it does not record signals. This function is useful to manage split times on tracks where more optical receivers are installed: set obscuring time on a low value (min accepted value is 3 seconds) to record splits and set it on a value lower than best lap time and higher than the time elapsed between last split and start/finish line (max accepted value is 255 seconds) not to record splits.
- **Lap segments:** is the number of segments the track is divided in and corresponds to the number of transmitters installed there.

### 10.5.4 – Use GPS Lap timer box



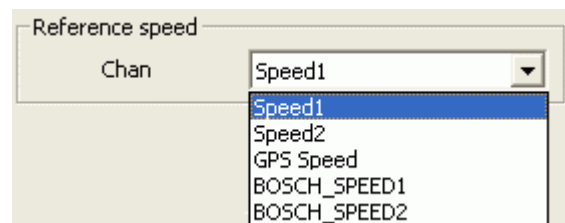
**EVO4** can sample lap time also through the integrated GPS. This function needs to be enabled through the proper checkbox as shown in the figure below.



It allows to use GPS lap timer in spite of the track beacon equipment. It is necessary to enable the corresponding checkbox and set the track width. Available options are:

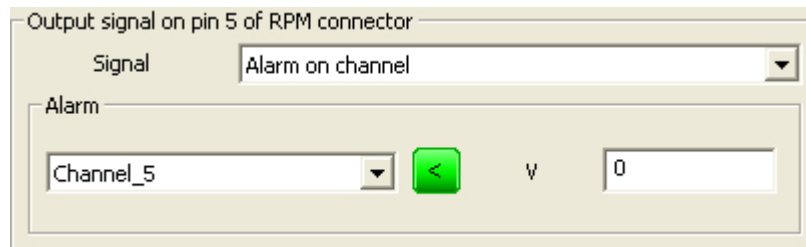
- Car/Bike and Boat whose measures are set by default and
- specific that allows to set a specific track width.

### 10.5.5 –Reference speed box



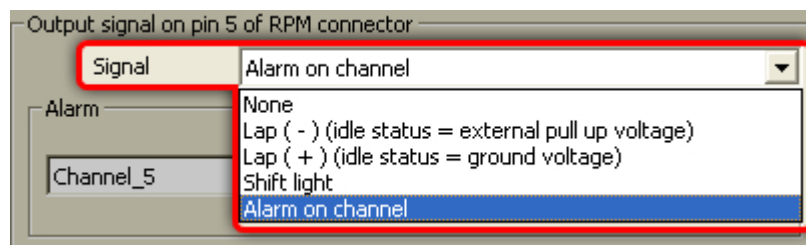
It is possible to select the reference speed used for gear calculation and for some Race Studio Analysis calculation. Available option are the logger speed(s) (depending on how many have been enabled), GPS Speed and ECU speed(s). In the figure above the logger has two enabled speeds and is connected to a Bosch ECU that transmits two speed channels.

### 10.5.6 – Output signal on pin 5 of RPM connector



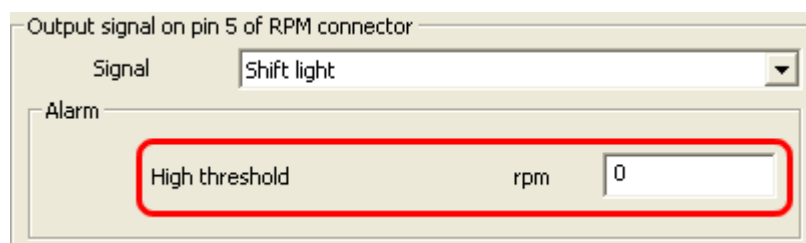
This function allows **EVO4** to send a signal to an external device, typically a display or an ECU. This output signal is connected to pin 5 of RPM connector of **EVO4** and has the following characteristics:

- **Voltage:** Depends on the external pull-up voltage
- **Output duration:** about 0,8 seconds [for Lap (-) and Lap (+) only]
- **Type:** can be type “Lap” or type “Alarm”.

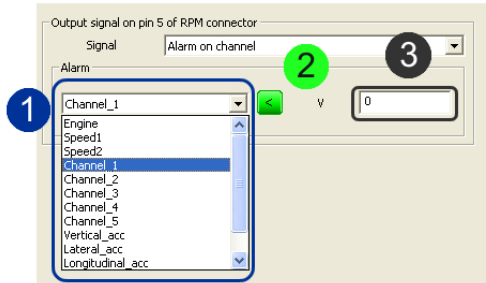


Available options are:

- **None:** signal disabled.
- **Lap (-) (idle status = external pull up voltage):** when EVO3 Pro receives a lap signal, the signal emitted decreases from pull-up voltage (idle status) to 0V (lap) for about 0,8 seconds.
- **Lap (+) (idle status = ground voltage):** when EVO3 Pro receives a lap signal, the signal emitted grows from 0V (idle status) to pull-up (lap) voltage for around 0,8 seconds.
- **Shift lights:** when RPM are over threshold value, the signal emitted grows from 0V (OFF status) to pull-up voltage (ON status) for the time period the threshold value is overcome. This function can be useful to switch on an alarm led on the display. Fill in the proper case highlighted in the figure below.



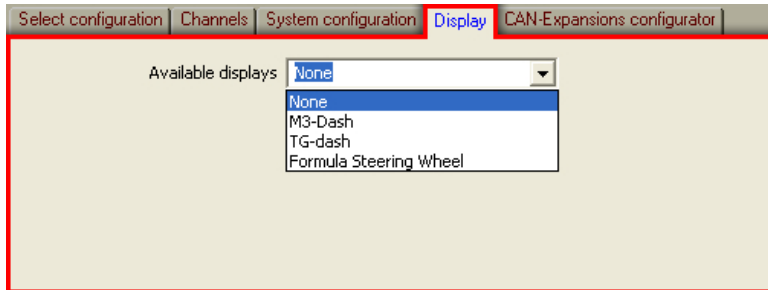
- **Alarm on channel:** starts up an alarm when a fixed threshold value is reached. With reference to the image below on the left, to enable this option select the channel where to set the alarm on (1), set it as max/min alarm clicking the central button (2) and fill in its threshold value (3). The image on the right shows the alarm set: an alarm switches on when Engine (1) RPM is higher (2) than 8000 (3).





## 10.6 – How to configure EVO4 displays

**EVO4** available displays are: **MyChron3 Dash**, **TG-Dash** and **Formula Steering Wheel**. To configure the display (optional to the logger) activate the related layer:



The first time the layer shows up empty. Select the proper display through the drop down menu. Refer to chapter 17 for further information.

## 10.7 – Configuring CAN expansions

**EVO4**, can be connected to numerous expansions that communicate with it through the CAN bus. See chapter 16 for further information.

**Note:** in case the expansion is a DaVid Slave refer to paragraph 8.6 (**DaVid** master) for information concerning its configuration.

## 10.8 – Transmitting the configuration

The procedure to transmit the configuration to the logger is the same for all AIM loggers. Refer to chapter 16 for further information.

## 10.9 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate gear sensor, mid zero and zero based potentiometer. See the related chapter for further information.

**Warning:** if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. Pay attention to sensors calibration/auto-calibration procedures.

## 10.10 – Gear calculation

For **EVO4** to calculate Gear it is just sufficient to enter the track and start running. It is strongly suggested to engage all gears, keep each gear engaged for at least 5/6 seconds and drive in a smooth way (avoiding sudden accelerations or wheels blocks during brakes). The system will calculate the engaged gear and it will appear on the proper field of the display.

## 10.11 – Online

Online function is very useful to check the logger proper working. Refer to chapter 18 for further information.

## Chapter 11 – How to configure SMC Bridge

To correctly configure **SMC Bridge (ECU Bridge and RPM Bridge)**, use a PC and **Race Studio 2** software. These devices can only be configured via software.

Before starting the configuration, install **Race Studio 2** and the USB driver as explained in chapter 2.

Run the software, clicking on **Race Studio 2** icon and the window here below appears.



In the title bar – white on blue background in the figure – you can see the **Race Studio 2** version installed on the PC. Immediately under is the menu bar, shown in a more intuitive way on the left thanks to the graphic buttons: Go to analysis (this button runs Race Studio Analysis software), Data download, AIM system manager, AIM system identification, Online, AIM system calibration, Custom sensors management, Select language.

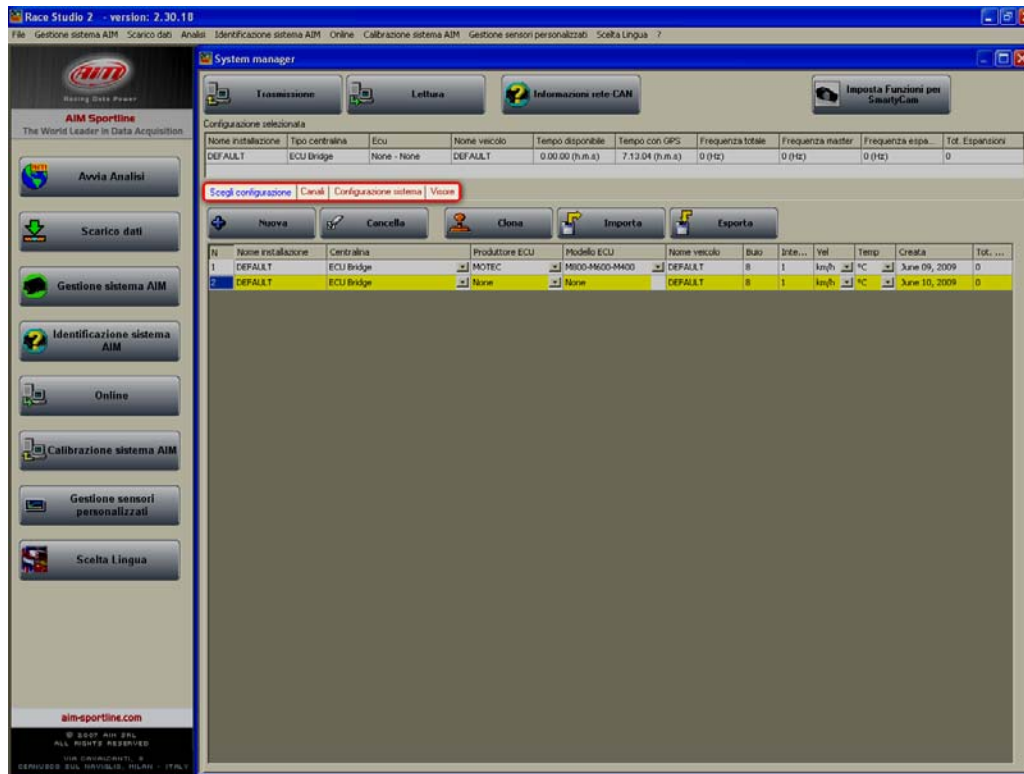
From this window it is possible to perform all needed operations to manage all AIM systems.

To enter configuration menu press “AIM system manager button; a panel showing all systems managed through **Race Studio 2** software appears: double click on “**SMC Bridge**” or select it and click “✓Go to”.



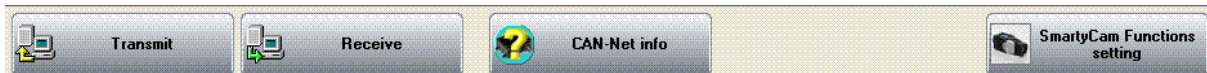
Race Studio 2 system manager window appears.

## 11.1 – System Manager window

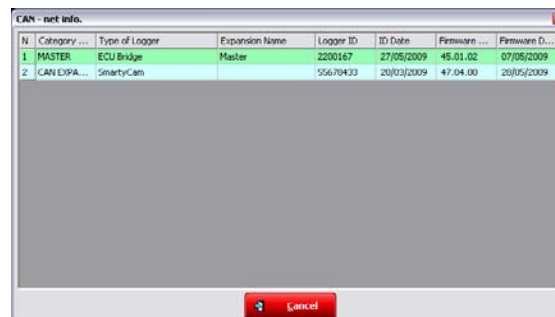


Using the keyboard and the layers, highlighted in the figure, it is possible to perform all operations necessary to manage an AIM system.

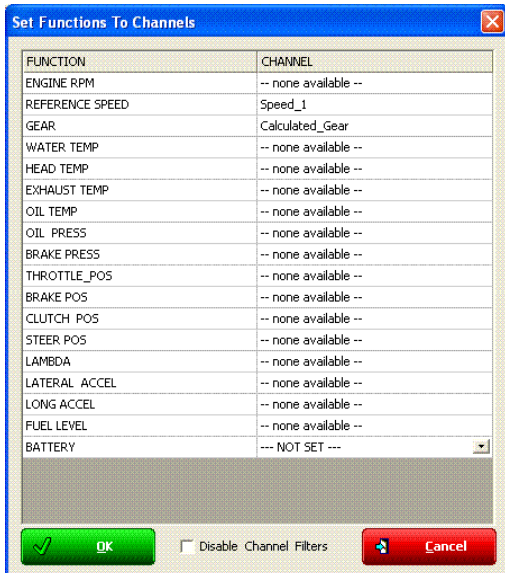
The top keyboard, shown here below, is made up of four buttons.



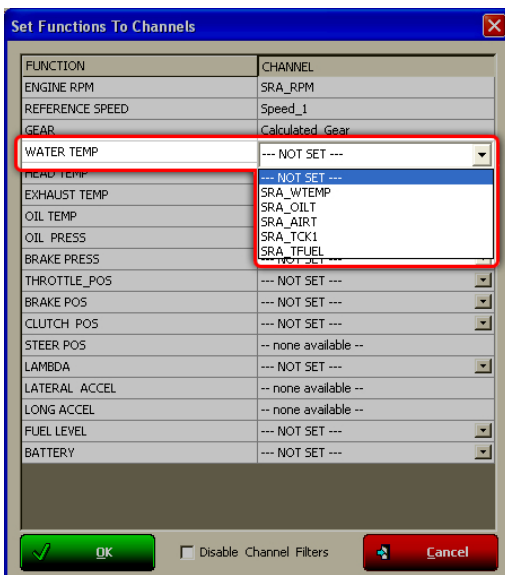
- **Transmit:** transmits a configuration to the logger and is active with any layer; it needs the logger to be switched on and connected to the PC.
- **Receive:** reads and saves the configuration of the logger and is active only in “select configuration” layer.
- **CAN-Net info:** identifies the CAN network connected to the PC, that means the logger and its peripherals. Pressing it a waiting window appears and – when once the connection established – “CAN-Net info” window appears. In the example below the CAN network includes an ECU Bridge Master and SmartyCam slave version as expansion.



- SmartyCam functions settings:** allows to set **SmartyCam** channels and is only useful for **ECU Bridge**. Pressing it the related panel appears. It shows all function supported by the Engine Control Unit ECU Bridge is connected as “Not set” and they can be set.



It is necessary to decide which channel to associate with each function. With reference to the images here below, for example, to set SmartyCam water temperature channel click on arrow right of the function and a drop down menu opens showing all available temperature channels. Select the one that will be shown on **SmartyCam** video and press OK. In case the channel is not shown it is possible to enable “Disable channel filters” checkbox and all available channels will be shown no matter if they are temperature channels or not.



**Current Configuration Table**, immediately under the keyboard, shows the main information concerning the configuration user is working on.

Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	ECU Bridge	MOTEC - M800-M...	DEFAULT	0.00.00 (h.m.s)	7.13.04 (h.m.s)	0 (Hz)	0 (Hz)	0 (Hz)	0

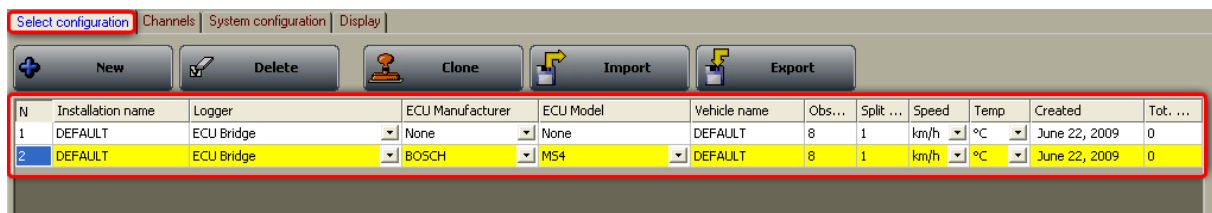
Again, under this table are four layers:



- **Select configuration:** allows the user to select the configuration to work on; it is always active.
- **Channels:** sets **ECU Bridge/RPM** channels. It is active only if there are configurations in “Select configuration” layer.
- **System configuration:** to set **ECU Bridge/RPM Bridge** configuration. It is active only if there are configurations in “Select configuration” layer.
- **Display:** allows to set the configuration of **ECU Bridge/RPM Bridge** display. It is active only if there are configurations in “Select configuration” layer. Refer to the related chapter for further information concerning AIM displays.

### 11.1.1 – Select configuration layer

“Select configuration” layer – shown here below – is made of:



On top is the keyboard made up of five buttons.

- **New:** creates a new configuration;
- **Delete:** deletes a configuration
- **Clone:** clones a configuration
- **Import:** imports a configuration from a file;
- **Export:** exports a configuration to a file.

**Central** is the available configurations database. To work on one of them click on any of its cell and the entire row is selected (highlighted in yellow).

In case of first configuration central table shows up empty.

## 11.2 – Creating a new configuration

Pressing “New” button in “Select configuration” layer this window appears:



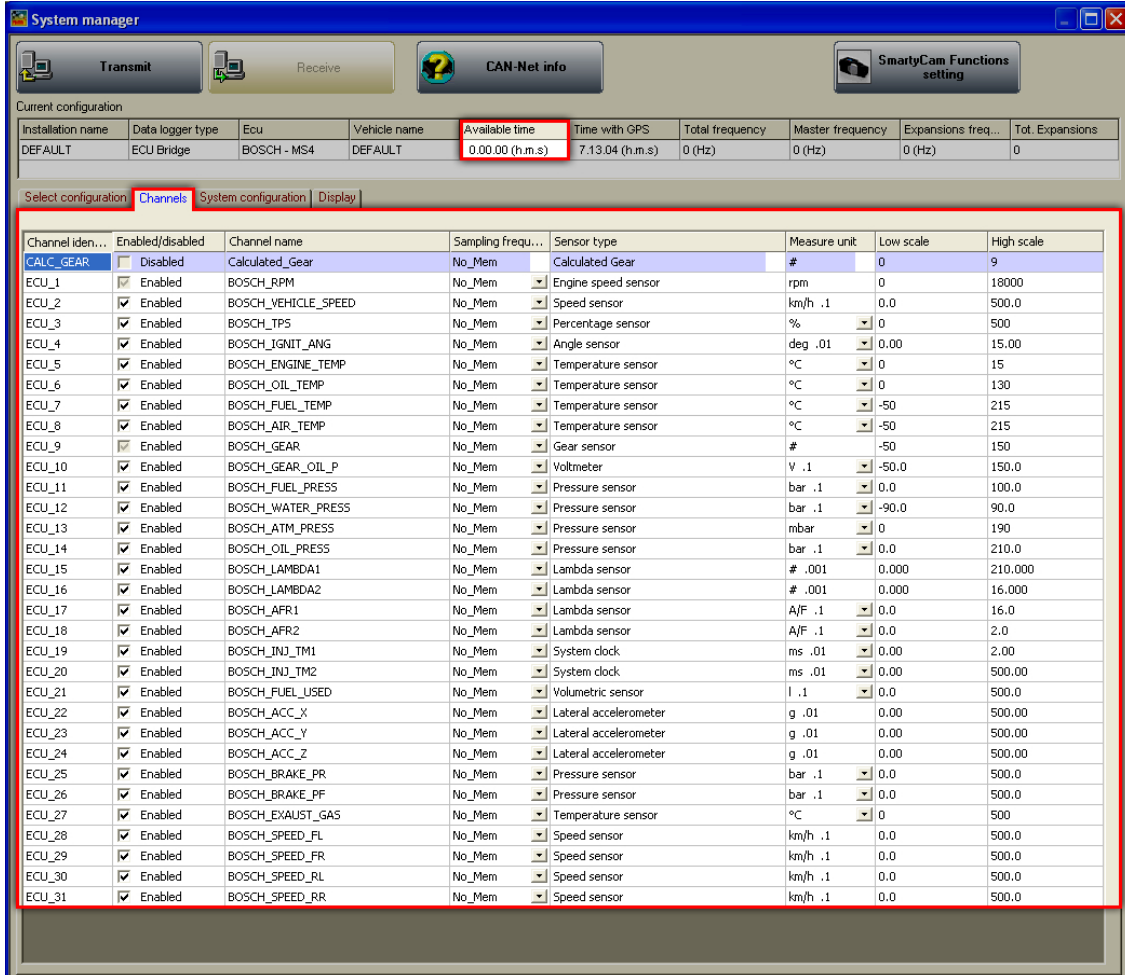
Some parameters need to be set:

- **Data logger type:** select the proper Bridge.
- **ECU Manufacturer:** select the Manufacturer of the ECU installed on the vehicle if supported or none. RPM Bridge has this parameter set on “Not supported”.
- **ECU Model:** select the ECU model. RPM Bridge has this parameter set on “Not supported”.
- **New configuration name:** fill in the new configuration name.
- **Vehicle name:** fill in the vehicle name.
- **Speeds unit of measure:** choose between km/h and mph.
- **Temperatures unit of measure:** choose between °C and °F.
- **Pressures unit of measure:** choose between Bar and PSI.

Press “OK” to save (or “Cancel” to quit without saving).  
The system comes back to system manager window.

## 11.3 – Channels

Activate channels layer. The layer layout depends on the Bridge and on the ECU connected to the interface Module (ECU Bridge only). The image here below shows an **ECU bridge** connected to a Bosch MS4 ECU.



Installation name	Data logger type	Ecu	Vehicle name	Available time	Time with GPS	Total frequency	Master frequency	Expansions freq...	Tot. Expansions
DEFAULT	ECU Bridge	BOSCH - MS4	DEFAULT	0.00.00 (h.m.s)	7.13.04 (h.m.s)	0 (Hz)	0 (Hz)	0 (Hz)	0

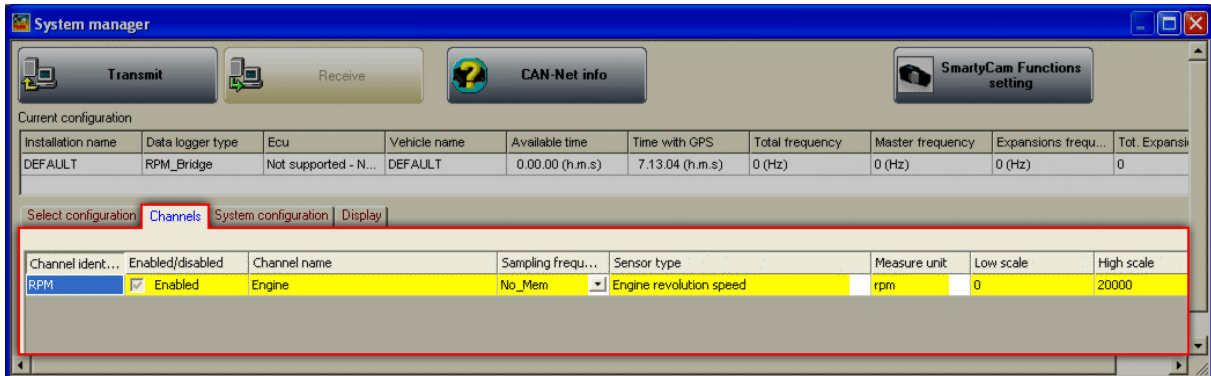
Channel iden...	Enabled/disabled	Channel name	Sampling frequ...	Sensor type	Measure unit	Low scale	High scale
CALC_GEAR	<input type="checkbox"/> Disabled	Calculated_Gear	No_Mem	Calculated Gear	#	0	9
ECU_1	<input checked="" type="checkbox"/> Enabled	BOSCH_RPM	No_Mem	Engine speed sensor	rpm	0	18000
ECU_2	<input checked="" type="checkbox"/> Enabled	BOSCH_VEHCLE_SPEED	No_Mem	Speed sensor	km/h .1	0.0	500.0
ECU_3	<input checked="" type="checkbox"/> Enabled	BOSCH_TP5	No_Mem	Percentage sensor	%	0	500
ECU_4	<input checked="" type="checkbox"/> Enabled	BOSCH_IGNIT_ANGLE	No_Mem	Angle sensor	deg .01	0.00	15.00
ECU_5	<input checked="" type="checkbox"/> Enabled	BOSCH_ENGINE_TEMP	No_Mem	Temperature sensor	°C	0	15
ECU_6	<input checked="" type="checkbox"/> Enabled	BOSCH_OIL_TEMP	No_Mem	Temperature sensor	°C	0	130
ECU_7	<input checked="" type="checkbox"/> Enabled	BOSCH_FUEL_TEMP	No_Mem	Temperature sensor	°C	-50	215
ECU_8	<input checked="" type="checkbox"/> Enabled	BOSCH_AIR_TEMP	No_Mem	Temperature sensor	°C	-50	215
ECU_9	<input checked="" type="checkbox"/> Enabled	BOSCH_GEAR	No_Mem	Gear sensor	#	-50	150
ECU_10	<input checked="" type="checkbox"/> Enabled	BOSCH_GEAR_OIL_P	No_Mem	Voltmeter	V .1	-50.0	150.0
ECU_11	<input checked="" type="checkbox"/> Enabled	BOSCH_FUEL_PRESS	No_Mem	Pressure sensor	bar .1	0.0	100.0
ECU_12	<input checked="" type="checkbox"/> Enabled	BOSCH_WATER_PRESS	No_Mem	Pressure sensor	bar .1	-90.0	90.0
ECU_13	<input checked="" type="checkbox"/> Enabled	BOSCH_ATM_PRESS	No_Mem	Pressure sensor	mbar	0	190
ECU_14	<input checked="" type="checkbox"/> Enabled	BOSCH_OIL_PRESS	No_Mem	Pressure sensor	bar .1	0.0	210.0
ECU_15	<input checked="" type="checkbox"/> Enabled	BOSCH_LAMBDA1	No_Mem	Lambda sensor	# .001	0.000	210.000
ECU_16	<input checked="" type="checkbox"/> Enabled	BOSCH_LAMBDA2	No_Mem	Lambda sensor	# .001	0.000	16.000
ECU_17	<input checked="" type="checkbox"/> Enabled	BOSCH_AFR1	No_Mem	Lambda sensor	A/F .1	0.0	16.0
ECU_18	<input checked="" type="checkbox"/> Enabled	BOSCH_AFR2	No_Mem	Lambda sensor	A/F .1	0.0	2.0
ECU_19	<input checked="" type="checkbox"/> Enabled	BOSCH_INJ_TM1	No_Mem	System clock	ms .01	0.00	2.00
ECU_20	<input checked="" type="checkbox"/> Enabled	BOSCH_INJ_TM2	No_Mem	System clock	ms .01	0.00	500.00
ECU_21	<input checked="" type="checkbox"/> Enabled	BOSCH_FUEL_USED	No_Mem	Volumetric sensor	l .1	0.0	500.0
ECU_22	<input checked="" type="checkbox"/> Enabled	BOSCH_ACC_X	No_Mem	Lateral accelerometer	g .01	0.00	500.00
ECU_23	<input checked="" type="checkbox"/> Enabled	BOSCH_ACC_Y	No_Mem	Lateral accelerometer	g .01	0.00	500.00
ECU_24	<input checked="" type="checkbox"/> Enabled	BOSCH_ACC_Z	No_Mem	Lateral accelerometer	g .01	0.00	500.00
ECU_25	<input checked="" type="checkbox"/> Enabled	BOSCH_BRAKE_PR	No_Mem	Pressure sensor	bar .1	0.0	500.0
ECU_26	<input checked="" type="checkbox"/> Enabled	BOSCH_BRAKE_PF	No_Mem	Pressure sensor	bar .1	0.0	500.0
ECU_27	<input checked="" type="checkbox"/> Enabled	BOSCH_EXHAUST_GAS	No_Mem	Temperature sensor	°C	0	500
ECU_28	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED_FL	No_Mem	Speed sensor	km/h .1	0.0	500.0
ECU_29	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED_FR	No_Mem	Speed sensor	km/h .1	0.0	500.0
ECU_30	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED_RL	No_Mem	Speed sensor	km/h .1	0.0	500.0
ECU_31	<input checked="" type="checkbox"/> Enabled	BOSCH_SPEED_RR	No_Mem	Speed sensor	km/h .1	0.0	500.0

It shows all logger channels with the related characteristics

- **Channel identifier:** shows the channel label. Channels labelled “ECU\_X” are the ones received from the ECU.
- **Enabled/disabled:** shows channel status (enabled or disabled). The status can be modified double clicking on the cell except for RPM and Gear. This last one needs to be set through “System Configuration” panel.
- **Channel name:** allows to name the channel.
- **Sampling frequency:** allows to set each channel sampling frequency. This last one influences the total available time, highlighted in the below figure, because the memory fills up faster.
- **Sensor type:** shows the type of sensor installed on that channel.
- **Measure unit:** shows the unit of measure selected for each channel; to change it double click on the cell.
- **Low/High scale:** shows high/low scale values of the sensor and allows to change it double clicking on the cell.



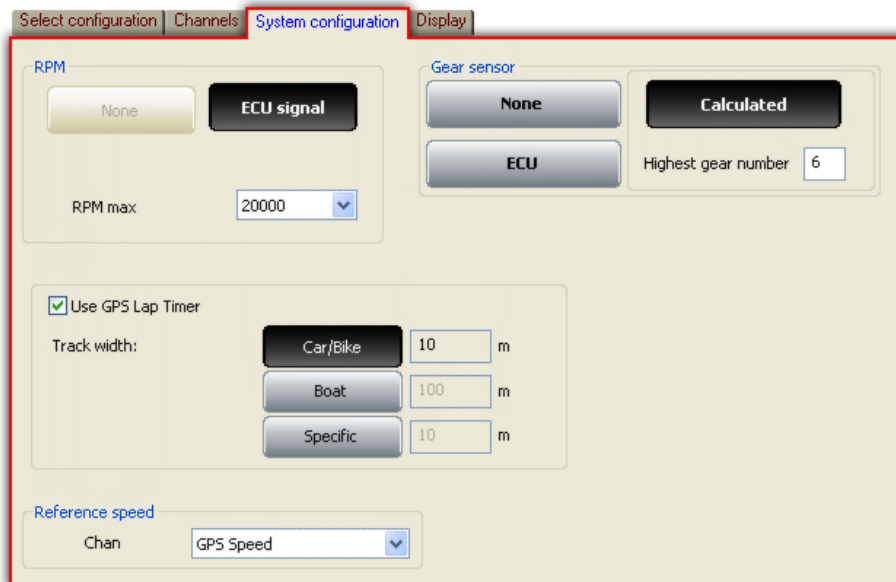
“RPM Bridge” channel layer is shown here below.



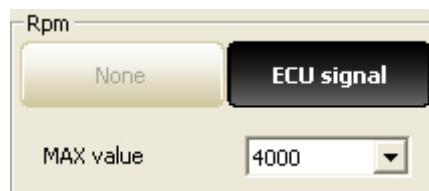
It is only possible to set “Channel Name”, “Low scale” and “High scale”.

## 11.4 – System configuration – ECU Bridge

Activate “System configuration” layer

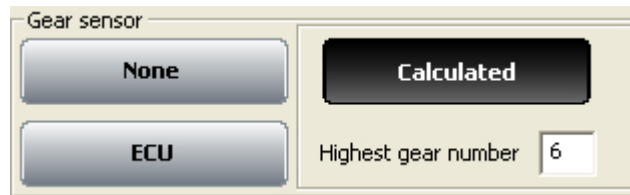


### 11.4.1 – RPM box



It is set on “**ECU signal**” by default: fill in RPM Max value.

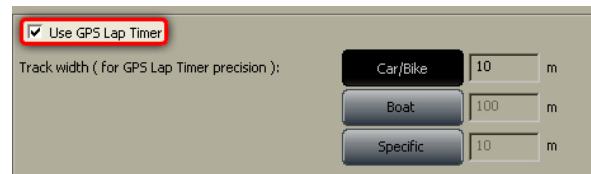
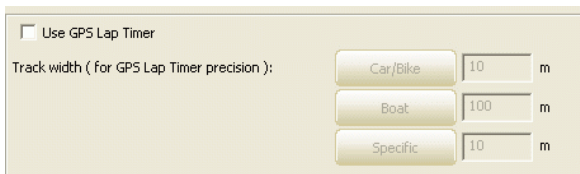
### 11.4.2 – Gear sensor box



Available options are:

- **None:** not to see the engaged gear.
- **ECU:** this information is sampled from the ECU.
- **Calculated:** to calculate the engaged gear with an algorithm based on RPM and speed; fill in “Highest gear number”

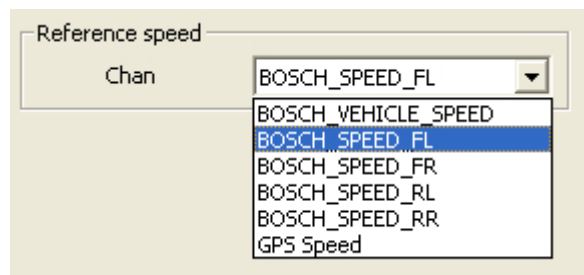
### 11.4.3 – Use GPS Lap timer box



**ECU Bridge** can sample lap time also through the GPS integrated in **SmartyCam**. This function needs to be enabled through the proper checkbox as shown in the figure below. Available options are:

- Car/Bike and Boat whose measures are set by default and
- specific that allows to set a specific track width.

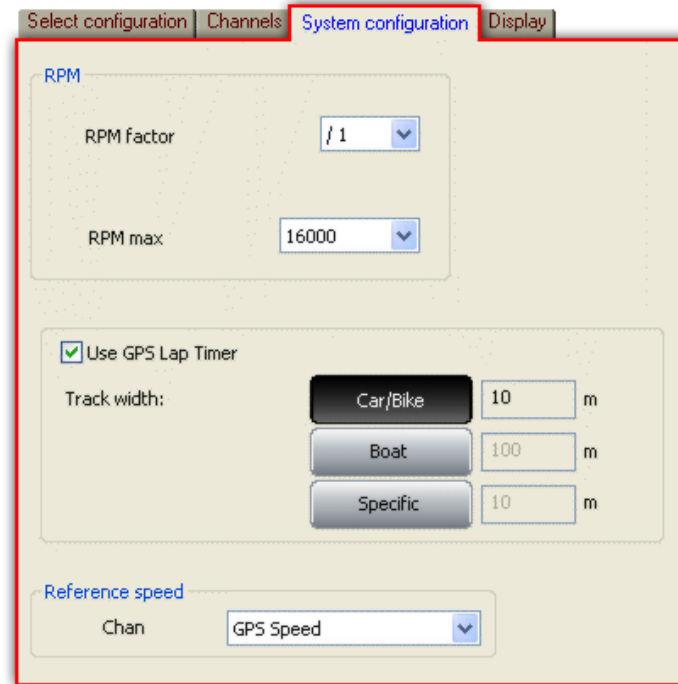
### 11.4.4 –Reference speed box



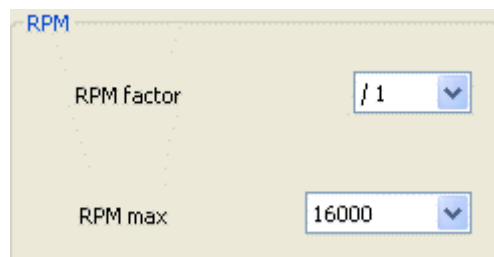
It is possible to select the reference speed used for gear calculation and for some Race Studio Analysis calculation. Available options are the speeds the ECU transmits and GPS Speed if enabled. In the figure above ECU Bosch MS4 transmits: vehicle speed, front left wheel speed (FL), front right wheel speed (FR), rear left wheel speed (RL), rear right (RR) wheel speed.

## 11.5 System Configuration – RPM Bridge

Active “System Configuration” layer. This window appears

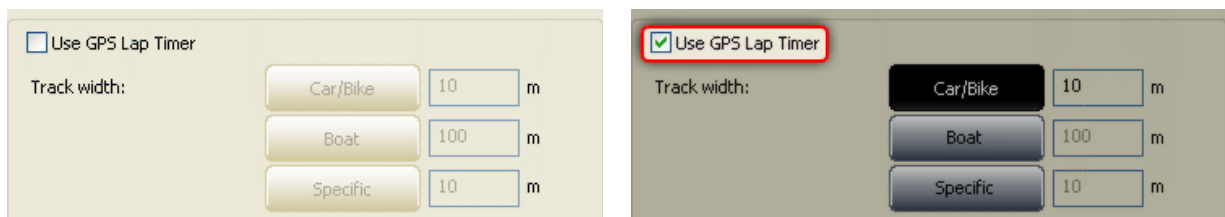


### 11.5.1 – RPM Box



Select the RPM factor from the drop down menu and fill in RPM Max value.

### 11.5.2 – Use GPS Lap time box

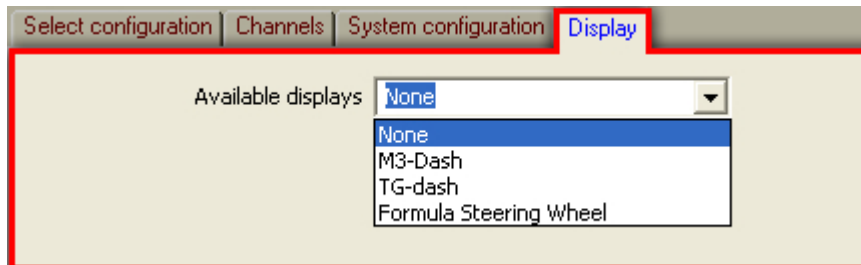


**SMC Bridge** can sample lap time through the GPS integrated in **SmartyCam**. This function needs to be enabled through the proper checkbox as shown in the figure below. Available options are:

- Car/Bike and Boat whose measures are set by default and
- specific that allows to set a specific track width.

## 11.6 – How to configure ECU Bridge/RPM Bridge displays

**ECU Bridge** and **RPM Bridge** can be connected to three displays (optional): **MyChron3 Dash**, **TG-Dash** and **Formula Steering wheel**. Activate the related layer (highlighted here below):



The first time the layer shows up empty. Select the proper display through the drop down menu. Refer to chapter 17 for further information.

## 11.7 – Transmitting the configuration

The procedure to transmit the configuration is the same for all AIM instruments. Refer to chapter 13 for further information.

## 11.8 – Gear calculation

For **ECU Bridge** to calculate Gear it is just sufficient to enter the track and start running. It is strongly suggested to engage all gears, keep each gear engaged for at least 5/6 seconds and drive in a smooth way (avoiding sudden accelerations or wheels blocks during brakes). The system will calculate the engaged gear and it will appear on the proper field of the display.

## 11.9 – Online

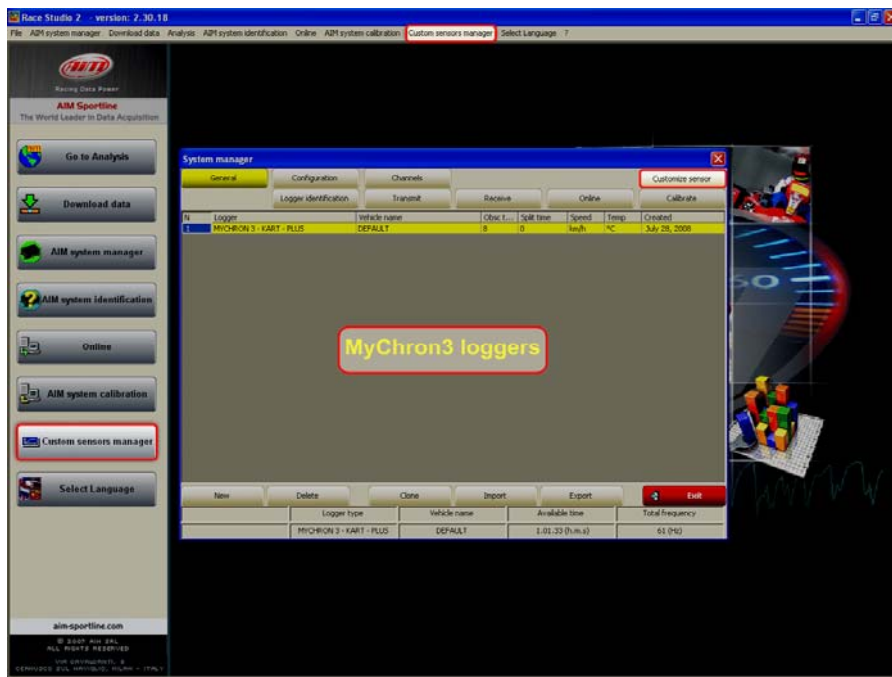
Online function is very useful to check the logger proper working. Refer to chapter 18 for further information.

## Chapter 12 – How to create a custom sensor

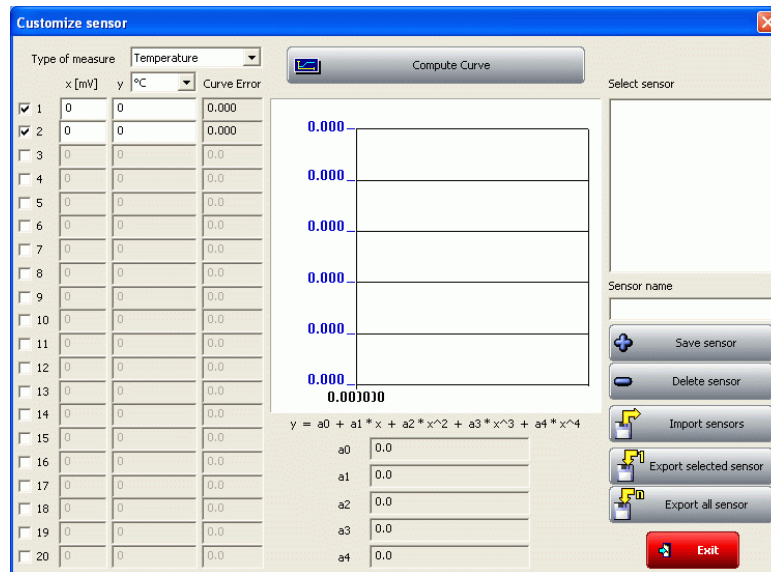
This function allows to configure a “custom” sensor setting the proper curve: it is very useful when the used sensor (pressure, temperature or other) is not included in the available sensors list.

**Please note: “Custom sensors” option is intended for expert users only.**

Press “Custom sensors manager” button in the menu bar or in the vertical keyboard. The button is also in system manager window for MyChron3 loggers as shown here below.



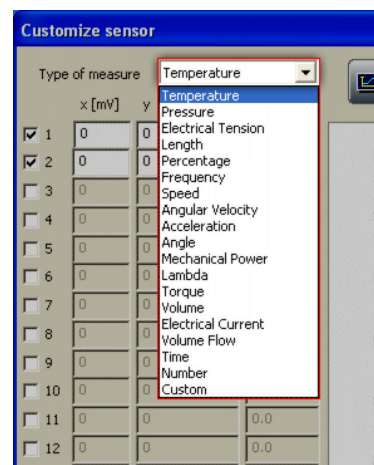
This window appears:



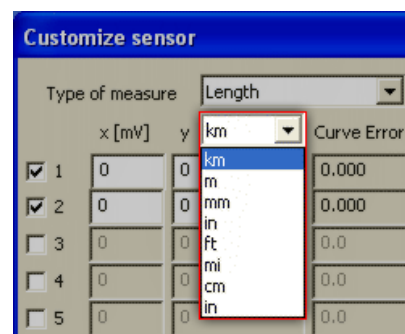
It allows to create/delete a custom sensor and import/export a sensor (or all sensors).

**To create a custom sensor:**

Click on the drop down menu corresponding to "Measure type" case and select the category the sensor belongs to.



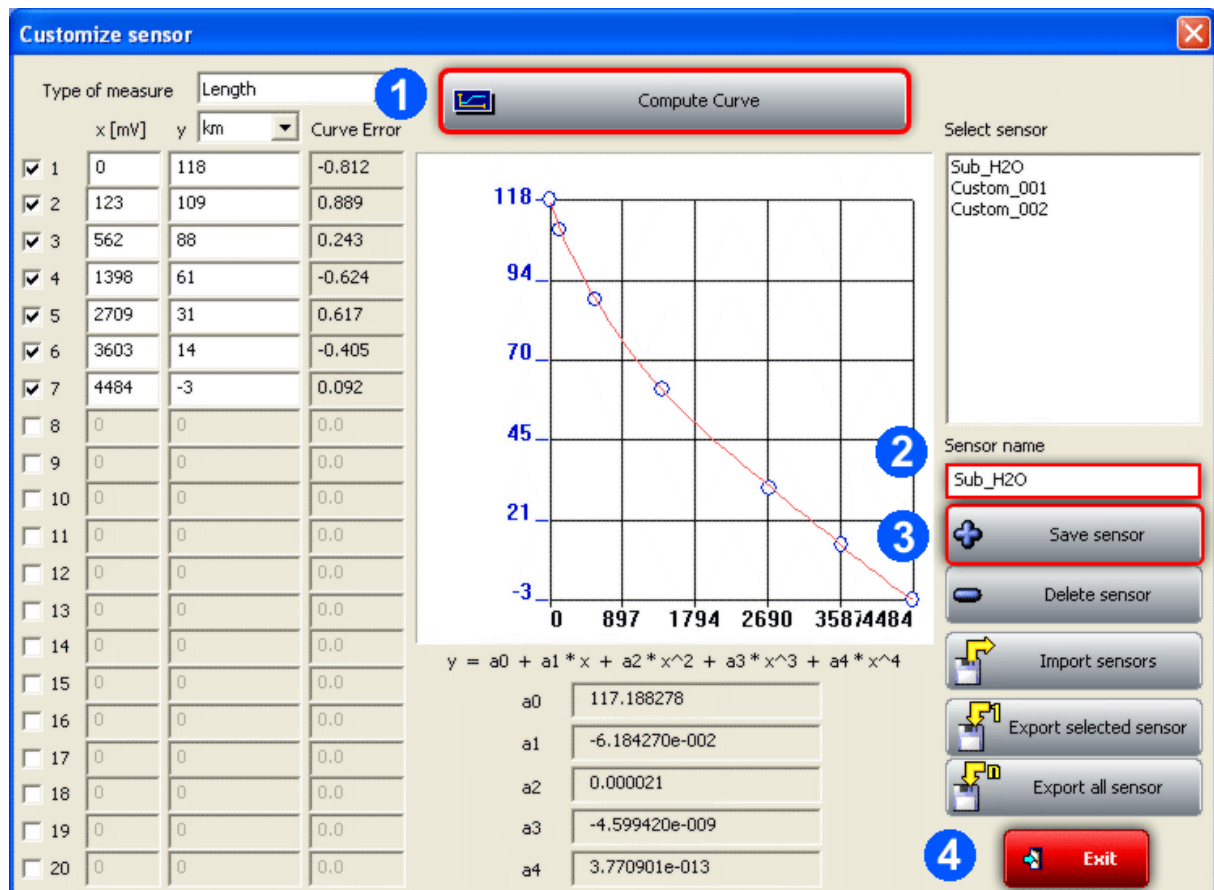
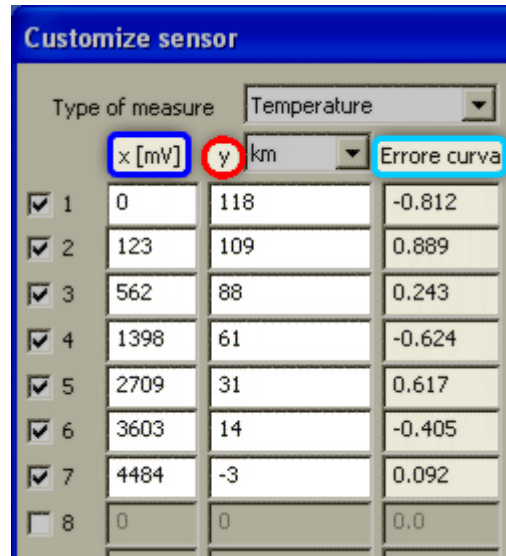
Select the unit of measure corresponding to the sensor to be created.



Enable the left cases corresponding to the number of experimental values to be used (up to 20 allowed).

Fill in the values corresponding to the sensor to be created in the two left columns.

- x[mV]: sensor output voltage in mV (X axle of the calibration curve);
- y: values of the selected measure concerning the output voltage – the values are interpolated using a polynomial (Y axle);
- Curve error: this column is useful to verify that the curve computed by the software is consistent with the experimental values.



After inserting the experimental values:

- click “Compute curve” (1);
- fill in “Sensor name” box (2);
- click “Save sensor” (3);
- click “Exit” (4);
- set the new sensor on the desired channel in channels window.

## Chapter 13 – How to transmit the configuration

To transmit the configuration the logger has to be switched on and connected to the PC USB port through the proper cable. Press “Transmit” button in system manager window and the system automatically will transmit the configuration to the logger.

**Warning: when the configuration has been transmitted to the logger it is not saved in the software configurations database. This means that - to have a copy of it in the database - users need to read and save it. To do so press “Receive” button in “System manager” window: the configuration appears as last row in the central part of the window and is highlighted in yellow.**

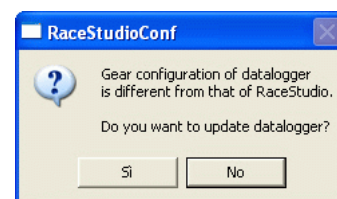
### 13.1 – Possible problems while transmitting the configuration

While transmitting the configuration various error messages can appear:

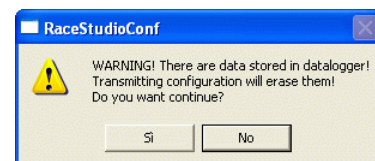
Check that the USB cable is correctly plugged in the PC and in the logger USB port, that the logger is switched on and try again transmitting the configuration.



The system informs the user that the configuration he is trying to transmit has a different gear setting. Press “Yes” only if you wish to change gear setting.



The system informs the user that the logger has data stored in its memory and they will be deleted if the configuration is transmitted. Press “Yes” only if you wish to delete the logger memory.



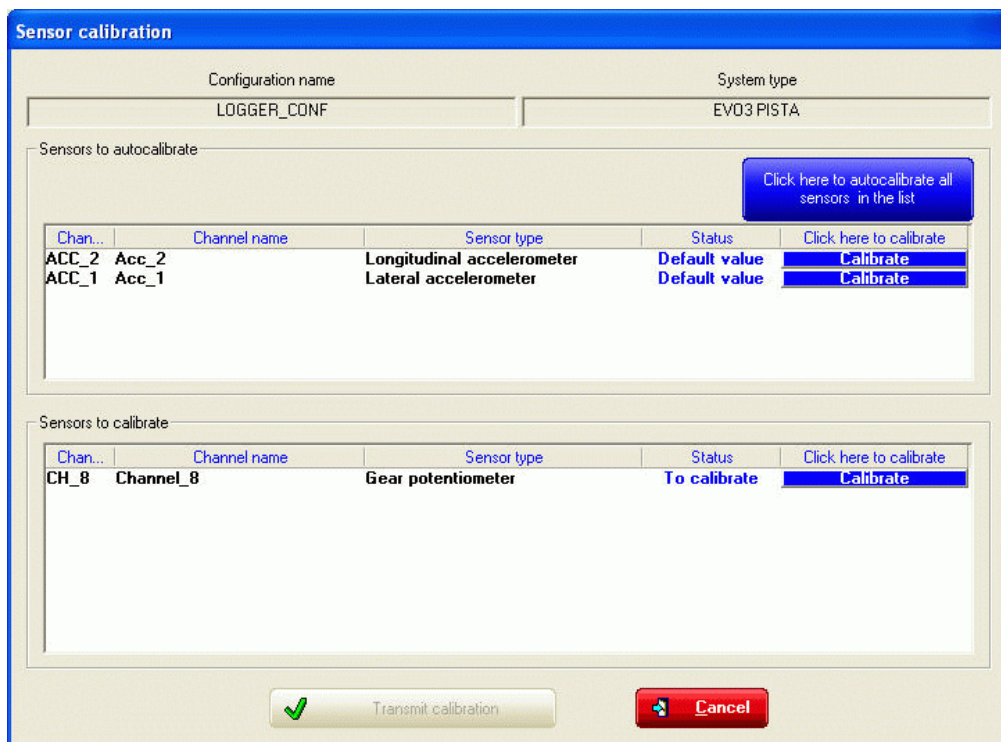


## Chapter 14 – Sensors calibration and auto-calibration

When the configuration has been transmitted it is necessary to perform calibration procedure, to say auto-calibrate accelerometer, gyroscope and distance potentiometer and calibrate the gear sensor, the mid zero potentiometer and the zero based potentiometer installed on the vehicle.

**Warning: if potentiometers, gyroscope and accelerometers have not been correctly calibrated it is not possible to sample correct data, nor the engaged gear nor create the track map. It is recommended to pay particular attention to sensors calibration/auto-calibration procedures.**

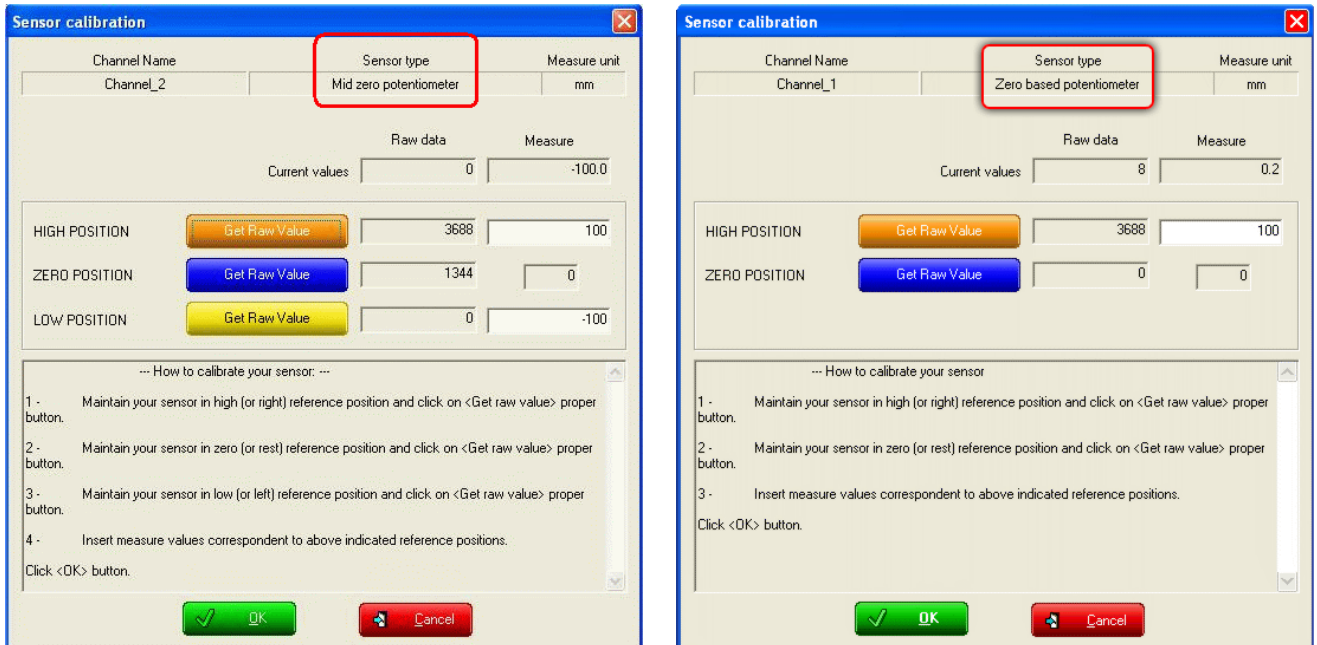
To enter calibration/auto calibration window press “AIM system calibration” button on the left keyboard or on **Race Studio 2** menu bar.



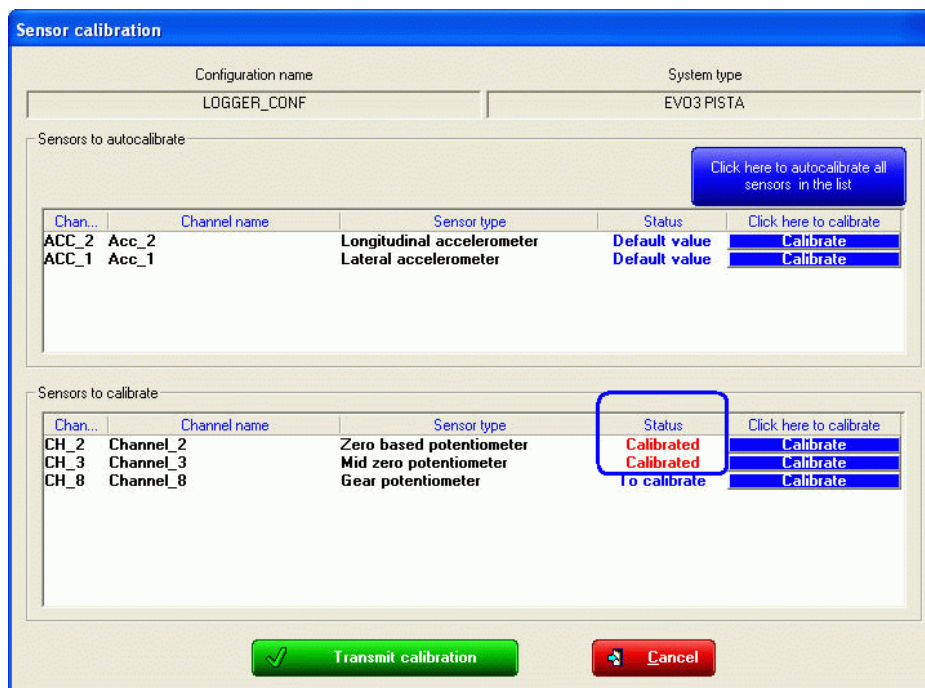
**Warning: to correctly perform the described procedures keep the vehicle as horizontal as possible (in case of a Bike leave it on the prop stand).**

## 14.1 – Sensors calibration procedure (except gear sensor)

Press “calibrate” button corresponding to the channel to be calibrated and follow the instructions that appear on the PC monitor. The figures here below show, on the left a mid zero potentiometer and on the right a zero based potentiometer calibration panel.



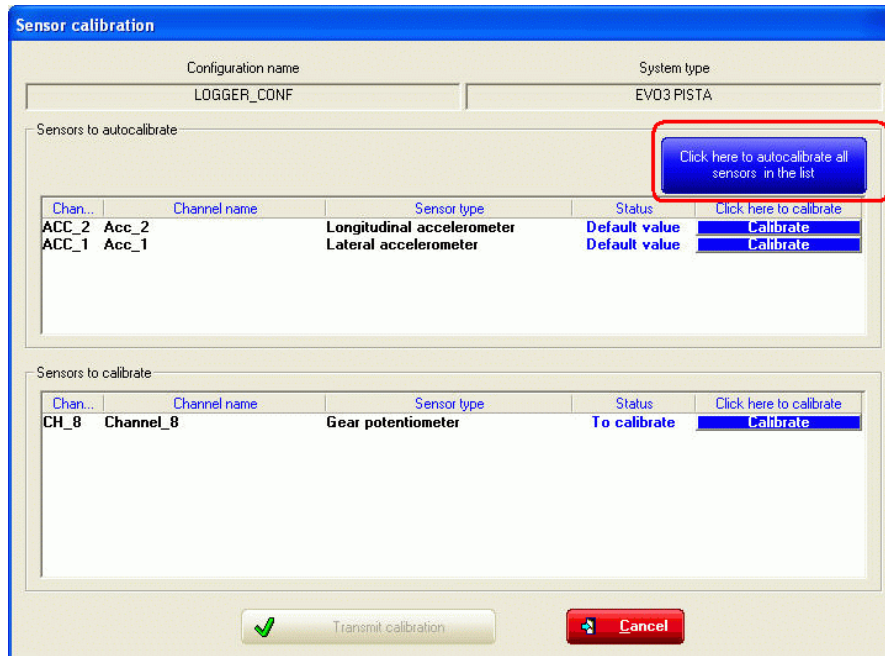
When the sensors have been calibrated their status in “Sensor calibration” window turns into “Calibrated” in red and “✓ Transmit calibration” button is enabled. Press it to transmit the calibration.



This procedure is fundamental to sample correct data.

## 14.2 – Sensors auto calibration procedure

Press “Click here to auto-calibrate all sensors in the list” to auto-calibrate accelerometer, gyroscope or distance potentiometer.

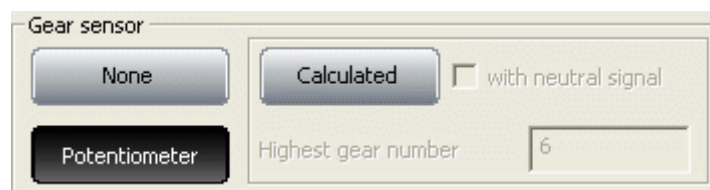


Sensors calibration status in “Sensor calibration” window turns into “Calibrated”, in red and “✓Transmit calibration” button, bottom left, is enabled: press it to transmit the calibration.

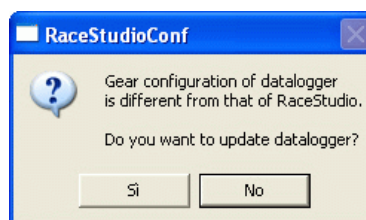
This procedure is fundamental to sample correct data.

## 14.3 – Gear sensor calibration procedure

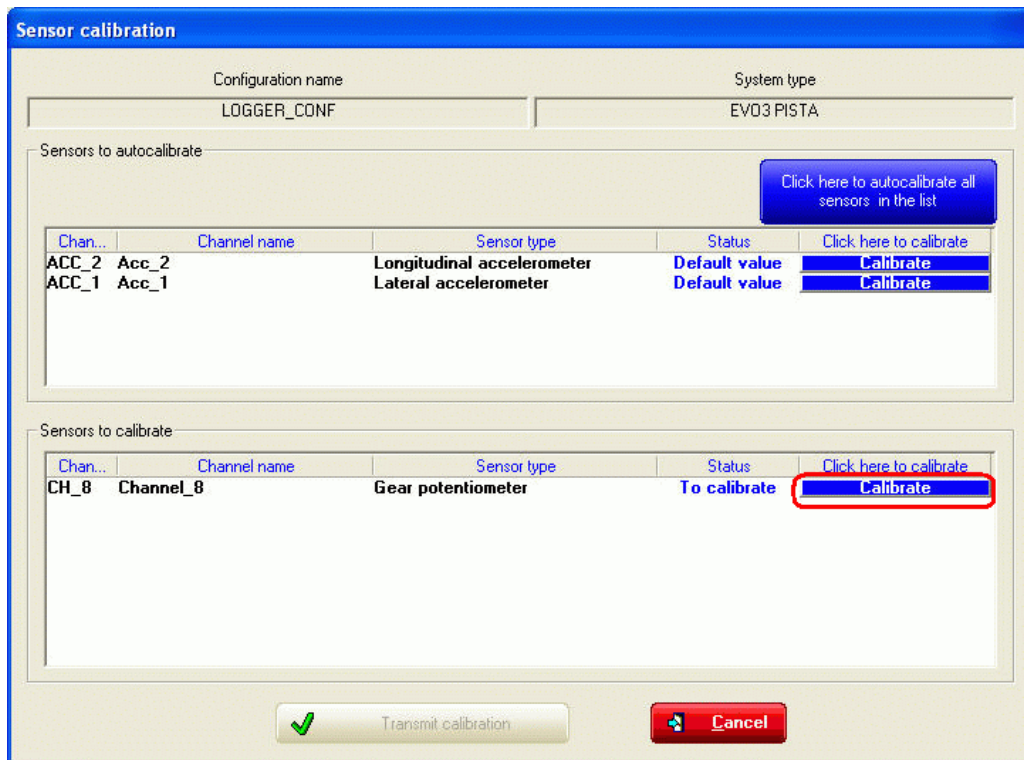
To calibrate the gear sensor it is necessary that the related panel in “System configuration” window is set on “Potentiometer” as shown here below.



In case during the transmission of the configuration the panel here below appears click on “Yes”.



then press “AIM system calibration” button in the menu bar or in the left vertical keyboard: this window appears:

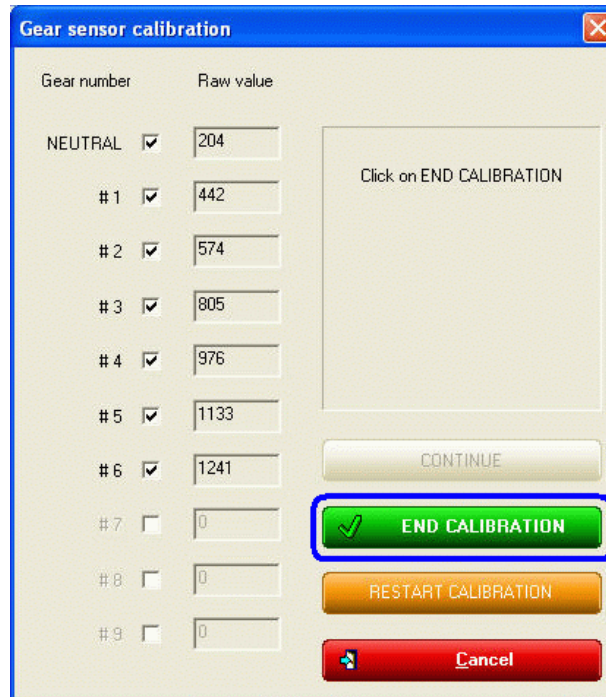


Press “Calibrate” button corresponding to the gear potentiometer. The window here below appears:

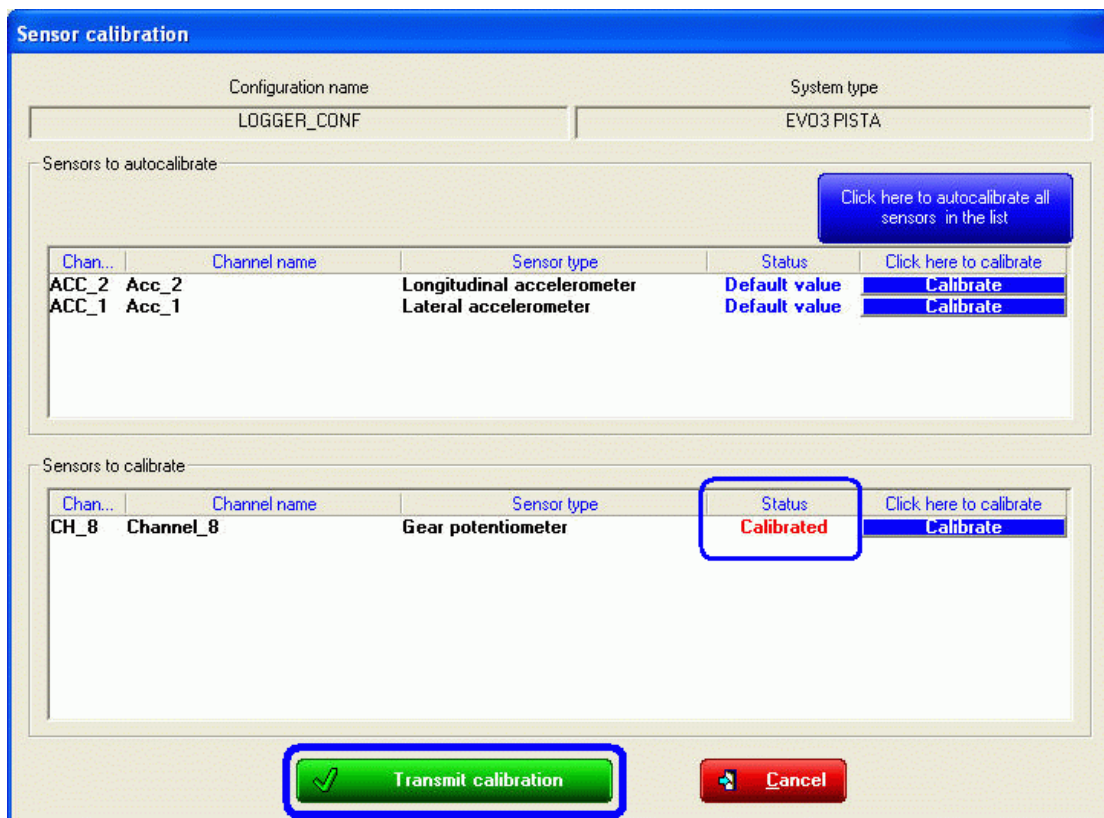


Follow the instructions that appear on the right part of the window (enable the checkbox corresponding to the highest gear number; press “Continue”, engage neutral gear, press “Continue”; engage the first gear, press “Continue” and repeat until the highest gear has been engaged).

When the procedure is over “✓ End calibration” button is enabled: press it.



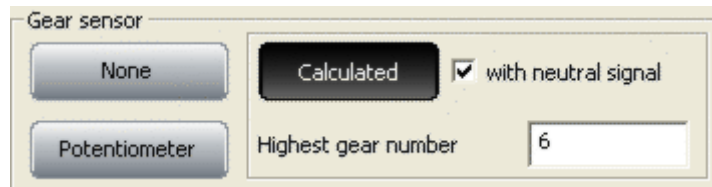
The system comes back to sensor calibration window. Gear potentiometer status turns into “Calibrated” in red and “✓ Transmit Calibration” button is enabled: press it.



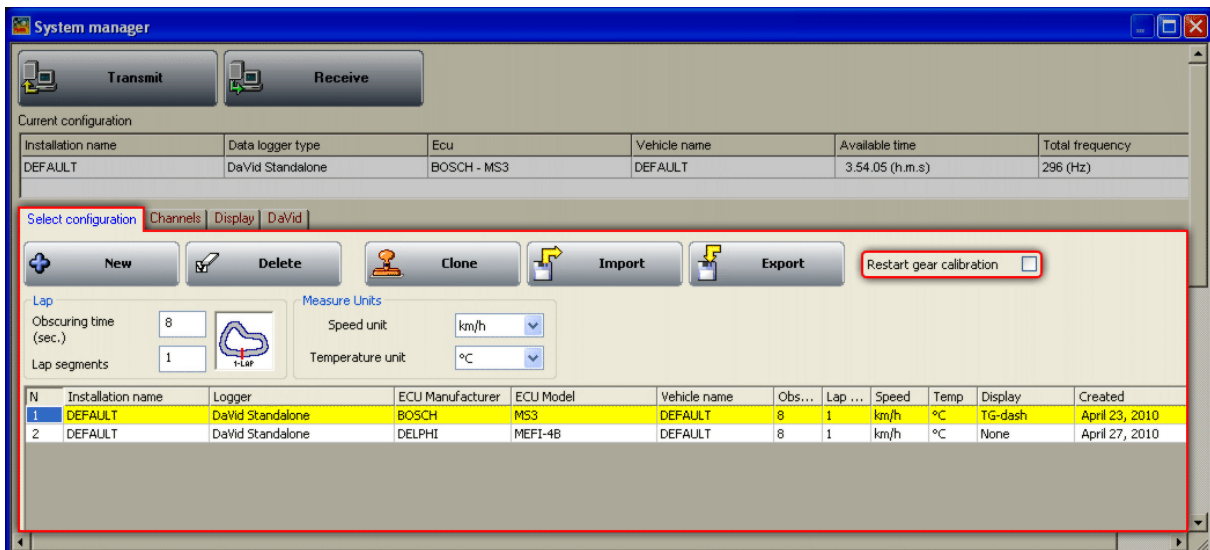
## Chapter 15 – Gear calculation procedure

Gear calculation procedure is to be set via software:

- set “Calculated” option in system calibration window;
- specify if a neutral sensor is available;
- fill in highest gear number;
- transmit the configuration to the logger.



**Note:** DaVid, the Data Video Recorder, needs that “Restart gear calibration” checkbox in “Select Configuration” layer is enabled, as shown here below.



When the gear sensor is set and the configuration has been transmitted, calculation procedure is to be performed through the logger keyboard and is made up of three steps: start, learning lap and calculation.

The correct procedure requires you to strictly follow these instructions.

Gear calibration proceeding is made using two inputs: RPM and speed. These two channels should be correctly configured and the related sensors installation should be faultless.

In case the logger has more than one speed input, gear calibration proceeding will take as reference speed the one shown on the display. It is suggested to take as reference the speed of the driving wheel. Gear calculation proceeding can be made also on not driving wheel, but in this case it is necessary to pay more attention not to have the wheels sliding or blocked during learning lap.

## Start (via keyboard)

To start this function or to reset previous values and re-start gear calculation proceeding (except for DaVid that needs a restart via software):

- press [MENU/←←] button until the display shows: GEAR CALIBRATION;
- press [MEM/OK] button: the display shows: calculated gear;
- press [MEM/OK] button and fill in the highest gear number using [←←] and [→→] buttons;
- confirm pressing [MEM/OK] button;
- quit the menu pressing [QUIT/VIEW] button.

As a confirmation of the activation the display shows “running GEAR CAL”: calibration procedure is correctly started.

## Learning lap

After gear calibration proceeding activation, a track lap needs to be run. During this learning lap, follow carefully these instructions.

- Engage all gears.
- Keep each gear engaged for at least 5/6 seconds.
- Drive in a smooth way (avoiding sudden accelerations or wheels blocks during brakes); let the engine keep RPM gradually and keep brakes as long as possible too in line with track characteristics and traffic situation. If using a reference speed coming from a not driving wheel, pay particular attention to driving style, reducing sliding between driving wheels and not driving ones.
- Go to the pit lane after the learning lap and switch the engine off.

**Warning: totally avoid “revs” while the vehicle is moving; avoid running through the pit lane with friction engaged. If needed, it is possible to press the accelerator before switching the engine off but when the vehicle is completely stopped.**

## Gear Calculation

After engine switch off gear calculation proceeding starts automatically. During this period LED AL1 blinks. After a few seconds (duration of the calculation depends on learning lap length) LED AL1 switches off and the display does no more show: “running GEAR CAL”.

All AIM systems allow gear calculation proceeding working also if engine switch off is needed. In this case just re-switch the system on and calculation proceeding re-starts automatically with recorded values. Calculation proceeding takes more time and blinking led will be LED AL2 and, after, LED AL1.

**Warning:** do not move the vehicle and do not switch the engine on during gear calculation. Moving the vehicle the logger could record values that would make it misdoing the calculation.

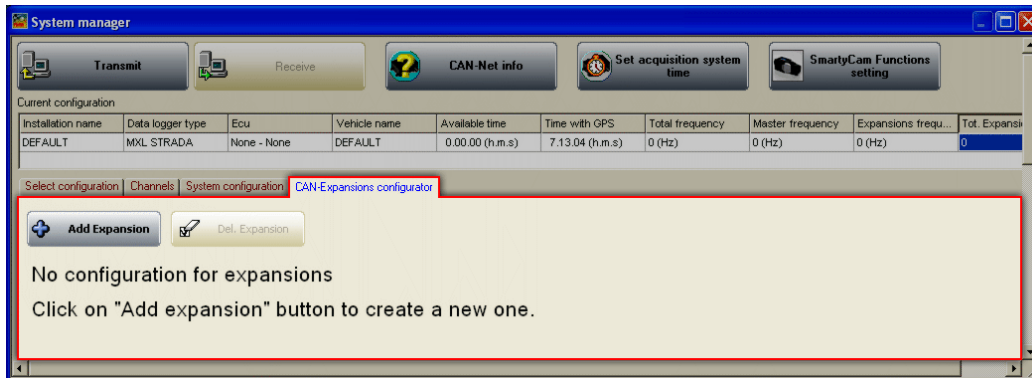
## Final suggestions

Gear calculation proceeding is only possible thanks to the measurement of the angular speed of the driving shaft and of the driving wheel. When the friction is completely engaged between the two speeds there is a ratio mechanically defined by the engaged gear. If the friction slides this ratio is no more determinable. If reference speed comes from a not driving wheel the sliding between driving wheel and not driving one due to accelerations and brakes implies an error in the gear computation. This is why it is strongly recommend to drive as smoothly as possible during learning lap.



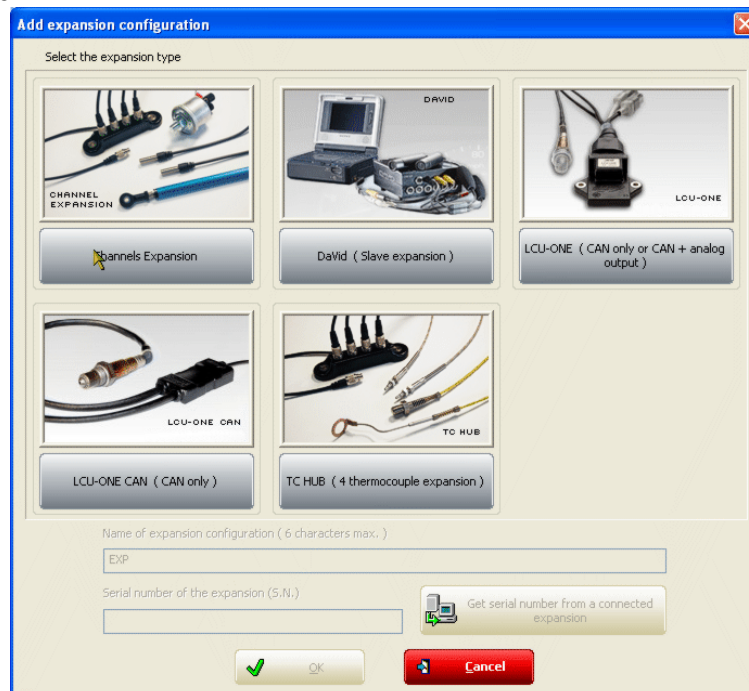
## Chapter 16 – How to configure CAN expansions

AIM loggers can be connected to different expansions that, communicating with him through the CAN bus, supply him with a lot of additional information without engaging any analog channel of the logger. To select the expansion to configure, enable “CAN expansions configurator” layer, shown here below.



In case of first expansions configuration or of very first configuration the layer shows up empty. To select the expansion to configure press “Add Expansion” button and the panel shown here below appears.

Please note: the products shown in the panel can change as soon as new products will be launched.



Select the expansion to configure pressing the button placed under each one.

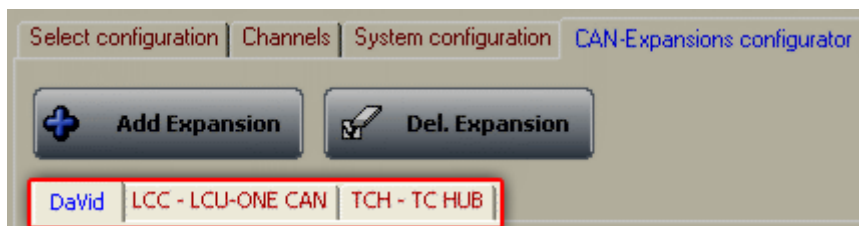
**It is suggested to perform all expansions configuration with all of them (except for DaVID) switched on and connected to the logger.**

For all CAN expansions, **except for DaVid**, the fields placed under the keyboard enables, as shown below.



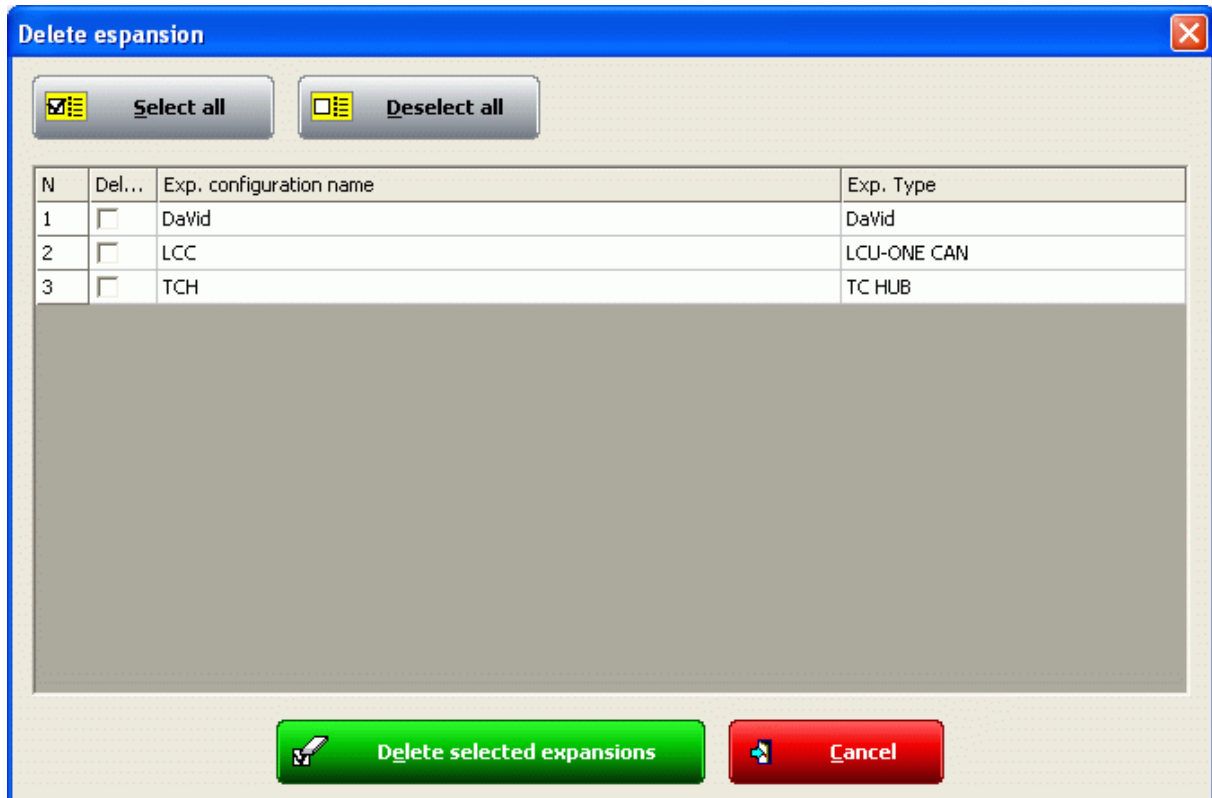
- Fill in the expansion name (1).
- Press “Get serial number from a connected expansion” (2) and the system uploads the expansion univocal serial number.
- press “OK” (3).

The system loads the configuration layer of the added expansion and it appears in “CAN expansions configurator” layer. This operation is to be repeated for each CAN expansions to be added. The image below shows “CAN expansions configurator” layer with three activated expansions (red circled): the video system, a Lambda Controller CAN (LCU-ONE CAN) and a TC Hub.

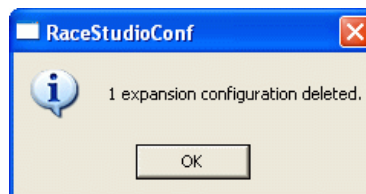


Each expansion is optional to the logger and is supplied with the related user manual. Refer to those user manuals for further information concerning each expansions configuration.

To delete an expansion from the logger configuration press “Del. expansion” button. This window appears:

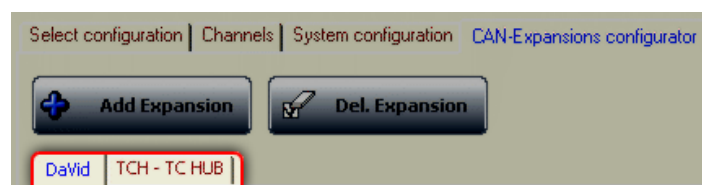
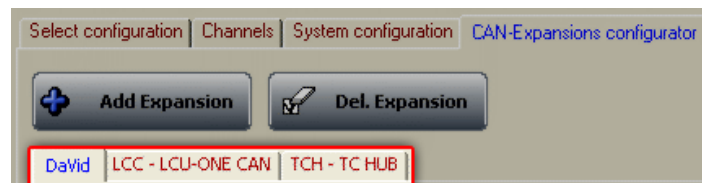


Enable the checkbox of the expansion to delete and press “Delete selected expansions” button. The system shows a confirmation message...



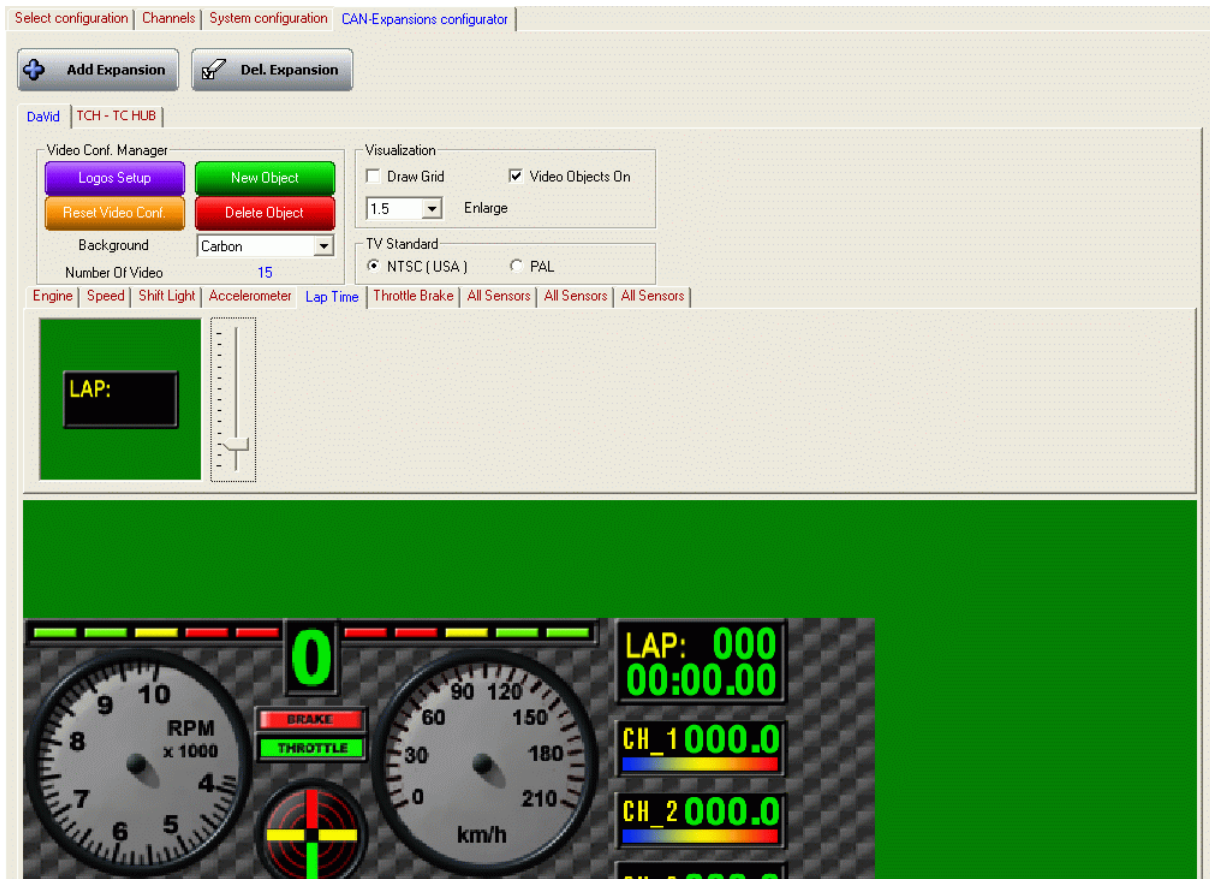
...and the related layer is deleted from “CAN expansions configurator” layer.

The images below show “CAN Expansions Configurator” layer with three expansions (DaVid, LCU-ONE CAN and TC Hub) on top and the same layer with LCU-ONE expansion deleted on bottom: the related layer disappeared.



Among CAN expansion that can be connected to AIM loggers is also a Video system, DaVid Slave Expansion, connected with up to two cameras. For further information on these objects refer to DaVid User Manual.

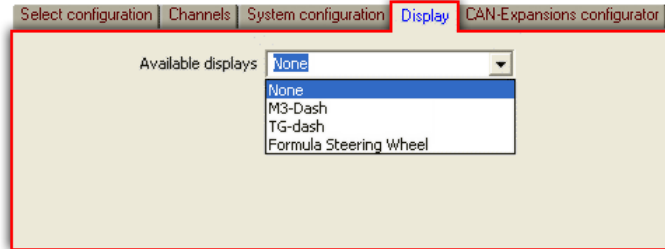
When the video system has been correctly installed and connected to AIM logger it will be necessary to load it as expansion using the panel shown before and its configuration window, shown here below, appears.



It allows to show all parameters of the video system. It is the same used to configure **DaVid** master and works exactly at the same way. Refer to paragraph 8.6 for further information.

## Chapter 17 – How to configure AIM displays

Those AIM loggers without an integrated display, like **EVO3** and **EVO4** can be connected to optional visors like **MyChron3 Dash**, **TG Dash** and **Formula Steering Wheel**. To configure the one connected activate the related layer:



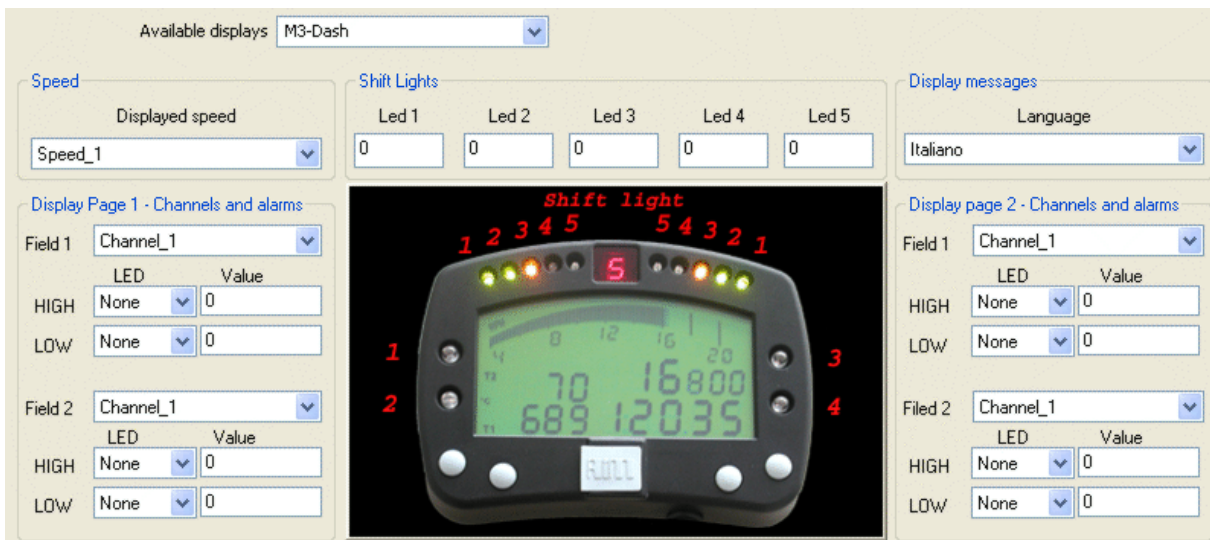
The first time the layer shows up empty.

### 17.1 – How to configure MyChron3 Dash

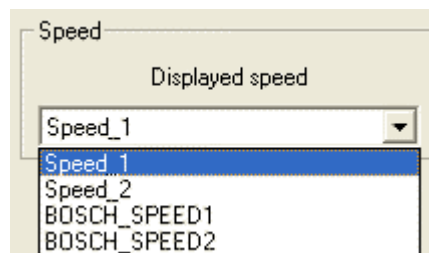
**MyChron3 Dash** display is available for **DaVid**, for **EVO3 Pro/Pista** and for **EVO4**.

#### 17.1.1 – How to configure MyChron3 Dash for DaVid

Select M3-Dash display and its configuration window appears.



Speed Channel box:



This drop down menu allows to select the speed shown by the display.

In the example above **DaVid** is connected to a Bosch ECU that transmits two speed channels which are additional to the logger ones, both enabled.

## Display Pages 1 e 2 – Channels and alarms

These boxes allow to set the displayed channels linking them to one of the four alarm led placed sideways of the display.

- select the channel to show from the drop down menu;
- set High/Low alarm selecting the led to link them to;
- fill in the threshold value.

## Shift Lights box

It manages the 10 led placed on top of the logger display.

Led colours: the first two on the left and on the right are green, the central two are orange and the last four are red. To set RPM threshold values fill in the cases. The led switch progressively on and when the engine reaches RPM value set for led 5 all led start blinking, warning the pilot to shift gear.

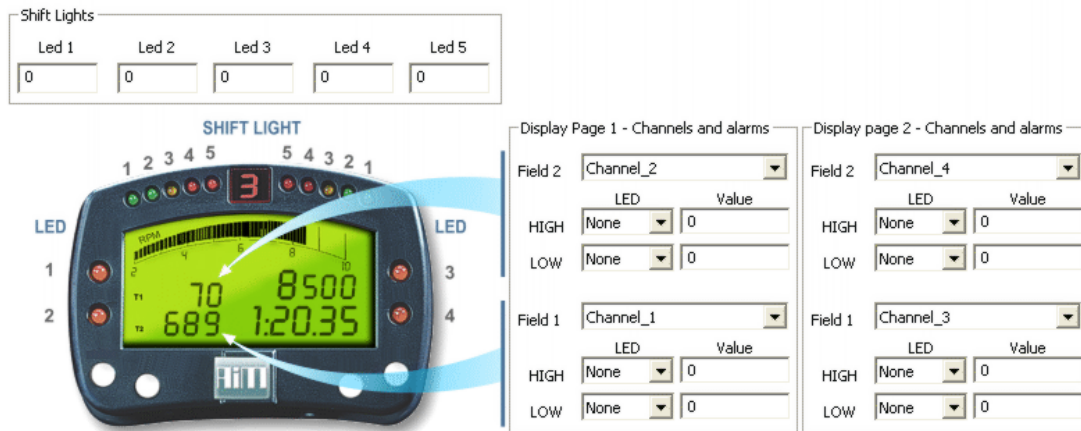
If a case is set on “0” the corresponding led is disabled.

## Display messages box

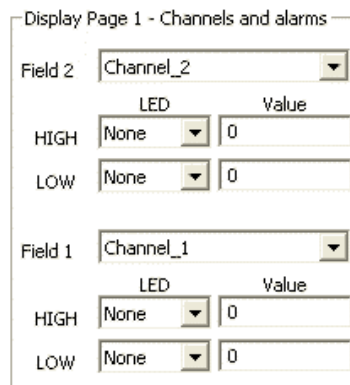
This drop down menu allows the user to select the display language.

### 17.1.2 – How to configure MyChron3 Dash for EVO3 Pro/Pista

Selecting **M3-Dash** this configuration window appears.



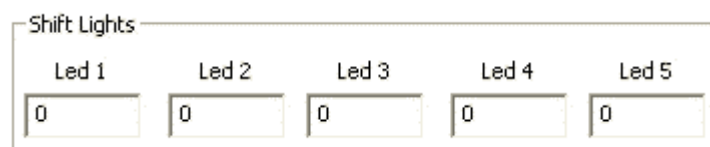
Display Page 1 and 2 – Channels and alarm



These boxes allow to set the displayed channels linking them to one of the four alarm led placed sideways of the display.

- select the channel to show from the drop down menu;
- set High/Low alarm selecting the led to link them to;
- fill in the threshold value.

#### Shift Light box



It manages the 10 led placed on top of the logger display.

Led colours: the first two on the left and on the right are green, the central two are orange and the last four are red. To set RPM threshold values fill in the cases. The led switch progressively on and when the engine reaches RPM value set for led 5 all led start blinking, warning the pilot to shift gear.

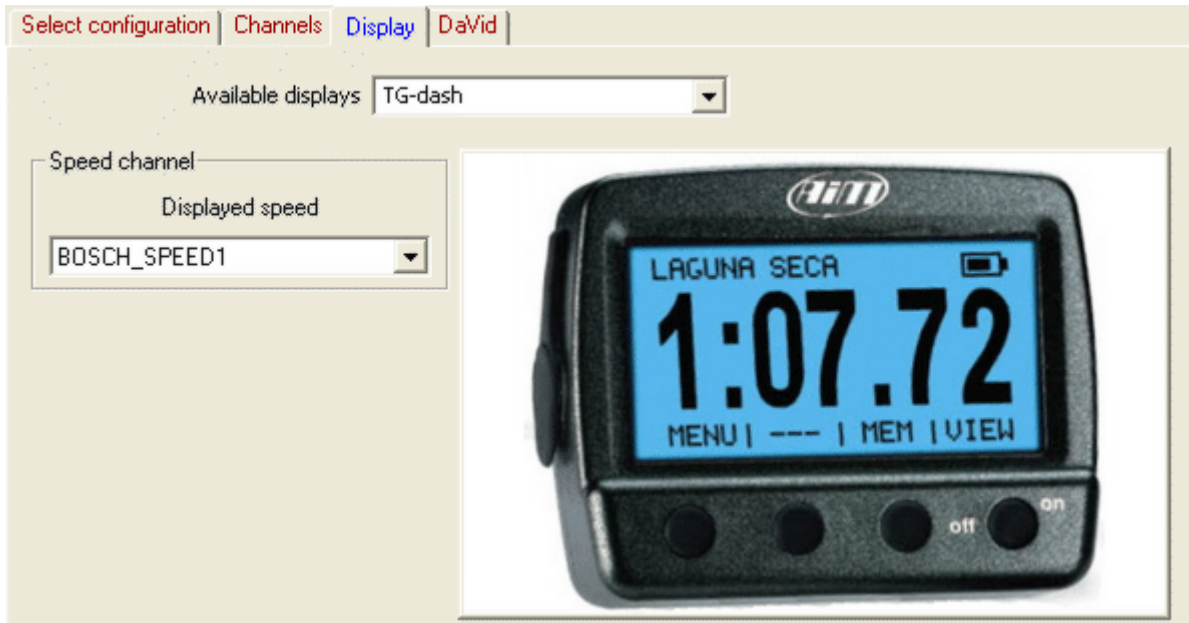
If a case is set on "0" the corresponding led is disabled.

## 17.2 – How to configure TG Dash

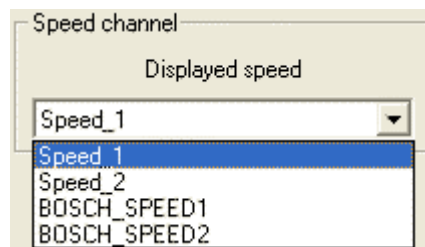
TG Dash is available for **David** and for **EVO3 Pro/Pista** and for **EVO4**.

### 17.2.1 – TG Dash for DaVid

Select TG-Dash display and this window appears.



The only settable channel is the speed.



In the example below **DaVid** is connected to a Bosch ECU, that transmits two speed channels; it is thereby possible to show one of **DaVid** speeds or one of the ECU ones.

**Note:** TG-Dash is mainly configurable via keyboard; refer to its user manual for further information.



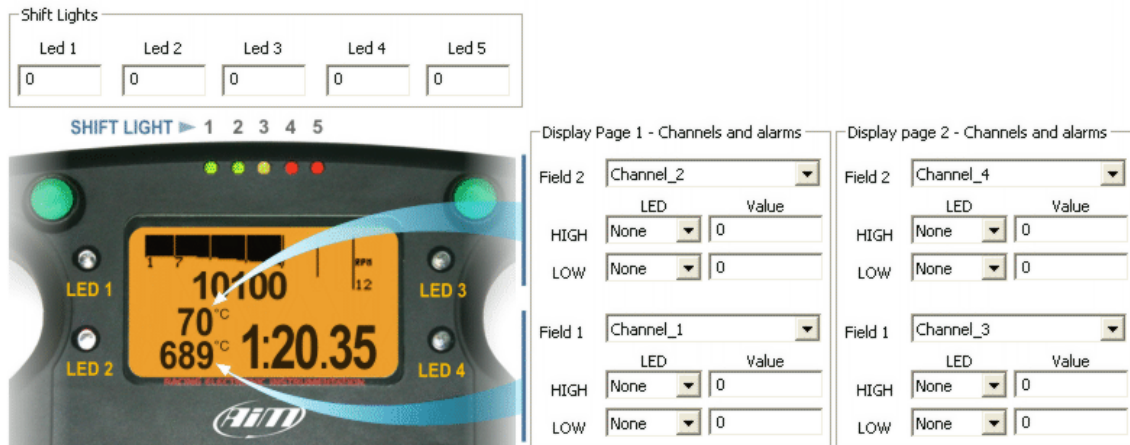
### 17.2.2 – TG Dash for EVO3 Pro/Pista and EVO4

Selecting **TG-dash** display the related window appears It needs no via software configuration. Just select the display from the drop down menu.

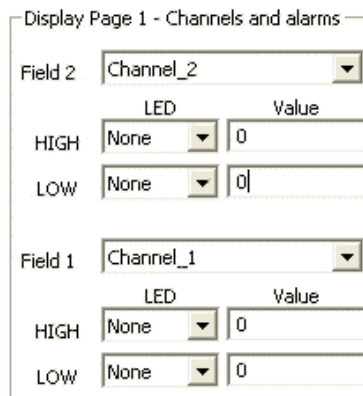


### 17.3 – How to configure Formula Steering Wheel

**Formula Steering wheel** display is only available for **EVO3 Pro/Pista** and **EVO4**. Selecting “**Formula Steering Wheel**” this window appears:



Display Pages 1and 2 – Channels and alarm Boxes



These boxes allow to set the displayed channels connecting them to one of the four alarm led placed laterally on the display.

To set them:

- select the channel to show from the drop down menu;
- set it as High/Low alarm selecting the led to link it to
- fill in threshold value case.

## Shift Light box

Shift Lights				
Led 1	Led 2	Led 3	Led 4	Led 5
0	0	0	0	0

Sets the 10 led placed on top of the logger display. Led colours: the first two on the left and on the right are green, the central two are orange and the last four are red. The led switch progressively on and when the engine reaches RPM value fixed for led 5 all led start blinking, warning the pilot to shift gear.

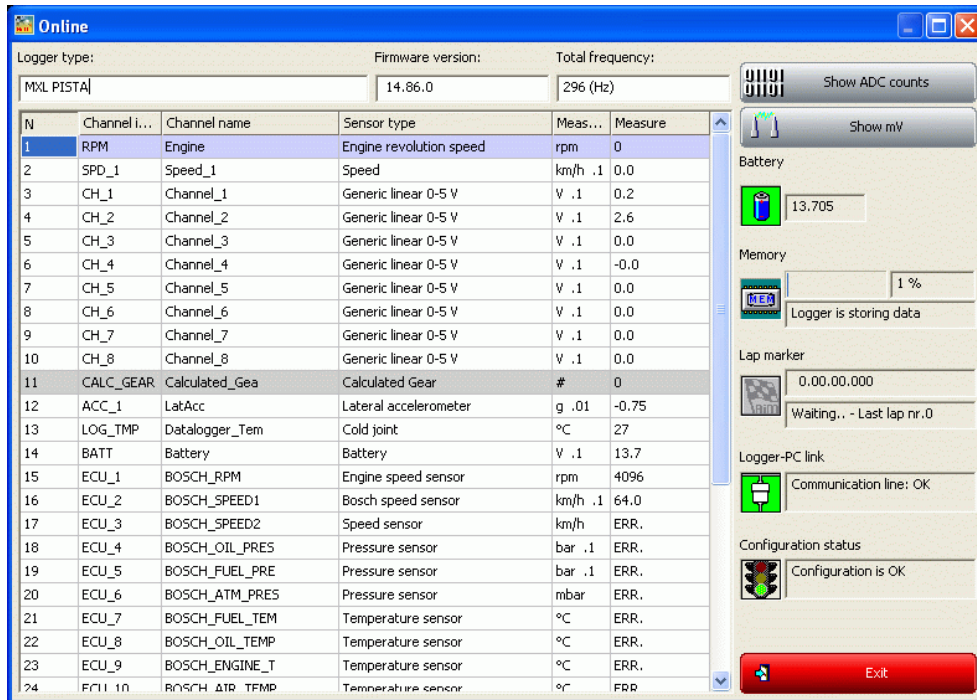
If one case is set on "0" the corresponding led is disabled.

## Chapter 18 – Online

When the calibration is over and the configuration has been transmitted to the logger, it is suggested to enter “Online” pressing the corresponding button on the menu bar, on the left vertical keyboard to verify that all works properly. In MyChron3 loggers online button is also in system manager window as shown here below.



This function allows to check that all works properly. Ensure that the logger is switched on and well connected to the Pc.



The screenshot shows the 'Online' window with the following data:

N	Channel i...	Channel name	Sensor type	Meas...	Measure
1	RPM	Engine	Engine revolution speed	rpm	0
2	SPD_1	Speed_1	Speed	km/h .1	0.0
3	CH_1	Channel_1	Generic linear 0-5 V	V .1	0.2
4	CH_2	Channel_2	Generic linear 0-5 V	V .1	2.6
5	CH_3	Channel_3	Generic linear 0-5 V	V .1	0.0
6	CH_4	Channel_4	Generic linear 0-5 V	V .1	-0.0
7	CH_5	Channel_5	Generic linear 0-5 V	V .1	0.0
8	CH_6	Channel_6	Generic linear 0-5 V	V .1	0.0
9	CH_7	Channel_7	Generic linear 0-5 V	V .1	0.0
10	CH_8	Channel_8	Generic linear 0-5 V	V .1	0.0
11	CALC_GEAR	Calculated_Gea	Calculated Gear	#	0
12	ACC_1	LatAcc	Lateral accelerometer	g .01	-0.75
13	LOG_TMP	Datalogger_Tem	Cold joint	°C	27
14	BATT	Battery	Battery	V .1	13.7
15	ECU_1	BOSCH_RPM	Engine speed sensor	rpm	4096
16	ECU_2	BOSCH_SPEED1	Bosch speed sensor	km/h .1	64.0
17	ECU_3	BOSCH_SPEED2	Speed sensor	km/h	ERR.
18	ECU_4	BOSCH_OIL_PRES	Pressure sensor	bar .1	ERR.
19	ECU_5	BOSCH_FUEL_PRE	Pressure sensor	bar .1	ERR.
20	ECU_6	BOSCH_ATM_PRES	Pressure sensor	mbar	ERR.
21	ECU_7	BOSCH_FUEL_TEM	Temperature sensor	°C	ERR.
22	ECU_8	BOSCH_OIL_TEMP	Temperature sensor	°C	ERR.
23	ECU_9	BOSCH_ENGINE_T	Temperature sensor	°C	ERR.
24	ECU_10	BOSCH_AIR_TEMP	Temperature sensor	°C	ERR.

Right-hand side indicators:

- Logger type: MXL PISTA
- Firmware version: 14.86.0
- Total frequency: 296 (Hz)
- Show ADC counts: [Button]
- Show mV: [Button]
- Battery: 13.705 V
- Memory: 1 %
- Logger is storing data: [Indicator]
- Lap marker: 0.00.00.000
- Waiting... - Last lap nr.0
- Logger-PC link: Communication line: OK
- Configuration status: Configuration is OK
- Exit: [Button]

**On top:**

- Logger type: the type of logger connected to the PC.
- Firmware version: firmware version installed on that logger.
- Total frequency: sum of all channels sampling frequency.

**Central: channels table**

**On the right:**

- Show ADC counts and show mV: buttons mainly used by AIM staff.
- Battery: shows battery voltage; in some loggers beside this case there is another one labelled V Ref. that shows V Ref value.
- Memory: shows memory status (logger is storing data or logger isn't storing data).
- Lap marker: checks transmitter/receiver channels. Place the transmitter in front of the receiver to test this function.
- Logger-PC link: shows the status of the USB connection.
- Configuration status: shows the configuration status.
- Exit: quits online window.

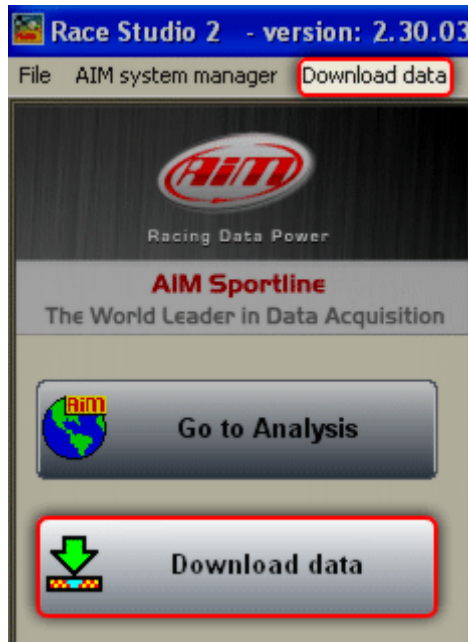
**Note:** if this message appears check that the logger is switched on, the cable is correctly plugged in the PC and in the Logger USB port; then try again.



## Chapter 19 – How to download data

Once a test session is over it is possible to download data sampled by the logger. The software procedure is slightly different for the different loggers. On the contrary, the mechanical procedure is the same:

- connect the USB cable to the logger and to the PC USB port;
- switch the logger on;
- press “Download data” on the menu bar or on the left vertical keyboard.

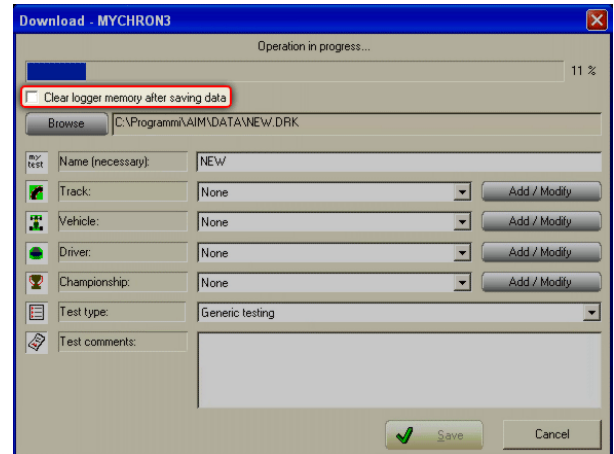
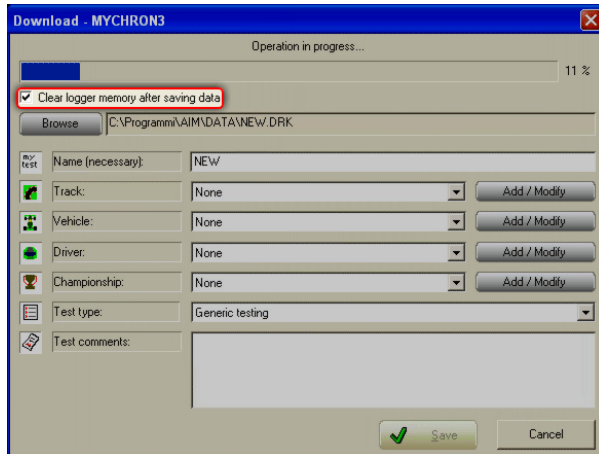


## 19.1 – Download data from MyChron3 (all versions) and DaVid

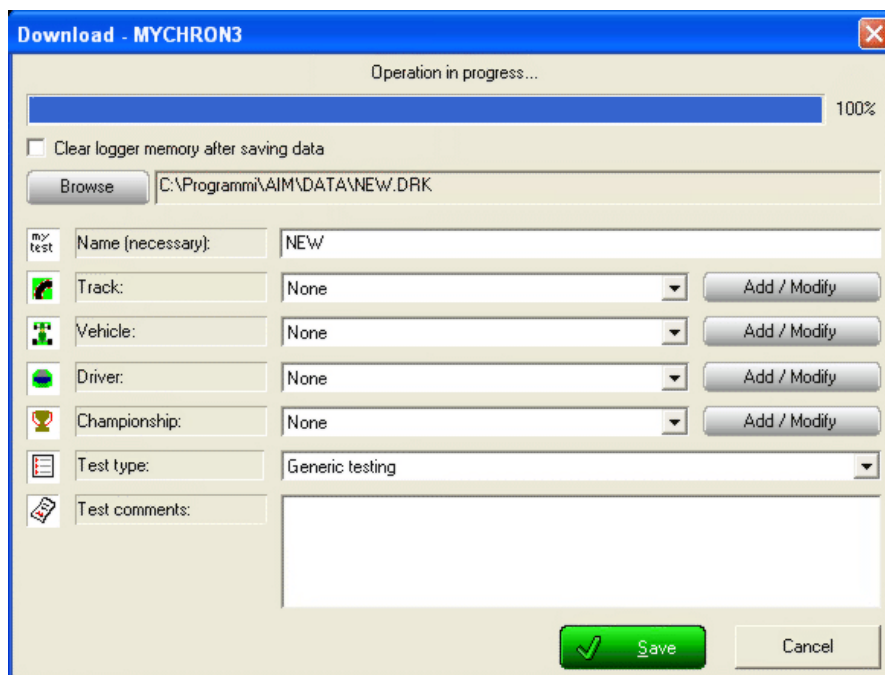
Pressing download buttons the related window appears.

**Warning: default setting is clear logger memory after saving data.**

It is possible to disable that checkbox. The figures here below show the two options:

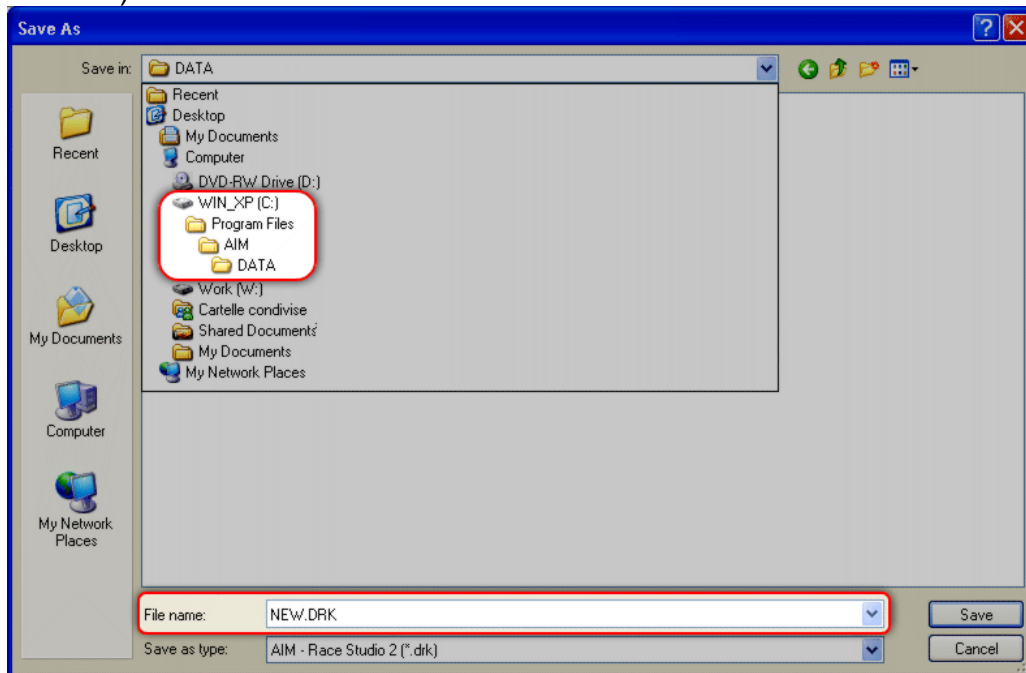


On top of the window there is a waiting bar that shows download progression in percentage.



When download is completed “✓Save” button – bottom right – enables.

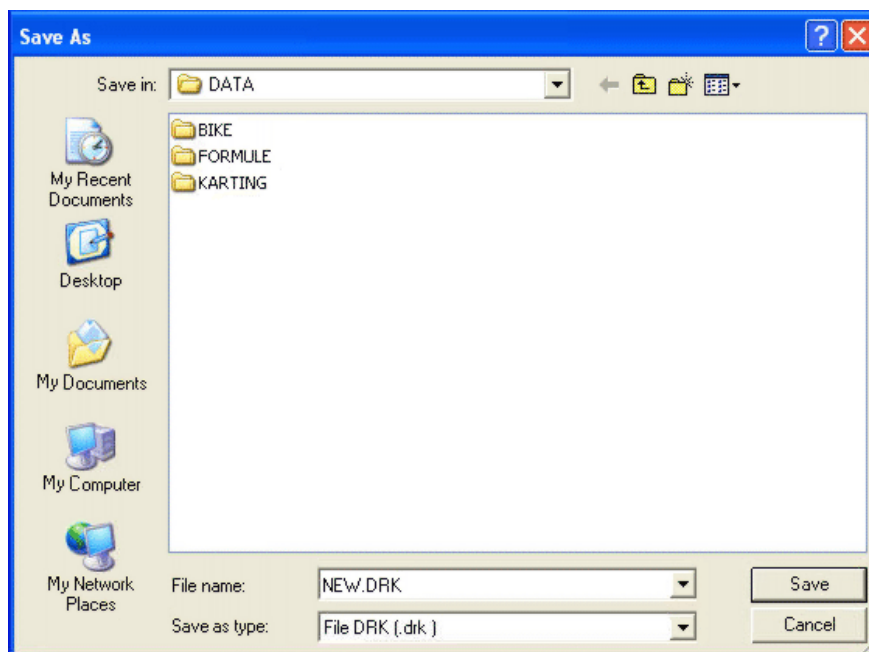
Pressing it without specifying anything the file is saved as “NEW.DRK” in this folder: “X:\Program files\AIM\DATA” (where X is the hard disk where **Race Studio 2** has been installed).



It is also possible to save the file with some specific characteristics and in a desired folder following the procedure here explained.

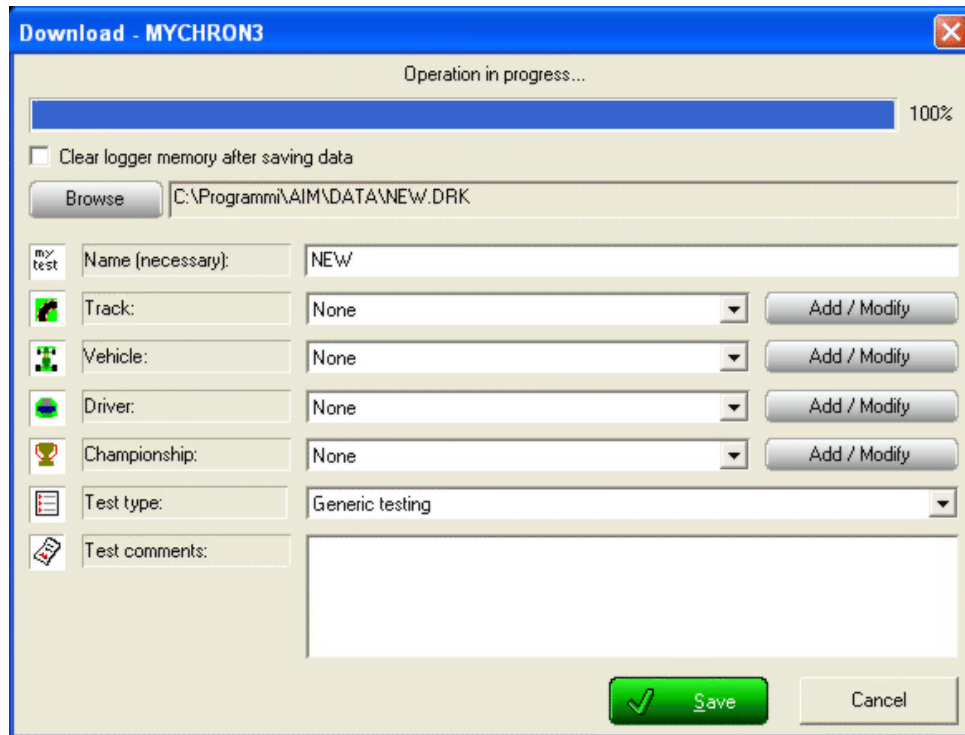
### **Saving the file in a specific folder**

- Press “Browse”.
- “Save as” window appears.
- Browse it and select the desired folder.



- fill in File name case.
- press “Save”.

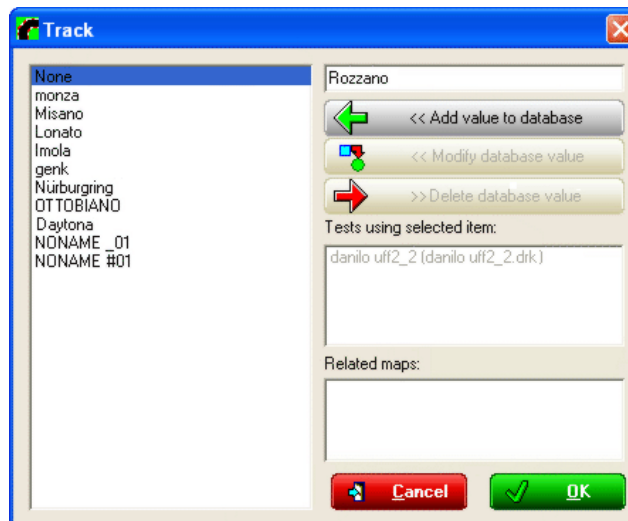
**Saving the file with some specific characteristics.**



Select the desired characteristics through the drop down menus placed beside the different characteristics: Track, Vehicle, Driver, Championship or Test type.

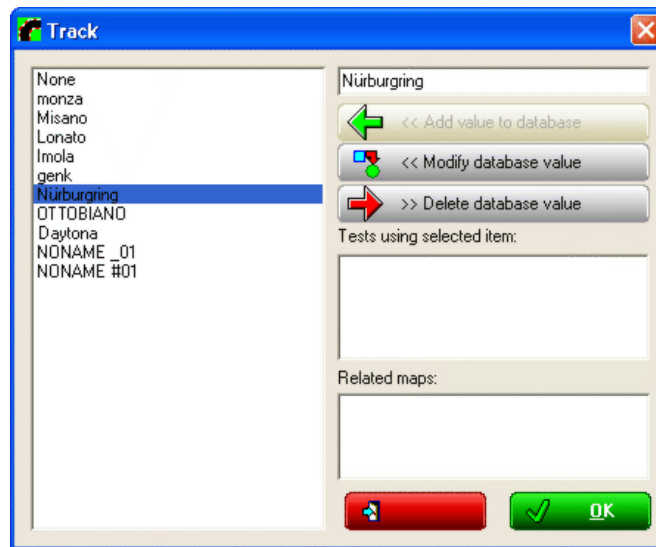
**To add new characteristics:**

- press lateral “Add/Modify” button and the window here below appears;



- fill in a new name in the top right case of the window;

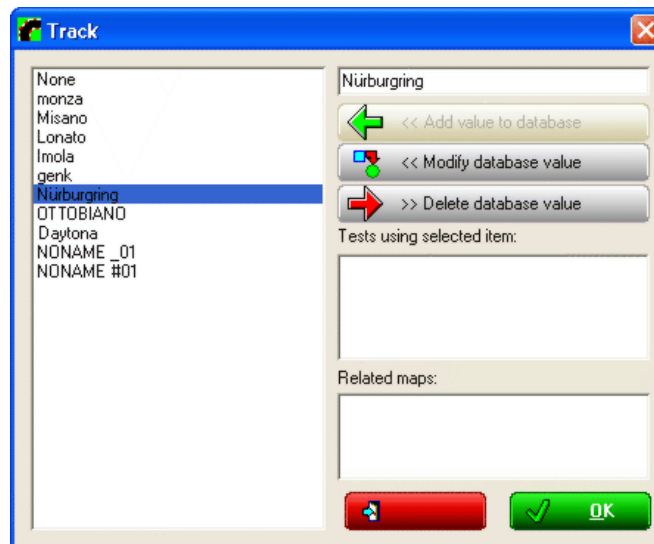




- “<< Add value to database” button enables;
- press it and the new characteristic are inserted in the database;
- press “✓OK” button to save the new characteristic (or “Cancel” to quit without saving);
- the system comes back to the previous window;
- this new characteristic is now selectable from the drop down menu.

#### To modify or delete a characteristic

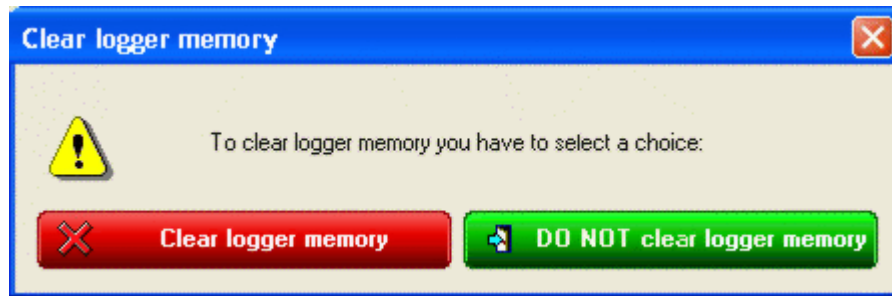
- press “Add/Modify” button and the window here below appears;



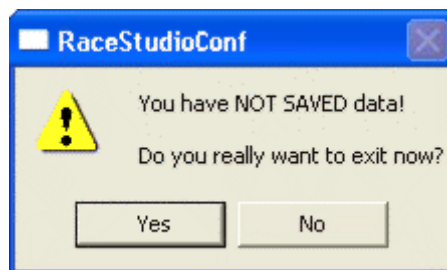
- select the characteristic to be deleted/modified
- “<< Modify database value” and “>>Delete database value” buttons enable;
- press the desired one;
- modify the characteristics if this is the selected option;
- press “✓OK” button to save changes (or “Cancel” to quit without saving);
- the system comes back to the previous window.

When all characteristics have been inserted press “✓ Save”.

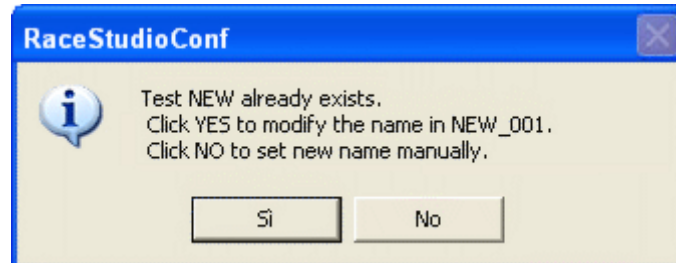
The system asks if the logger memory has to be deleted or not. Press the desired button.



During data download the system can show different warning messages:



The system informs the user that downloaded data have not been saved. Press “No” to save data before quitting.



The system warns that that file name already exists and gives two options:

- using a progressive nomenclature: press “Yes”
- filling in a new name manually: press “NO” and follow the procedure explained before.

## 19.2 – Downloading data from other systems

Pressing “Download data” button the related window, shown here below, appears.



Data download from **MXL** and **EVO3 Pro/Pista** requires an inverted procedure compared to **MyChron3** and **DaVid** one.

While before data were characterised after download, now it is necessary to before characterise the data and after download them.

Starting download procedure the system shows - in the central table - data stored in the logger memory.

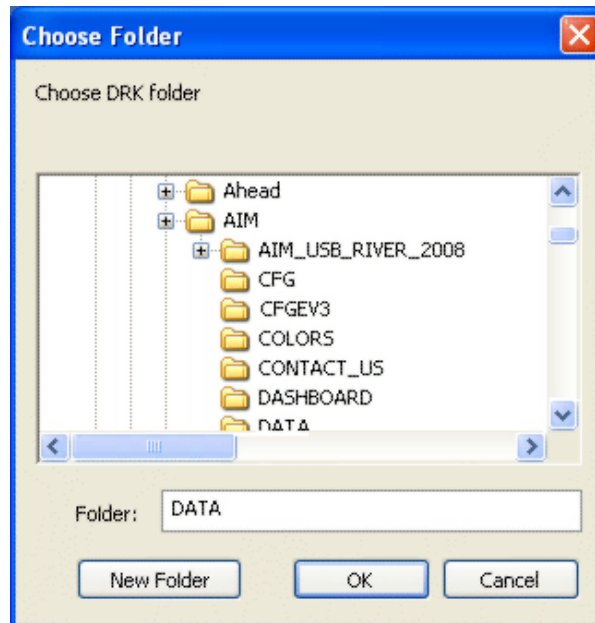
This window allows to select which data to download, if showing or hiding and how to group them.

## Choose folder button

This button allows the user to select the file destination folder.



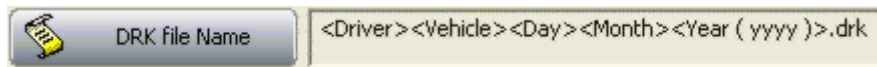
As shown here above, the system has a default destination folder, that is on the hard disk where **Race Studio 2** is installed (in this case hard disk "C"). To save the data elsewhere press "Choose folder" button. "Choose folder" window appears:



Browse it to select the destination folder or create a new one pressing "New folder" button.

## DRK File name button

This button allows to save data with a custom name.

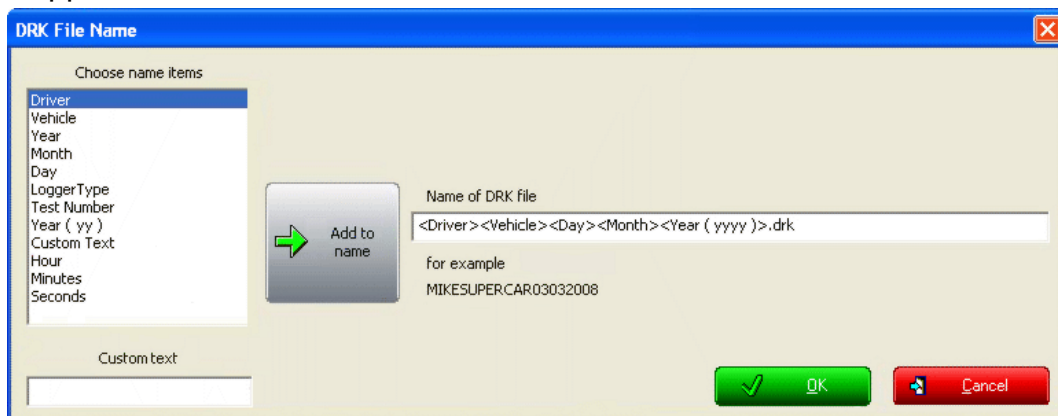


As shown in the figure above, the default name has some specific characteristics that have to be defined.

In case user does not select these characteristics they are automatically set on "None", as shown here below:



To define the characteristics press "DRK file name" button and the window here below appears.



To fill in each field:

- select it from "Choose name items" case;
- place the pointer in the point where to insert the item;
- press "Add to name";

To insert a custom text in the name, insert it in the related case;

- select the custom text from the left list;
- place the pointer in the point where to insert the new item;
- press "Add to name";

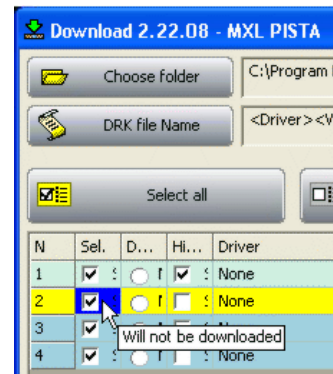
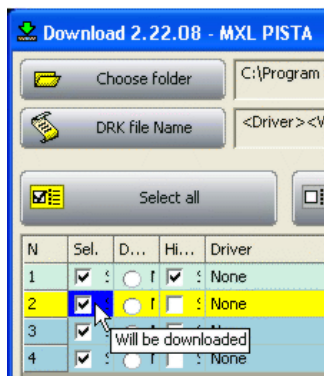
When all name characteristics have been defined press "✓OK" (or "Cancel" to quit without saving) and the new name is saved.

## Central keyboard

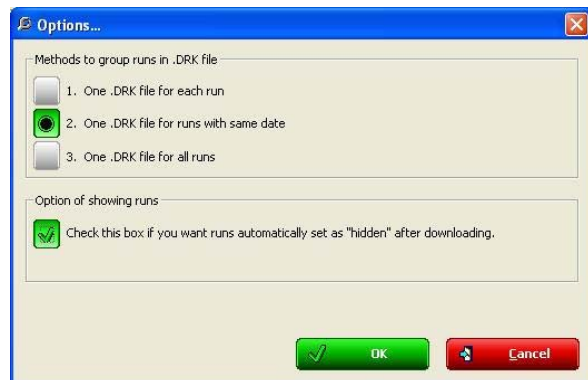
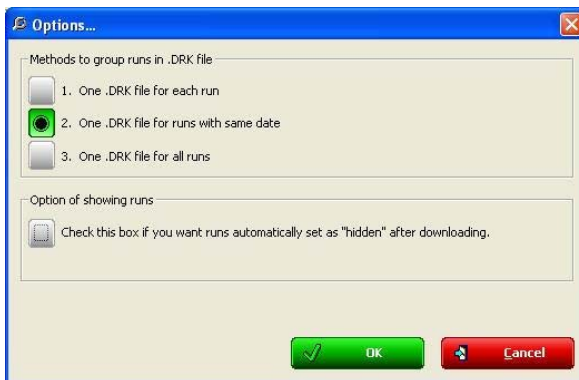


These buttons allow to decide which data to download.

- Pressing “Select all” button all runs stored in the logger memory are downloaded.
- Pressing “Deselect all” no run is downloaded.
- To download only some runs: select them manually in the central table. As shown here below, placing the mouse pointer near to each run the system automatically shows the actual setting of that run. Just change it as needed.



Pressing “Option” button it is possible to decide how to group runs, if showing them or setting them as hidden after download. The figures below show the two options.



In case the choice is to set run as hidden after download it is possible to show them in a second time pressing “Show run marked as hidden” button on the central keyboard of download window.

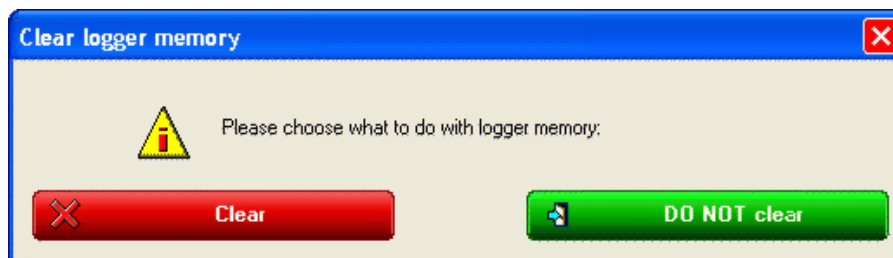
## Bottom keyboard



Bottom buttons manage data download and memory deletion of the logger.

- **“Clear data logger memory”**: deletes the logger memory without downloading data.
- **“Download selected runs, then clear memory”**: downloads selected runs and then deletes the logger memory.
- **“Download selected”**: downloads selected runs and does not clear logger memory.

**Note:** each time an operation involving memory deletion is performed the system asks for confirmation showing the related window.



**“DO NOT clear memory”**: quits data download without performing it nor deleting the logger memory.

When data download is set and data characteristics defined, press the desired download button. Download waiting bar starts showing the download progression and at the end the software comes back to **Race Studio 2** main window.

